# Evolution of geometric properties on solution curve of KdV equation 

Ling $\mathrm{XU}^{\# 1}$<br>\# Collage of Sciences of Jiangsu University<br>China ,Jiangsu ,Zhenjiang


#### Abstract

This paper discusses some properties of solution curve of the Cauchy problem on the KdV equation by Lagrange coordinate, obtained the evolution consequence of monotonicity, concavity and the isolated extreme points. Namely under the enough smooth condition, the isolated extreme points, monotonicity and convexity of initial solution can be inherited to the solution curve at any $t>0$.


Keywords: KdV equation ; solution curve ; monotonicity ; convexity ; isolated extreme point.

## Introduction

No matter in mathematical theories or application field ,the KdV equation is a very important equation. This equations are used to describe the shallow water wave phenomenon with small amplitude in physical systems.The background of the equation goes back to the concept of solitary wave is put forward .Solitary wave was first found by Russell in 1834 . Until 1895,Korteweg and de Vries researched the Shallow water wave and established a one-dimensional mathematical model under the assumption of small amplitude and the long wave approximation.The equation they established is $\eta_{t}+6 \eta \eta_{x}+\eta_{x x x}=0$, which is called the KdV equation.

Many important results on KdV equation had be obtained. In 1983, Kato proved that the $\left\{\begin{array}{l}\partial_{t} u+\partial_{x}^{3} u+u \partial_{x} u=0, x, t \in R \\ u(x, 0)=\varphi\end{array}\right.$ have only one solution $u \in C\left(I T ; H^{s}\right) \cap C^{1}\left(I T ; H^{s-3}\right)$ which was only decided by $|\varphi|_{1}\left(| |_{s}\right.$ means $H^{s}$-norm $)$ with $I T \equiv[0, T], T>0$ in $[1]$.

Suppose $A(r)$ is a Fréchet space if for some $r_{0}>0, \varphi \in A\left(r_{0}\right)$, there is a $r_{1}>0$ and the solution of problem $u \in C\left(I T ; A\left(r_{1}\right)\right)$ in [2].

In 1970 ,Anders founded the KdV equation $u_{t}=u u_{x}+\delta u_{x x x}$ has only one solution if $f(x)$ is a period function with the period 1 and $f_{x x x}(x) \in L_{2}$, where $\delta \neq 0, u(x, t)=u(x+1, t)$ and $u(x, 0)=f(x)$ in [3].

In 1991,Kenig,Ponce and Vega proved that the $\left\{\begin{array}{l}\partial_{t} u+\partial_{x}^{3} u+u \partial_{x} u=0, x, t \in R \\ u(x, 0)=u_{0}(x)\end{array}\right.$ is local well-posed in $C\left([-T, T]: H^{s}(R)\right)$ when $s>-\frac{3}{4}$ in[4].

For the high order KdV equation and the discrete KdV equation , researchers also get many results . Readers refer to see[5],[7] and [8]and those references within.

In 2011,Hannah, Himonas and Petronilho studied the regularity of period gKdV equation during the Gevrey space and the corresponding results are obtained, the norm of $G^{\delta, s}$ is defined by $\left\|u_{0}\right\|_{G^{\sigma, s}}^{2}=\int(1+|\xi|)^{2 s} e^{2 \sigma(1+|\xi|)}\left|\hat{u}_{0}(\xi)\right|^{2} d \xi$ in [9].

On the other hand, by studying the relationship between the point on the curve and the time variable, we can obtain the evolution process of the solution curve or the solution surface with time. It is meaningful to understand the equations and its related problems.

Gage proved that each level curve of evolution equation like $X_{t}(t, \varphi)=k(t, \varphi) N(t, \varphi)$ converges to a circle before disappearing in[10].

Marcos and Ralph studied the curvature equation,which is given by $\frac{\partial u}{\partial t}=\frac{\frac{\partial^{2} u}{\partial x^{2}}\left(\frac{\partial u}{\partial y}\right)^{2}-2 \frac{\partial^{2} u}{\partial x \partial y} \frac{\partial u}{\partial x} \frac{\partial u}{\partial y}+\frac{\partial^{2} u}{\partial y^{2}}\left(\frac{\partial u}{\partial x}\right)^{2}}{\left(\frac{\partial u}{\partial x}\right)^{2}+\left(\frac{\partial u}{\partial y}\right)^{2}}$.

