Triple finite series relations involving the multivariable Aleph-function

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Abstract

The aim of this document is to establish finite triple series relations for the multivariable Aleph-function. These relations are quite general in nature, from which a large number of new results can be obtained simply by specializing the parameters.

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1. Introduction and preliminaries.

The object of this document is to evaluate four finite triple summations involving the multivariable aleph-function. These function generalize the multivariable I-function recently study by C.K. Sharma and Ahmad [3], itself is an a generalisation of G and H-functions of multiple variables. The multiple Mellin-Barnes integral occuring in this paper will be referred to as the multivariables Aleph-function throughout our present study and will be defined and represented as follows.

$$\begin{aligned} & \text{We have}: \aleph(z_1, \cdots, z_r) = \aleph_{p_i, q_i, \tau_i; R: p_{i^{(1)}}, q_{i^{(1)}}, \tau_{i^{(1)}}; R^{(1)}; \cdots; p_{i^{(r)}}, q_{i^{(r)}}; \tau_{i^{(r)}}; R^{(r)} \\ & \vdots \\ & \vdots \\ & z_r \end{aligned}$$

$$[(\mathbf{a}_j; \alpha_j^{(1)}, \cdots, \alpha_j^{(r)})_{1,\mathfrak{n}}] \ \, , [\tau_i(a_{ji}; \alpha_{ji}^{(1)}, \cdots, \alpha_{ji}^{(r)})_{\mathfrak{n}+1, p_i}] : \\ & \vdots \\ & \vdots \\ & [\tau_i(b_{ji}; \beta_{ij}^{(1)}, \cdots, \beta_{ji}^{(r)})_{m+1, q_i}] : \end{aligned}$$

$$\begin{array}{l} [(c_{j}^{(1)}),\gamma_{j}^{(1)})_{1,n_{1}}], [\tau_{i^{(1)}}(c_{ji^{(1)}}^{(1)},\gamma_{ji^{(1)}}^{(1)})_{n_{1}+1,p_{i}^{(1)}}];\cdots;\;;[(c_{j}^{(r)}),\gamma_{j}^{(r)})_{1,n_{r}}], [\tau_{i^{(r)}}(c_{ji^{(r)}}^{(r)},\gamma_{ji^{(r)}}^{(r)})_{n_{r}+1,p_{i}^{(r)}}]\\ [(d_{j}^{(1)}),\delta_{j}^{(1)})_{1,m_{1}}], [\tau_{i^{(1)}}(d_{ji^{(1)}}^{(1)},\delta_{ji^{(1)}}^{(1)})_{m_{1}+1,q_{i}^{(1)}}];\cdots;;[(d_{j}^{(r)}),\delta_{j}^{(r)})_{1,m_{r}}], [\tau_{i^{(r)}}(d_{ji^{(r)}}^{(r)},\delta_{ji^{(r)}}^{(r)})_{m_{r}+1,q_{i}^{(r)}}] \end{array} \right)$$

$$= \frac{1}{(2\pi\omega)^r} \int_{L_1} \cdots \int_{L_r} \psi(s_1, \cdots, s_r) \prod_{k=1}^r \theta_k(s_k) z_k^{s_k} ds_1 \cdots ds_r$$

$$\tag{1.1}$$

with
$$\omega = \sqrt{-1}$$

For more details, see Ayant [1].

The reals numbers au_i are positives for $i=1,\cdots,R$, $au_{i^{(k)}}$ are positives for $i^{(k)}=1,\cdots,R^{(k)}$

The condition for absolute convergence of multiple Mellin-Barnes type contour (1.9) can be obtained by extension of the corresponding conditions for multivariable H-function given by as:

$$|argz_k|<rac{1}{2}A_i^{(k)}\pi$$
 , where

$$A_i^{(k)} = \sum_{j=1}^{\mathfrak{n}} \alpha_j^{(k)} - \tau_i \sum_{j=\mathfrak{n}+1}^{p_i} \alpha_{ji}^{(k)} - \tau_i \sum_{j=1}^{q_i} \beta_{ji}^{(k)} + \sum_{j=1}^{n_k} \gamma_j^{(k)} - \tau_{i^{(k)}} \sum_{j=n_k+1}^{p_{i^{(k)}}} \gamma_{ji^{(k)}}^{(k)}$$

$$+\sum_{j=1}^{m_k} \delta_j^{(k)} - \tau_{i^{(k)}} \sum_{j=m_k+1}^{q_{i^{(k)}}} \delta_{ji^{(k)}}^{(k)} > 0, \text{ with } k = 1 \cdots, r, i = 1, \cdots, R, i^{(k)} = 1, \cdots, R^{(k)}$$

$$(1.2)$$

The complex numbers z_i are not zero. Throughout this document, we assume the existence and absolute convergence conditions of the multivariable Aleph-function. The numbers. We may establish the the asymptotic expansion in the following convenient form:

