

Stability Results for Iteration Procedures using Integral Type Contraction Conditions

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Abstract: In this paper we obtained stability results for Picard iteration procedure using Integral type contraction conditions in complete metric space.

Keywords: Stability, Picard iteration procedure, multi-valued mapping, fixed point.

1. INTRODUCTION

Initially Urabe [23] did study on iteration procedures while the formal definition of stability of iteration procedures was given by Harder and Hicks. The study of stability of iteration procedures in metric space was first studied by Ostrowski [26].

Many authors (see [2], [3], [4], [6], [7], [9], [10], [14], [15], [18], [20], [21], [22], [30], etc) worked on convergence and stability result various mappings in different spaces. Harde Hicks [2,3] worked on theoretical as well as numerical aspect of stability. Several researchers ([1], [8], [10], [11], [12], [13], [14], [16], [17], [19], [20], [24], [25]) have done work on integral type inequalities. Harder and Hicks done a lot of work on stability of Picard iteration using various contraction conditions. Rhoades [7] established stability results for Mann, Kirk or Massa iteration procedures while Bosed and Rhoades [5] obtained stability results for both Picard and Mann iterations using general class of functions. Also Rezapour et al [28] obtained stability results for Picard iteration procedure for integral type contractive conditions.

Recently Branciari [1] worked on the following contraction integral condition: for some $\alpha \in [0, 1)$ such that

$$\int_0^{d(f(x), f(y))} \varphi(t) dt \leq \alpha \int_0^{d(x, y)} \varphi(t) dt$$

for all $x, y \in E$ where $\varphi: R^+ \rightarrow R^+$ is a Lebesgue integrable mapping which is summable, nonnegative with $\epsilon > 0$, $\int_0^\epsilon \varphi(t) dt > 0$.

While Rhoades [8] worked on the integral condition:

$$\int_0^{d(f(x), f(y))} \varphi(t) dt \leq k \int_0^{m(x, y)} \varphi(t) dt$$

$$\forall x, y \in E$$

where

$$m(x, y) = \max\{d(x, y), d(x, f(x)), d(y, f(y)), \frac{d(x, f(y)) + d(y, f(x))}{2}\}$$

And

$$\int_0^{d(f(x), f(y))} \varphi(t) dt \leq k \int_0^{M(x, y)} \varphi(t) dt \quad \forall x, y \in E$$

where

$$M(x, y) = \max\{d(x, y), d(x, f(x)), d(y, f(y)), d(x, f(y)), d(y, f(x))\}$$

with $k \in [0, 1)$

to establish stability results.

2. PRELIMINARIES

There are several iterative processes in the literature for which the fixed points of operators have been approximated over the years by various authors. Some of them are as follows:

For $x_0 \in X$, the sequence $\{x_n\}_{n=1}^\infty$ given by

$$x_{n+1} = Tx_n, \quad n = 0, 1, 2, \dots$$

(1)

is called the Picard iteration.

Definition 2.1 [32] Let E be a Banach space and T a mapping from E to E is a self map of E .

For $x_0 \in E$, the sequence $\{x_n\}_{n=1}^\infty$ given by

$$x_{n+1} = (1 - \alpha_n) x_n + \alpha_n Tx_n, \quad n = 0, 1, 2, \dots$$

(2)

where $\{\alpha_n\}_{n=0}^\infty$ is a real sequence in $[0, 1)$ such that $\sum_{n=0}^\infty \alpha_n = \infty$ is called the Mann iteration.

If we put $\alpha_n = 1$ in equation (2) we get the Picard iteration.

Definition 2.2 [27] For $x_0 \in E$, the sequence $\{x_n\}_{n=0}^\infty$

defined by

$$x_{n+1} = (1 - \alpha_n) x_n + \alpha_n T x_n$$

$$t_n = (1 - \beta_n) x_n + \beta_n T x_n, \quad n = 0, 1, 2, \dots$$

where $\{\alpha_n\}_{n=0}^\infty$ and $\{\beta_n\}_{n=0}^\infty$ are sequences in $[0, 1]$ and satisfy $\sum_{n=0}^\infty \alpha_n = \infty$ is called the Ishikawa iteration. If we put $\beta_n = 0$ then the Ishikawa iteration becomes the Mann iteration.

Definition 2.3 [26] Let (X, d) be a metric space and Y be an arbitrary nonempty set.
 $CL(X) = \{A; A \text{ is a non empty closed subset of } X\}$,
 $N(X) = \{A; A \text{ is a non-empty subset of } X\}$,
 For $x \in X$ and $B \in N(X)$ is defined as
 $D(a, B) = \inf \{d(a, b); b \in B\}$

$H(A, B) = \max \{\sup D(a, B); a \in A, \sup D(A, b); b \in B\}$
 H is called a generalized Hausdorff on $CL(X)$.

Definition 2.4 [29] Let (X, d) be a metric space and $Y \subseteq X$. Let $T: Y \rightarrow CL(X)$, $S: Y \rightarrow X$ and SY or TY is a complete subspace of X . Let T and S have a common fixed point p . For any $x_0 \in Y$ there exists a sequence $\{Sx_n\}$ generated by $Sx_{n+1} \in Tx_n, n = 1, 2, \dots$ converges to p . Let $\{Sy_n\} \subseteq X$ and set $\epsilon_n = H(Sy_{n+1}, Ty_n), n = 0, 1, 2, \dots$ then this iterative procedure is (S, T) stable if $\lim_{n \rightarrow \infty} \epsilon_n = 0$ implies that $\lim_{n \rightarrow \infty} Sy_n = p$.