The initial curve $u(x, y, 0)$ has a local isolated extremum $\left(\mathrm{x}_{\mathrm{m}}, \mathrm{y}_{\mathrm{m}}\right)$ and assume that the level curves near the extremum are closed and convex, then the solution $u(x, y, t)$ admits a local extremum $\left(x_{m}(t), y_{m}(t)\right)$ close to $\left(\mathrm{x}_{\mathrm{m}}, \mathrm{y}_{\mathrm{m}}\right)$ for any small $\mathrm{t}>0$ in [11].

In this paper, we will study the following problem :

$$
\left\{\begin{array}{l}
u_{t}+u u_{x}+u_{x x x}=0  \tag{1.1}\\
u(x, 0)=u_{0}(x)
\end{array}\right.
$$

where ( $\mathrm{x}, \mathrm{y}$ ) are the space variables and t the time variable. We will investigate the process of evolution of monotonicity, isolated extreme point and concavity of the solution curve. This discussion will be helpful for solving practical problem

In order to the accuracy and convenience, we first review the following concepts .
Definition 1.1.The $x_{0}$ is called maximum point(minimum point) of $f$ if $\forall x \in U^{\circ}\left(x_{0}, h\right) \subset I$,

$$
f(x)<f\left(x_{0}\right) \quad \text { (or } f(x)>f\left(x_{0}\right) \text {, where } I \text { is the domain interval of function } f .
$$

Definition 1.2.The $U$ is called the monotone increasing interval of $f(x)$ if $\forall x_{1}, x_{2} \in U$,

$$
x_{1}<x_{2}, \text { then } f\left(x_{1}\right)<f\left(x_{2}\right)
$$

Definition1.3.The function $f$ is called convex function if $\forall x_{1}, x_{2} \in I, \lambda \in(0,1)$

$$
\begin{equation*}
f\left(\lambda x_{1}+(1-\lambda) x_{2}\right)<\lambda f\left(x_{1}\right)+(1-\lambda) f\left(x_{2}\right) \tag{1}
\end{equation*}
$$

Conversely the function $f$ is called concave function if $\forall x_{1}, x_{2} \in I, \lambda \in(0,1)$

$$
\begin{equation*}
f\left(\lambda x_{1}+(1-\lambda) x_{2}\right)>\lambda f\left(x_{1}\right)+(1-\lambda) f\left(x_{2}\right) \tag{2}
\end{equation*}
$$

where $I$ is the interval of function $f$.

In the next, we will prove that under the assumption of sufficient smooth, the isolated extreme point,local monotonicity and local concavity of initial solution curve could be inherited at any $\mathrm{t}>0$.

## Theorem and proving

First, introduce following lemmas:
Lemma 2.1[12] $\left\{\begin{array}{l}u_{t}+u^{k} u_{x}+u_{x x x}=0, t \in R, x \in R, k \in N \\ u(0)=\varphi\end{array}, u \in H^{s}(R)\right.$ is global well-posed when $s \geq 1$,
$k=1,2,3$.

Lemma 2.2.Assume $u_{0} \in H^{4}(R)$, if $u(x, t)$ is the solution of (1.1), then for any $t>0,\|u(x, t)\|_{H^{4}}$ is bounded .

Proof. Do product on the left of the first equation of $(1.1)$ by $u, u_{x x}, u_{x^{4}}, u_{x^{6}}$ and $u_{x^{8}}$ respectively, then integrate them, we obtain