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$$\aleph(z_1, \dots, z_r) = 0(|z_1|^{\alpha_1} \dots |z_r|^{\alpha_r}), max(|z_1| \dots |z_r|) \to 0$$

$$\aleph(z_1, \dots, z_r) = 0(|z_1|^{\beta_1} \dots |z_r|^{\beta_r}), min(|z_1| \dots |z_r|) \to \infty$$

where, with $k=1,\cdots,r$: $\alpha_k=min[Re(d_j^{(k)}/\delta_j^{(k)})], j=1,\cdots,m_k$ and

$$\beta_k = max[Re((c_j^{(k)} - 1)/\gamma_j^{(k)})], j = 1, \dots, n_k$$

We will use these following notations in this paper

$$U = p_i, q_i, \tau_i; R ; V = m_1, n_1; \cdots; m_r, n_r$$
(1.3)

$$W = p_{i(1)}, q_{i(1)}, \tau_{i(1)}; R^{(1)}, \cdots, p_{i(r)}, q_{i(r)}, \tau_{i(r)}; R^{(r)}$$
(1.4)

$$A = \{(a_j; \alpha_j^{(1)}, \cdots, \alpha_j^{(r)})_{1,n}\}, \{\tau_i(a_{ji}; \alpha_{ji}^{(1)}, \cdots, \alpha_{ji}^{(r)})_{n+1,p_i}\}$$
(1.5)

$$B = \{ \tau_i(b_{ji}; \beta_{ji}^{(1)}, \cdots, \beta_{ji}^{(r)})_{m+1, q_i} \}$$
(1.6)

$$C = \{(c_j^{(1)}; \gamma_j^{(1)})_{1,n_1}\}, \tau_{i^{(1)}}(c_{ji^{(1)}}^{(1)}; \gamma_{ji^{(1)}}^{(1)})_{n_1+1,p_{i^{(1)}}}\}, \dots, \{(c_j^{(r)}; \gamma_j^{(r)})_{1,n_r}\}, \tau_{i^{(r)}}(c_{ji^{(r)}}^{(r)}; \gamma_{ji^{(r)}}^{(r)})_{n_r+1,p_{i^{(r)}}}\}$$
(1.7)

$$D = \{(d_j^{(1)}; \delta_j^{(1)})_{1,m_1}\}, \tau_{i^{(1)}}(d_{ji^{(1)}}^{(1)}; \delta_{ji^{(1)}}^{(1)})_{m_1+1,q_{i^{(1)}}}\}, \cdots, \{(d_j^{(r)}; \delta_j^{(r)})_{1,m_r}\}, \tau_{i^{(r)}}(d_{ji^{(r)}}^{(r)}; \delta_{ji^{(r)}}^{(r)})_{m_r+1,q_{i^{(r)}}}\}$$
(1.8)

The multivariable Aleph-function write:

$$\aleph(z_1, \dots, z_r) = \aleph_{U:W}^{0, \mathfrak{n}:V} \begin{pmatrix} z_1 \\ \cdot \\ \cdot \\ \cdot \\ z_r \end{pmatrix} A : C$$

$$(1.9)$$

2. Series relations

We have the following four finites sums;

Formula 1

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}}{u!v!t!} \aleph_{p_{i}+5,q_{i}+3,\tau_{i};R:W}^{m,\mathfrak{n}+4:V} \begin{pmatrix} z_{1} \\ \vdots \\ z_{r} \end{pmatrix} \frac{(1-\text{a-v-t };\theta_{1},\cdots,\theta_{r}),}{(1-\text{c-u-v-t };\delta_{1},\cdots,\delta_{r}),}$$

$$(1+d-n+v;\delta_1-\theta_1-\phi_1,\cdots,\delta_r-\theta_r-\phi_r),(1-b-v;\phi_1,\cdots,\phi_r),A:C$$

$$\vdots$$

$$B:D$$

$$= (-)^{m+n+p} \aleph_{p_i+5,q_i+3,\tau_i;R:W}^{m,\mathfrak{n}+4:V} \begin{pmatrix} \mathbf{z}_1 \\ \cdot \\ \cdot \\ \mathbf{z}_r \end{pmatrix} (1-\mathbf{a}-\mathbf{m} \ ; \theta_1,\cdots,\theta_r), \ (1-\mathbf{c}+\mathbf{a}-\mathbf{n}-\mathbf{p} \ ; \delta_1-\theta_1,\cdots,\delta_r-\theta_r), \\ \cdot \\ \cdot \\ \mathbf{z}_r \end{pmatrix} (1-\mathbf{c}-\mathbf{m}-\mathbf{n} \ ; \delta_1,\cdots,\delta_r), \quad (\mathbf{b}-\mathbf{a} \ ; \theta_1-\phi_1,\cdots,\theta_r-\phi_r),$$

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$$(1+d; \delta_1 - \theta_1 - \phi_1, \cdots, \delta_r - \theta_r - \phi_r), (1+b-c-n; \delta_1 - \phi_1, \cdots, \delta_r - \phi_r),$$

$$(d; \delta_1 - \theta_1 - \phi_1, \cdots, \delta_r - \theta_r - \phi_r),$$

$$\ldots,$$

$$(1-b-m-p;\phi_1,\cdots,\phi_r), A:C$$

$$\vdots$$

$$B:D$$
(2.1)

with the validity conditions : δ_i , θ_i , ϕ^i > 0, δ_i > θ_i + ϕ_i ; $i=1,\cdots,r$ and

 $|argz_k|<rac{1}{2}A_i^{(k)}\pi$, where $A_i^{(k)}$ is defined by (1.2) and d=a+b-c

Formula 2

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}(a)_{v+t}}{u!v!t!} \aleph_{p_{i}+5,q_{i}+2,\tau_{i};R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_{1} \\ \vdots \\ z_{r} \end{pmatrix} (1-c+a-u;\delta_{1},\cdots,\delta_{r}),$$

$$\vdots \\ \vdots \\ (1-c-u-v-t;\delta_{1},\cdots,\delta_{r}),$$

$$\begin{pmatrix}
(1+d-n+s); \delta_1 - \phi_1, \cdots, \delta_r - \phi_r), A : C \\
\vdots \\
\vdots \\
\vdots
\end{pmatrix}$$

with the validity conditions : $\delta_i > \phi_i > 0$; $i=1,\cdots,r$ and $|argz_k| < \frac{1}{2}A_i^{(k)}\pi$, where $A_i^{(k)}$ is defined by (1.2) and d=a+b-c

Formula 3

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}(b)_{v}}{u!v!t!} \aleph_{p_{i}+4,q_{i}+3,\tau_{i};R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_{1} \\ \vdots \\ z_{r} \end{pmatrix} \frac{(1-\text{a-v-t};\theta_{1},\cdots,\theta_{r}),}{(1-\text{c-u-v-t}};\delta_{1},\cdots,\delta_{r}),$$

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$$= (-)^{m+n+p}(b)_{m+p} \aleph_{p_i+4,q_i+3,\tau_i;R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_1 \\ \cdot \\ \cdot \\ \cdot \\ z_r \end{pmatrix} (1-a-m;\theta_1,\cdots,\theta_r), \quad (1+b-c-n;\delta_1,\cdots,\delta_r),$$

$$(1-c-m-n-p;\delta_1,\cdots,\delta_r), \quad (b-a;\theta_1,\cdots,\theta_r),$$

$$(1+d; \delta_{1}-\theta_{1}, \cdots, \delta_{r}-\theta_{r}), (1-c+a-n-p; \delta_{1}-\theta_{1}, \cdots, \delta_{r}-\theta_{r}), A:C)$$

$$\vdots$$

$$(d; \delta_{1}-\theta_{1}, \cdots, \delta_{r}-\theta_{r}), B:D,$$

$$(2.3)$$

with the validity conditions : $\delta_i > \theta_i > 0; i=1,\cdots,r$ and $|argz_k| < \frac{1}{2}A_i^{(k)}\pi$, where $A_i^{(k)}$ is defined by (1.2)

Formula 4

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}(c-b)_{v+t}(c-a)_{u}}{(1+a-b-p)_{t}u!v!t!} \aleph_{p_{i}+3,q_{i}+2,\tau_{i};R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_{1} \\ \cdot \\ \cdot \\ z_{r} \end{pmatrix} (1-b-v;\delta_{1},\cdots,\delta_{r}),$$

$$\begin{array}{ccc}
(1-d-m+u;\delta_1,\cdots,\delta_r), & (1-a-v-t;\delta_1,\cdots,\delta_r), & A:C \\
& \ddots & & \\
(1-c-u-v-t;\delta_1,\cdots,\delta_r), & B:D,
\end{array}$$

$$\begin{array}{c}
(1-b-m-p; \delta_1, \cdots, \delta_r), A: C \\
\vdots \\
(1-c-m-n-p; \delta_1, \cdots, \delta_r), B: D
\end{array}$$
(2.4)

with the validity conditions : $\delta_i>0; i=1,\cdots,r$ and $|argz_k|<rac{1}{2}A_i^{(k)}\pi$, where $A_i^{(k)}$ is defined by (1.2)