$$
\begin{align*}
& \frac{1}{2} \frac{d}{d t}\|u\|_{H^{4}}^{2}=\int_{R}\left(u u_{x} u_{x x}-u u_{x} u_{x^{4}}+3 u_{x} u_{x x} u_{x^{4}}+u u_{x x x} u_{x^{4}}-10 u_{x x} u_{x x x} u_{x^{4}}-\frac{7}{2} u_{x} u_{x^{4}}^{2}\right) d x \\
& \frac{d}{d t}\|u\|_{H^{4}}^{2} \leq C \int_{R}\left|u u_{x} u_{x x}\right|+\left|u u_{x} u_{x^{4}}\right|+\left|u_{x} u_{x x} u_{x^{4}}\right|+\left|u u_{x x x} u_{x^{4}}\right|+\left|u_{x x} u_{x x x} u_{x^{4}}\right|+\left|u_{x} u_{x^{4}}^{2}\right| d x \\
& \|u\|_{H^{4}}^{2} \geq \max _{0 \leq i \leq 4,0 \leq j \leq 4, i, j \in z}\left\{\left\|u_{x^{i}}\right\|\left\|u_{x^{j}}\right\|\right. \\
& \frac{d}{d t}\|u\|_{H^{4}}^{2} \leq C\|u\|_{H^{4}}^{4} \\
& \|u(x, t)\|_{H^{4}}^{2} \leq \frac{\|u(x, 0)\|_{H^{4}}^{2}}{1-C\|u(x, 0)\|_{H^{4}}^{2} t} \quad C \geq 20  \tag{5}\\
& \text { Let } t_{1}=\frac{1}{2 C\|u(x, 0)\|_{H^{4}}^{2}, \text { then }} \\
& \|u(x, t)\|_{H^{4}}^{2} \leq 2\|u(x, 0)\|_{H^{4}}^{2} \\
& \exists t_{1}, 0<t \leq t_{1},\|u(x, t)\|_{H^{4}}<+\infty
\end{align*}
$$

When $t>t_{1}$, use $t_{1}$ replace $t=0$, so we have
$\|u(x, t)\|_{H^{4}}^{2} \leq \frac{\left\|u\left(x, t_{1}\right)\right\|_{H^{4}}^{2}}{1-C\left\|u\left(x, t_{1}\right)\right\|_{H^{4}}^{2}\left(t-t_{1}\right)}$
Let $t-t_{1}=\frac{1}{2 C\left\|u\left(x, t_{1}\right)\right\|_{H^{4}}^{2}}$, so $\|u(x, t)\|_{H^{4}}^{2} \leq 2\left\|u\left(x, t_{1}\right)\right\|_{H^{4}}^{2}$.
Let $t_{2}=\frac{1}{2 C\left\|u\left(x, t_{1}\right)\right\|_{H^{4}}^{2}}+t_{1}$, then $\|u(x, t)\|_{H^{4}}<+\infty$ for all $t_{1}<t<t_{2}$.
Repeat the steps above, we find there always have

$$
\begin{aligned}
& \|u(x, t)\|_{H^{4}}^{2} \leq \frac{\left\|u\left(x, t_{n}\right)\right\|_{H^{4}}^{2}}{1-C\left\|u\left(x, t_{n}\right)\right\|_{H^{4}}^{2}\left(t-t_{n}\right)}, \\
& t-t_{n}=\frac{1}{2 C\left\|u\left(x, t_{n}\right)\right\|_{H^{4}}^{2}}, t_{n+1}=\frac{1}{2 C\left\|u\left(x, t_{n}\right)\right\|_{H^{4}}^{2}}+t_{n} .
\end{aligned}
$$

For all $t_{n}<t<t_{n+1},\|u(x, t)\|_{H^{4}}^{2} \leq 2\left\|u\left(x, t_{n}\right)\right\|_{H^{4}}^{2}$, that means $\|u(x, t)\|_{H^{4}}<+\infty$.
So for any $t_{n}, \exists \Delta t_{n}$, when $t \in U\left(t_{n}, \Delta t_{n}\right),\|u(x, t)\|_{H^{4}}<+\infty$ if $u_{0}(x) \in H^{4}(R)$.
We denote

$$
\begin{equation*}
w(u, y, x, z, t)=u_{y y y}(\lambda(y(x, t)+y(z, t)), t)-\lambda(u(y(x, t), t)-u(y(z, t), t)) \tag{7}
\end{equation*}
$$

If $u_{0} \in H^{4}(R)$, then $w(u, y, x, z, t)$ is bounded.
In order to explain and understand the process of evolution of curve of KdV equation , we will use Lagrange coordinates

$$
\left\{\begin{array}{l}
y_{t}(x, t)=u[t, y(x, t)]  \tag{8}\\
y(0, x)=x
\end{array}\right.
$$