Proof of (2.1)

Substituting contour integral (1.1) for the Aleph-function of several variables in left-hand side of (2.1), changing the order of summation and integration which is justified as the series involved are finite and using the following result of Paradhan [2,p.33]

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}(a)_{v+t}(c-a)_{u}(c-b)_{u+t}(b)_{v}}{(c)_{u+v+t}(1-d-m)_{u}(1+d-n)_{v}(1+a-b-p)_{v}u!v!t!}$$

$$= \frac{(a)_{m}(c-a)_{n+p}(b)_{m+p}(c-a)_{n}}{(-d)_{n}(b-a)_{p}(d)_{m}(c)_{m+n+p}} \text{ with } d=a+b-c \text{ (not an integer)}$$
(2.5)

Interpreting the result, thus obtained with the help pf (1.1), we get the desired result. To prove (2.2) to (2.4), we use the similar methods to (3.1).

3. Multivariable I-function

If $\tau_i, \tau_{i^{(1)}}, \cdots, \tau_{i^{(r)}} \to 1$, the Aleph-function of several variables degenere to the I-function of several variables. The finite triple sums have been derived in this section for multivariable I-functions defined by Sharma et al [3]. In these section, we note

$$B_{i}^{(k)} = \sum_{j=1}^{\mathfrak{n}} \alpha_{j}^{(k)} - \sum_{j=\mathfrak{n}+1}^{p_{i}} \alpha_{ji}^{(k)} - \sum_{j=1}^{q_{i}} \beta_{ji}^{(k)} + \sum_{j=1}^{n_{k}} \gamma_{j}^{(k)} - \sum_{j=n_{k}+1}^{p_{i}(k)} \gamma_{ji}^{(k)} + \sum_{j=1}^{n_{k}} \delta_{j}^{(k)} - \sum_{j=m_{k}+1}^{q_{i}(k)} \delta_{ji}^{(k)} > 0, \text{ with } k = 1 \cdots, r, i = 1, \cdots, R, i^{(k)} = 1, \cdots, R^{(k)}$$

$$(3.1)$$

Formula 1

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}}{u!v!t!} I_{p_{i}+5,q_{i}+3;R:W}^{m,\mathfrak{n}+4:V} \begin{pmatrix} z_{1} \\ \vdots \\ z_{r} \end{pmatrix} (1-\text{a-v-t };\theta_{1},\cdots,\theta_{r}),$$

$$\vdots \\ \vdots \\ (1-\text{c-u-v-t };\delta_{1},\cdots,\delta_{r}),$$

$$(1-c+a-u;\delta_1-\theta_1,\cdots,\delta_r-\theta_r), \qquad (1-c+b-u-t;\delta_1-\phi_1,\cdots,\delta_r-\phi_r),$$

$$...$$

$$(d+m-u;\delta_1-\phi_1-\theta_1,\cdots,\delta_r-\phi_r-\theta_r), (b+p-a-t;\theta_1-\phi_1,\cdots,\theta_r-\phi_r),$$

$$(1+d-n+v;\delta_1-\theta_1-\phi_1,\cdots,\delta_r-\theta_r-\phi_r),(1-b-v;\phi_1,\cdots,\phi_r),A:C$$

$$\vdots$$

$$B:D$$

$$(1+d; \delta_1 - \theta_1 - \phi_1, \cdots, \delta_r - \theta_r - \phi_r), (1+b-c-n; \delta_1 - \phi_1, \cdots, \delta_r - \phi_r),$$

$$(d; \delta_1 - \theta_1 - \phi_1, \cdots, \delta_r - \theta_r - \phi_r),$$

$$\ldots,$$

$$\begin{array}{c}
(1-b-m-p;\phi_1,\cdots,\phi_r), A:C \\
\vdots \\
B:D
\end{array}$$
(3.2)

with the validity conditions : δ_i , θ_i , $\phi_i > 0$, $\delta_i > \theta_i + \phi_i$; $i = 1, \dots, r$ and

Formula 2

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}(a)_{v+t}}{u!v!t!} I_{p_{i}+5,q_{i}+2;R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_{1} \\ \vdots \\ z_{r} \end{pmatrix} (1-c+a-u;\delta_{1},\cdots,\delta_{r}),$$

$$(1-b-v;\phi_1,\cdots,\phi_r), \qquad (1-c+b-u-t;\delta_1-\phi_1,\cdots,\delta_r-\phi_r), \\ (1-b-v;\phi_1,\cdots,\phi_r), \\ \vdots \\ (d+m-u;\delta_1-\phi_1,\cdots,\delta_r-\phi_r), \qquad B:D,$$

$$\begin{pmatrix}
(1+d-n+s); \delta_1 - \phi_1, \cdots, \delta_r - \phi_r), A : C \\
\vdots \\
\vdots \\
\vdots
\end{pmatrix}$$

$$= (-)^{m+n+p} I_{p_i+5,q_i+3;R:W}^{m,\mathfrak{n}+4:V} \begin{pmatrix} z_1 \\ \cdot \\ \cdot \\ \cdot \\ z_r \end{pmatrix} (1-\text{a-m} ; \theta_1,\theta_2), (1-\text{c+a-n-p} ; \delta_1-\theta_1,\delta_2-\theta_2), \\ \vdots \\ (1-\text{c-m-n} ; \delta_1,\delta_2), (b-\text{a} ; \theta_1-\phi_1,\theta_2-\phi_2),$$

$$\begin{array}{ccc}
(1+d; \delta_{1}-\theta_{1}-\phi_{1}, \cdots, \delta_{r}-\theta_{r}-\phi_{r}), & (1+b-c-n; \delta_{1}-\phi_{1}, \cdots, \delta_{r}-\phi_{r}), A:C \\
& \ddots & \vdots \\
(d; \delta_{1}-\theta_{1}-\phi_{1}, \cdots, \delta_{r}-\theta_{r}-\phi_{r}), & B:D
\end{array}$$
(3.3)

with the validity conditions : $\delta_i > \phi_i > 0$; $i=1,\cdots,r$ and $|argz_k| < \frac{1}{2}B_i^{(k)}\pi$, where $B_i^{(k)}$ is defined by (3.1) and d=a+b-c

Formula 3

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}(b)_{v}}{u!v!t!} I_{p_{i}+4,q_{i}+3;R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_{1} \\ \vdots \\ z_{r} \end{pmatrix} (1-\text{a-v-t};\theta_{1},\cdots,\theta_{r}),$$

$$\vdots \\ \vdots \\ z_{r} \end{pmatrix} (1-\text{a-v-t};\theta_{1},\cdots,\theta_{r}),$$

$$= (-)^{m+n+p}(b)_{m+p} I_{p_i+4,q_i+3;R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} \mathbf{z}_1 \\ \vdots \\ \mathbf{z}_r \end{pmatrix} (1-\mathbf{a}-\mathbf{m};\theta_1,\cdots,\theta_r), \quad (1+\mathbf{b}-\mathbf{c}-\mathbf{n}\;;\delta_1,\cdots,\delta_r), \\ \vdots \\ \mathbf{z}_r \end{pmatrix} (1-\mathbf{c}-\mathbf{m}-\mathbf{n}-\mathbf{p}\;;\delta_1,\cdots,\delta_r), \quad (\mathbf{b}-\mathbf{a}\;;\theta_1,\cdots,\theta_r),$$

$$(1+d; \delta_{1}-\theta_{1}, \cdots, \delta_{r}-\theta_{r}), (1-c+a-n-p; \delta_{1}-\theta_{1}, \cdots, \delta_{r}-\theta_{r}), A:C$$

$$\vdots \qquad \vdots \qquad \vdots \qquad \vdots$$

$$(d; \delta_{1}-\theta_{1}, \cdots, \delta_{r}-\theta_{r}), \qquad B:D,$$

$$(3.4)$$

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with the validity conditions : $\delta_i > \theta_i > 0$; $i = 1, \dots, r$ and $|argz_k| < \frac{1}{2}B_i^{(k)}\pi$, where $B_i^{(k)}$ is defined by (3.1)