Lemma $2.3 y\left(x_{1}, t\right)>y\left(x_{2}, t\right)$ for any $\boldsymbol{t}>\mathbf{0}$ if $x_{1}>x_{2} \in R$.
Proof. Because $y_{t}(x, t)=u(t, y(x, t))$

$$
\begin{aligned}
& y_{t x}(x, t)=u_{x}(y(x, t), t) \frac{d y}{d x}, \text { so }\left(\frac{d y}{d x}\right)_{t}=u_{x}(t, y(x, t)) \frac{d y}{d x} \\
& y_{x}=e^{\int_{0}^{t} u_{x}(\tau, y(x, \tau)) d \tau}, \quad y_{x}>0 \text {. Therefore }, \quad y\left(x_{1}, t\right)>y\left(x_{2}, t\right) \text { when } x_{1}>x_{2} .
\end{aligned}
$$

Theorem 2.1 The monotonicity of $u(y(x, t), t)$ still hold on $\left(y\left(x_{1}, t\right), y\left(x_{2}, t\right)\right)$ if $u_{0}(x)$ is monotone on
$\left(x_{1}, x_{2}\right)$ for any $t>0$, where $u(y(x, t), t)$ is the solution of (1.1) and $u_{0} \in H^{4}(R)$.
Proof. Assume $u_{0}(x)$ is monotonic increase on $\left(x_{1}, x_{2}\right)$, and $s_{1}$ is the first time the monotonicity of $u(y(x, t), t)$ has changed on $\left(x_{1}, x_{2}\right)$.So $\exists m<n \in\left(x_{1}, x_{2}\right) u\left(y\left(m, s_{1}\right), s_{1}\right) \leq u\left(y\left(n, s_{1}\right), s_{1}\right)$ But when $t<s_{1}, u\left(y\left(m, s_{1}\right), s_{1}\right)>u\left(y\left(n, s_{1}\right), s_{1}\right)$.

From lemma 2.2 we know $\exists \Delta s_{1}$, when $t \in U\left(s_{1}, \Delta s_{1}\right),\|u(y(x, t), t)\|_{H^{4}}<+\infty$.Then linearize $u\left(y\left(m, s_{1}\right), s_{1}\right)-u\left(y\left(n, s_{1}\right), s_{1}\right)$ at time $s_{1}-\Delta s \in U\left(s_{1}, \Delta s_{1}\right)$
$u\left(y\left(m, s_{1}\right), s_{1}\right)-u\left(y\left(m, s_{1}\right), s_{1}\right)$
$=u\left(y\left(m, s_{1}-\Delta s\right), s_{1}-\Delta s_{1}\right)-u\left(y\left(m, s_{1}-\Delta s\right), s_{1}-\Delta s_{1}\right)$
$-\left[u_{y y y}\left(y\left(m, \xi_{1}\right), \xi_{1}\right)-u_{y y y}\left(y\left(n, \xi_{1}\right), \xi_{1}\right)\right] \Delta s+o(\Delta s)$
Where $\xi_{1} \in\left(s_{1}-\Delta s, s_{1}\right) \subset U\left(s_{1}, \Delta s_{1}\right)$.
Because $u\left(y\left(m, s_{1}-\Delta s\right), s_{1}-\Delta s\right)-u\left(y\left(n, s_{1}-\Delta s\right), s_{1}-\Delta s\right)>0$,so there exist appropriate small $s_{1}^{*}$ (such as let $\left.s_{1}^{*}=\frac{1}{2} \frac{u\left(y\left(m, s_{1}-s_{1}^{*}\right), s_{1}-s_{1}^{*}\right)-u\left(\left(n, s_{1}-s_{1}^{*}\right), s_{1}-s_{1}^{*}\right)}{\left|u_{y y y}\left(y\left(m, \xi_{1}\right), \xi_{1}^{*}\right)-u_{y y y}\left(y\left(n, \xi_{1}\right), \xi_{1}^{*}\right)\right|}\right)$ let
$u\left(y\left(m, s_{1}-s_{1}^{*}\right), s_{1}-s_{1}^{*}\right)-u\left(\left(n, s_{1}-s_{1}^{*}\right), s_{1}-s_{1}^{*}\right)$
$-\left[u\left(y\left(m, \xi_{1}^{*}\right), \xi_{1}^{*}\right)-u\left(\left(n, \xi_{1}^{*}\right), \xi_{1}^{*}\right)\right] s_{1}^{*}+o(\Delta s)>0$
Where $\xi_{1}^{*} \in\left(s_{1}-s_{1}^{*}, s_{1}\right) \subset U\left(s_{1}, \Delta s_{1}\right)$.
This is contradictory to the hypothesis, so we know the monotonicity of $u(y(x, t), t)$ not change on $\left(x_{1}, x_{2}\right)$ at time $s_{1}$. That means the monotonicity of $u(y(x, t), t)$ would never change on $\left(y\left(x_{1}, t\right), y\left(x_{2}, t\right)\right)$ for any $t>0$ if $u_{0}(x)$ is monotone on $\left(x_{1}, x_{2}\right)$.