Formula 4

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}(c-b)_{v+t}(c-a)_{u}}{(1+a-b-p)_{t}u!v!t!} I_{p_{i}+3,q_{i}+2;R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_{1} \\ \cdot \\ \cdot \\ \cdot \\ z_{r} \end{pmatrix} (1-b-v;\delta_{1},\cdots,\delta_{r}),$$

$$\begin{array}{ccc}
(1-d-m+u; \delta_1, \cdots, \delta_r), (1-a-v-t; \delta_1, \cdots, \delta_r), A:C \\
& \cdot \cdot \cdot \\
(1-c-u-v-t; \delta_1, \cdots, \delta_r), & B:D,
\end{array}$$

$$= (-)^{m+n} \frac{(c-a)_{n+p}(c-b)_n}{(b-a)_p} I_{p_i+3,q_i+2;R:W}^{m,n+3:V} \begin{pmatrix} z_1 \\ \cdot \\ \cdot \\ z_r \end{pmatrix} (1-a-m; \delta_1, \dots, \delta_r), (1+d; \delta_1, \dots, \delta_r),$$

$$(-d; \delta_1, \dots, \delta_r), \qquad \dots,$$

$$\begin{array}{c}
(1-b-m-p; \delta_1, \cdots, \delta_r), A: C \\
 & \cdots \\
(1-c-m-n-p; \delta_1, \cdots, \delta_r), B: D
\end{array}$$
(3.5)

with the validity conditions : $\delta_i>0; i=1,\cdots,r$ and $|argz_k|<rac{1}{2}B_i^{(k)}\pi$, where $B_i^{(k)}$ is defined by (3.1)

4. Aleph-function of two variables

If r = 2, we obtain the Aleph-function of two variables defined by K.Sharma [5], and we have the following relations.

Formula 1

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}}{u!v!t!} \aleph_{p_{i}+5,q_{i}+3,\tau_{i};R:W}^{m,\mathfrak{n}+4:V} \begin{pmatrix} z_{1} \\ \vdots \\ z_{2} \end{pmatrix} (1-\text{a-v-t };\theta_{1},\theta_{2}),$$

$$\vdots \\ (1-\text{c-u-v-t };\delta_{1},\delta_{2}),$$

$$\begin{array}{c}
(1+d-n+v;\delta_1-\theta_1-\phi_1,\delta_2-\theta_2-\phi_2), (1-b-v;\phi_1,\phi_2), A:C \\
& \cdot \cdot \cdot \\
B:D
\end{array}$$

$$= (-)^{m+n+p} \aleph_{p_i+5,q_i+3,\tau_i;R:W}^{m,\mathfrak{n}+4:V} \begin{pmatrix} z_1 \\ \cdot \\ \cdot \\ z_2 \end{pmatrix} (1-\text{a-m };\theta_1,\theta_2), \ (1-\text{c+a-n-p };\delta_1-\theta_1,\delta_2-\theta_2), \\ \cdot \cdot \cdot \\ (1-\text{c-m-n };\delta_1,\delta_2), \quad (\text{b-a };\theta_1-\phi_1,\theta_2-\phi_2), \end{pmatrix}$$

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$$\begin{array}{c}
(1+d; \delta_{1}-\theta_{1}-\phi_{1}, \delta_{2}-\theta_{2}-\phi_{2}), (1+b-c-n; \delta_{1}-\phi_{1}, \delta_{2}-\phi_{2}), (1-b-m-p; \phi_{1}, \phi_{2}), A:C \\
& \cdot \cdot \cdot \\
(d; \delta_{1}-\theta_{1}-\phi_{1}, \delta_{2}-\theta_{2}-\phi_{2}), & \cdot \cdot \cdot , & B:D
\end{array}$$
(4.1)

with the validity conditions : $\delta_i, \theta_i, \phi_i > 0, \delta_i > \theta_i + \phi_i; i=1,2$ and $|argz_k| < \frac{1}{2}A_i^{(k)}\pi$, where $A_i^{(k)}$ is defined by (1.2) and d=a+b-c

Formula 2

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}(a)_{v+t}}{u!v!t!} \aleph_{p_{i}+5,q_{i}+2,\tau_{i};R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} \mathbf{z}_{1} \\ \cdot \\ \cdot \\ \mathbf{z}_{2} \end{pmatrix} (1-\mathbf{c}+\mathbf{a}-\mathbf{u};\delta_{1},\delta_{2}),$$

$$(1+d-n+s; \delta_1 - \phi_1, \delta_2 - \phi_2), A: C$$

$$(1+d ; \delta_{1} - \phi_{1}, \delta_{2} - \phi_{2}), (1+a-b ; \phi_{1}, \phi_{2}), (1+b-n-c ; \delta_{1} - \phi_{1}, \delta_{2} - \phi_{2}), A : C$$

$$\vdots \qquad \vdots \qquad \vdots \qquad \vdots \qquad \vdots$$

$$B : D, \qquad \vdots \qquad \vdots \qquad \vdots$$

$$(4.2)$$

with the validity conditions : $\delta_i>\phi_i>0; i=1,2$ and $|argz_k|<\frac{1}{2}A_i^{(k)}\pi$, where $A_i^{(k)}$ is defined by (1.2) and d=a+b-c