Theorem 2.2. $u\left(y\left(x_{0}, t\right), t\right)>u(y(x, t), t) \quad\left(\quad\right.$ or $\quad u\left(y\left(x_{0}, t\right), t\right)<u(y(x, t), t) \quad$ ) if any $x \in U^{\circ}\left(x_{0}, h\right), u_{0}\left(x_{0}\right)>u_{0}(x)$ (or $u_{0}\left(x_{0}\right)<u_{0}(x)$ )for any $t>0$, where $u(y(x, t), t)$ is the solution of (1.1) and $u_{0} \in H^{4}(R)$.

Proof. Assume $x_{0}$ is an isolated maximum point of $u_{0}(x)$. By the smoothness and continuity of $u_{0}(x)$ we know $\exists h_{1}, x \in U^{\circ}\left(x_{0}, h\right), u_{0}(x)<u_{0}\left(x_{0}\right), u_{0}(x)$ is increasing on $\left(x_{0}-h, x_{0}\right)$, and decreasing on
$\left(x_{0}, x_{0}+h\right)$.Then from lemma 2.3 and theorem 2.1 we know the monotonicity of $u(y(x, t), t)$ on $\left(y\left(x_{0}-h, t\right), y\left(x_{0}, t\right)\right) \quad$ and $\quad\left(y\left(x_{0}, t\right), y\left(x_{0}+h, t\right)\right)$ will not change. So for any $t>0$, $x \in U^{\circ}\left(x_{0}, h\right), y\left(x_{0}, t\right) \quad$ still be an isolated maximum point of $u(y(x, t), t)$ on $\left(y\left(x_{0}-h, t\right), y\left(x_{0}+h, t\right)\right)$.

From theorem 2.1 and theorem 2.2 we know the isolated extreme point of initial curve will not change at any $t>0$.

Theorem $2.3 u(y(x, t), t)$ still be convex (or be concave) on $\left(y\left(x_{1}, t\right), y\left(x_{2}, t\right)\right)$ if $u_{0}(x)$ is convex ( or is concave ) for any $t>0$ on $\left(x_{1}, x_{2}\right)$, where $u(y(x, t), t)$ is the solution of (1.1) and $u_{0} \in H^{4}(R)$.

Proof. Assume $u_{0}(x)$ is convex on $\left(x_{1}, x_{2}\right)$ and $T_{1}$ is the first time the concavity of $u(y(x, t), t)$ change on $\left(x_{1}, x_{2}\right)$.So
$u\left(\lambda y\left(x, T_{1}\right)+(1-\lambda) y\left(z, T_{1}\right), T_{1}\right) \geq \lambda u\left(y\left(x, T_{1}\right), T_{1}\right)+(1-\lambda) u\left(y\left(z, T_{1}\right), T_{1}\right) \quad$ with $\quad x, z \in\left(x_{1}, x_{2}\right)$.From lemma 2.2 we know $\exists \Delta T_{1}$, then $\|u(y(x, t), t)\|_{H^{4}}<+\infty$ when $t \in U\left(T_{1}, \Delta T_{1}\right)$.For convenience of calculation, let $\lambda=\frac{1}{2}$, we get

$$
\begin{equation*}
u\left(\frac{1}{2}\left(y\left(x, T_{1}\right)+y\left(z, T_{1}\right)\right), T_{1}\right)-\frac{1}{2}\left(u\left(y\left(x, T_{1}\right), T_{1}\right)+u\left(y\left(z, T_{1}\right), T_{1}\right)\right) \geq 0 . \tag{11}
\end{equation*}
$$

The concavity of $u(y(x, t), t)$ would not change when $t<T_{1}$, then linearize $u\left(\frac{1}{2}\left(y\left(x, T_{1}\right)+y\left(z, T_{1}\right)\right), T_{1}\right)-\frac{1}{2}\left(u\left(y\left(x, T_{1}\right), T_{1}\right)+u\left(y\left(z, T_{1}\right), T_{1}\right)\right)$ at $T_{1}-\Delta T \in\left(T_{1}-\Delta T_{1}, T_{1}\right)$,
we get

$$
\begin{aligned}
& u\left(\frac{1}{2}\left(y\left(x, T_{1}\right)+y\left(z, T_{1}\right)\right), T_{1}\right)-\frac{1}{2}\left(u\left(y\left(x, T_{1}\right), T_{1}\right)+u\left(y\left(z, T_{1}\right), T_{1}\right)\right) \\
& =u\left(\frac{1}{2}\left(y\left(x, T_{1}-\Delta T\right)+y\left(z, T_{1}-\Delta T\right)\right), T_{1}-\Delta T\right) \\
& -\frac{1}{2}\left(u\left(y\left(x, T_{1}-\Delta T\right), T_{1}-\Delta T\right)+u\left(y\left(z, T_{1}-\Delta T\right), T_{1}-\Delta T\right)\right)
\end{aligned}
$$

$-w\left(u, y, x, z, \omega_{1}\right) \Delta T+o(\Delta t)$,
where $\omega_{1} \in\left(T_{1}-\Delta T, T_{1}\right) \subset U\left(T_{1}, \Delta T_{1}\right)$.
But from the hypothesis we know

$$
\begin{aligned}
& u\left(\frac{1}{2}\left(y\left(x, T_{1}-\Delta T\right)+y\left(z, T_{1}-\Delta T\right)\right), T_{1}-\Delta T\right) \\
& -\frac{1}{2}\left(u\left(y\left(x, T_{1}-\Delta T\right), T_{1}-\Delta T\right)+u\left(y\left(z, T_{1}-\Delta T\right), T_{1}-\Delta T\right)\right)<0
\end{aligned}
$$

so there exist appropriate small time $T_{1}^{*}$ and

$$
\begin{align*}
& u\left(\frac{1}{2}\left(y\left(x, T_{1}-\Delta T\right)+y\left(z, T_{1}-T_{1}^{*}\right)\right), T_{1}-T_{1}^{*}\right) \\
& -\frac{1}{2}\left(u\left(y\left(x, T_{1}-T_{1}^{*}\right), T_{1}-T_{1}^{*}\right)+u\left(y\left(z, T_{1}-T_{1}^{*}\right), T_{1}-T_{1}^{*}\right)\right) \\
& -w\left(u, y, x, z, \omega_{1}^{*}\right) \Delta T+o(\Delta t)<0 \tag{13}
\end{align*}
$$

Where $\omega_{1}^{*} \in\left(T_{1}-T_{1}^{*}, T_{1}\right) \subset U\left(T_{1}, \Delta T_{1}\right)$.
This is contradictory to the hypothesis, so we know the concavity of $u(y(x, t), t)$ not change on $\left(x_{1}, x_{2}\right)$ at time $T_{1}$. That means the concavity of $u(y(x, t), t)$ would never change on $\left(y\left(x_{1}, t\right), y\left(x_{2}, t\right)\right)$ for any $t>0$ if $u_{0}(x)$ is convex on $\left(x_{1}, x_{2}\right)$,.

This paper discuss the evolution of geometric properties of KdV equation by Lagrange coordinates , explains how would the solution curve change .

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