Formula 3

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}(b)_{v}}{u!v!t!} \aleph_{p_{i}+4,q_{i}+3,\tau_{i};R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} \mathbf{z}_{1} \\ \cdot \\ \cdot \\ \mathbf{z}_{2} \end{pmatrix} (1-\text{a-v-t};\theta_{1},\theta_{2}),$$

$$(1-\text{c-u-v-t}};\delta_{1},\delta_{2}),$$

$$(1+d ; \delta_{1} - \theta_{1}, \delta_{2} - \theta_{2}), (1-c+a-n-p; \delta_{1} - \theta_{1}, \delta_{2} - \theta_{2}), A : C)$$

$$\vdots \qquad \vdots \qquad \vdots \qquad \vdots$$

$$(d; \delta_{1} - \theta_{1}, \delta_{2} - \theta_{2}), \qquad B : D,$$

$$(4.3)$$

with the validity conditions : $\delta_i>\theta_i>0; i=1,2$ and $|argz_k|<rac{1}{2}A_i^{(k)}\pi$, where $A_i^{(k)}$ is defined by (1.2)

Formula 4

$$(1-d-m+u;\delta_1,\delta_2),(1-a-v-t;\delta_1,\delta_2),A:C$$

$$\vdots$$

$$(1-c-u-v-t;\delta_1,\delta_2),\qquad B:D,$$

$$= (-)^{m+n} \frac{(c-a)_{n+p}(c-b)_n}{(b-a)_p} \aleph_{p_i+3,q_i+2,\tau_i;R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_1 \\ \vdots \\ z_r \end{pmatrix} (1-\text{a-m };\delta_1,\delta_2), (1+\text{d };\delta_1,\delta_2), \\ \vdots \\ \vdots \\ z_r \end{pmatrix} (-\text{d };\delta_1,\delta_2), (1+\text{d };\delta_1,\delta_2),$$

(1-b-m-p;
$$\delta_1, \delta_2$$
), $A:C$
...
(1-c-m-n-p; δ_1, δ_2), $B:D$
(4.4)

with the validity conditions : $\delta_i>0; i=1,2$ and $|argz_k|<rac{1}{2}A_i^{(k)}\pi$, where $A_i^{(k)}$ is defined by (1.2)

5. I-function of two variables

If $\tau_i, \tau_{i'}, \tau_{i''} \to 1$, then the Aleph-function of two variables degenere in the I-function of two variables defined by sharma et al [4] and we obtain

Formula 1

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}}{u!v!t!} I_{p_{i}+5,q_{i}+3;R:W}^{m,\mathfrak{n}+4:V} \begin{pmatrix} z_{1} \\ \vdots \\ z_{2} \end{pmatrix} (1-\text{a-v-t };\theta_{1},\theta_{2}),$$

$$\vdots \\ (1-\text{c-u-v-t };\delta_{1},\delta_{2}),$$

(1-c+a-u;
$$\delta_1 - \theta_1, \delta_2 - \theta_2$$
), (1-c+b-u-t; $\delta_1 - \phi_1, \delta_2 - \phi_2$),
...
(d+m-u; $\delta_1 - \phi_1 - \theta_1, \delta_2 - \phi_2 - \theta_2$), (b+p-a-t; $\theta_1 - \phi_1, \theta_2 - \phi_2$),

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$$(1+d-n+v;\delta_{1}-\theta_{1}-\phi_{1},\delta_{2}-\theta_{2}-\phi_{2}),(1-b-v;\phi_{1},\phi_{2}),A:C$$

$$\vdots$$

$$B:D$$

$$= (-)^{m+n+p} I_{p_i+5,q_i+3;R:W}^{m,\mathfrak{n}+4:V} \begin{pmatrix} z_1 \\ \cdot \\ \cdot \\ z_2 \end{pmatrix} (1-\text{a-m} ; \theta_1,\theta_2), \ (1-\text{c+a-n-p} ; \delta_1-\theta_1,\delta_2-\theta_2), \\ \vdots \\ (1-\text{c-m-n} ; \delta_1,\delta_2), \quad (\text{b-a} ; \theta_1-\phi_1,\theta_2-\phi_2),$$

$$\begin{array}{c}
(1+d; \delta_{1}-\theta_{1}-\phi_{1}, \delta_{2}-\theta_{2}-\phi_{2}), (1+b-c-n; \delta_{1}-\phi_{1}, \delta_{2}-\phi_{2}), (1-b-m-p; \phi_{1}, \phi_{2}), A:C \\
\vdots \\
(d; \delta_{1}-\theta_{1}-\phi_{1}, \delta_{2}-\theta_{2}-\phi_{2}), & \vdots \\
B:D
\end{array}$$
(5.1)

with the validity conditions : $\delta_i, \theta_i, \phi_i > 0, \delta_i > \theta_i + \phi_i; i = 1, 2$ and $|argz_k| < \frac{1}{2}B_i^{(k)}\pi$, where $B_i^{(k)}$ is defined by (3.1) and d = a + b - c

Formula 2

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}(a)_{v+t}}{u!v!t!} I_{p_{i}+5,q_{i}+2;R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_{1} \\ \vdots \\ z_{2} \end{pmatrix} (1-c+a-u;\delta_{1},\delta_{2}),$$

$$\vdots$$

$$(1-c-u-v-t;\delta_{1},\delta_{2}),$$

$$(1+d-n+s; \delta_1 - \phi_1, \delta_2 - \phi_2), A: C$$

$$= (-)^{m+n+p}(a)_m I_{p_i+5,q_i+2;R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_1 \\ \cdot \\ \cdot \\ z_2 \end{pmatrix} (1-c+a-n-p;\delta_1,\delta_2), (1+d;\delta_1-\phi_1,\delta_2-\phi_2), \\ \vdots \\ (1-c-m-n-p;\delta_1,\delta_2), \qquad B:D,$$

with the validity conditions : $\delta_i > \phi_i > 0$; i=1,2 and $|argz_k| < \frac{1}{2}B_i^{(k)}\pi$, where $B_i^{(k)}$ is defined by (3.1) and d=a+b-c

Formula 3

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}(b)_{v}}{u!v!t!} I_{p_{i}+4,q_{i}+3;R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_{1} \\ \vdots \\ z_{2} \end{pmatrix} (1-\text{a-v-t};\theta_{1},\theta_{2}),$$

$$\vdots \\ (1-\text{c-u-v-t};\delta_{1},\delta_{2}),$$

$$= (-)^{m+n+p}(b)_{m+p} I_{p_i+4,q_i+3;R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_1 \\ \cdot \\ \cdot \\ z_2 \end{pmatrix} (1-a-m;\theta_1,\theta_2), \quad (1+b-c-n;\delta_1,\delta_2),$$

$$(1-c-m-n-p;\delta_1,\delta_2), \quad (b-a;\theta_1,\theta_2),$$

with the validity conditions : $\delta_i>\theta_i>0; i=1,2$ and $|argz_k|<rac{1}{2}B_i^{(k)}\pi$, where $B_i^{(k)}$ is defined by (3.1)

Formula 4

$$\sum_{u=0}^{m} \sum_{v=0}^{n} \sum_{t=0}^{p} \frac{(-m)_{u}(-n)_{v}(-p)_{t}(c-b)_{v+t}(c-a)_{u}}{(1+a-b-p)_{t}u!v!t!} I_{p_{i}+3,q_{i}+2;R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_{1} \\ \vdots \\ z_{2} \end{pmatrix} (1-b-v;\delta_{1},\delta_{2}),$$

$$= (-)^{m+n} \frac{(c-a)_{n+p}(c-b)_n}{(b-a)_p} I_{p_i+3,q_i+2;R:W}^{m,\mathfrak{n}+3:V} \begin{pmatrix} z_1 \\ \vdots \\ z_r \end{pmatrix} (1-\text{a-m };\delta_1,\delta_2), (1+\text{d };\delta_1,\delta_2), \\ \vdots \\ (-\text{d };\delta_1,\delta_2), \ldots,$$

(1-b-m-p;
$$\delta_1, \delta_2$$
), $A: C$
...
(1-c-m-n-p; δ_1, δ_2), $B: D$ (5.4)

with the validity conditions : $\delta_i>0; i=1,2$ and $|argz_k|<rac{1}{2}B_i^{(k)}\pi$, where $B_i^{(k)}$ is defined by (3.1)

6. Conclusion

The aleph-function of several variables presented in this paper, is quite basic in nature. Therefore, on specializing the parameters of this function, we may obtain various other special functions o several variables such as multivariable I-function, multivariable Fox's H-function, Fox's H-function, Meijer's G-function, Wright's generalized Bessel function, Wright's generalized hypergeometric function, MacRobert's E-function, generalized hypergeometric function, Bessel function of first kind, modied Bessel function, Whittaker function, exponential function, binomial function etc. as its special cases, and therefore, various unified integral presentations can be obtained as special cases of our results.

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