Lemma 2.1 [30, 31] Let us consider $\delta \in [0, 1)$ to be a real number and $\{\epsilon_n\}$ be a sequence of positive numbers such that $\lim_{n \rightarrow \infty} \epsilon_n = 0$. If $\{u_n\}$ a sequence of positive real numbers such that

$$u_{n+1} \leq \delta u_n + \epsilon_n, \quad n = 0, 1, 2, \dots$$

Then, $\lim_{n \rightarrow \infty} u_n = 0$.

Lemma 2.2 Let (X, d) be a complete metric space and $\{u_n\}_{n=0}^\infty, \{v_n\}_{n=0}^\infty \subset X$ and $\{a_n\}_{n=0}^\infty \subset [0, 1)$ are sequences such that

$$\left| d(u_n, v_n) - \int_0^{d(u_n, v_n)} \varphi(t) dv(t) \right| \leq a_n$$

With $\lim_{n \rightarrow \infty} a_n = 0$. Then,

$$d(u_n, v_n) - a_n \leq \int_0^{d(u_n, v_n)} \varphi(t) dv(t) \leq d(u_n, v_n) + a_n$$

Where $\varphi: R^+ \rightarrow R^+$ a Lebesgue-Stieltjes integrable mapping which is summable, non-negative such that for each $\epsilon > 0, \int_0^\epsilon \varphi(t) dv(t) > 0$.

3. MAIN RESULTS

Theorem 3.1: Let $T: Y \rightarrow CL(X)$ and $S: Y \rightarrow X$ be a mapping satisfying

$$\int_0^{H(Tx, Ty)} \varphi(t) dv(t) \leq e^{LD(Sx, Tx)} [\psi \int_0^{D(Sx, Tx)} \varphi(t) dv(t) + k \int_0^{d(Sx, Sy)} \varphi(t) dv(t)]$$

on a complete metric space (X, d) and $S(Y) \subseteq T(Y)$ such that $S(Y)$ or $T(Y)$ is a complete subspace of X . Let p is a fixed point of T and for $x_0 \in X$, there exists a sequence

$$Sx_{n+1} \in Tx_n, \quad n = 0, 1, 2, \dots$$

Let $v, \psi: R^+ \rightarrow R^+$ be monotone increasing function such that $\psi(0) = 0$ and $\psi: R^+ \rightarrow R^+$ is a Lebesgue-Stieltjes integrable mapping which is summable, non-negative and such that for each $\epsilon > 0, \int_0^\epsilon \varphi(t) dv(t) > 0$, then Picard iteration is T-Stable.

Proof: Let us consider $\lim_{n \rightarrow \infty} \epsilon_n = 0$ where $\epsilon_n = H(Sy_{n+1}, Ty_n)$ such that $\{y_n\}_{n=0}^\infty \subset X$.

Let us consider $\{a_n\}_{n=0}^\infty \subset (0, 1)$

Then by using lemma 2.2 and triangular inequality, we get

$$\begin{aligned} \int_0^{d(Sy_{n+1}, p)} \varphi(t) dv(t) &\leq d(Sy_{n+1}, p) + a_n \\ &\leq H(Sy_{n+1}, Ty_n) + D(Ty_n, p) + a_n \\ &\leq [H(Sy_{n+1}, Ty_n) - a_n] + [D(Ty_n, p) - a_n] + 3a_n \\ &\leq \int_0^{d(Sy_{n+1}, Ty_n)} \varphi(t) dv(t) + \int_0^{H(Ty_n, Tp)} \varphi(t) dv(t) + 3a_n \end{aligned}$$

$$\begin{aligned} &\leq \int_0^{\epsilon_n} \varphi(t) dv(t) + 3a_n + e^{LD(Sp, Tp)} \\ &[\psi \int_0^{D(Sp, Tp)} \varphi(t) dv(t) + k \int_0^{d(Sp, Sy_n)} \varphi(t) dv(t)] \end{aligned}$$

$$\begin{aligned} &\leq k e^{LD(Sp, Tp)} \int_0^{d(Sp, Sy_n)} \varphi(t) dv(t) + \int_0^{\epsilon_n} \varphi(t) dv(t) + 3a_n \\ &\leq k e^{Ld(p, p)} \int_0^{d(p, Sy_n)} \varphi(t) dv(t) + \int_0^{\epsilon_n} \varphi(t) dv(t) + 3a_n \end{aligned}$$

By lemma 2.1, we have,

$$u_{n+1} \leq \delta u_n + \epsilon'_n$$

$$0 \leq \delta = ke^{Ld(p,p)} < 1$$

$$u_n = \int_0^{d(p,Sy_n)} \varphi(t)dv(t)$$

$$\in'_n = \int_0^{\in'_n} \varphi(t)dv(t) + 3a_n$$

With

$$\lim_{n \rightarrow \infty} \in'_n = \lim_{n \rightarrow \infty} \left(\int_0^{\in'_n} \varphi(t)dv(t) + 3a_n \right) = 0$$

So that by Lemma 2.1 and $\int_0^\infty \varphi(t)dv(t) > 0$ for each $\in > 0$

We have,

$$\lim_{n \rightarrow \infty} \int_0^{d(p,Sy_n)} \varphi(t)dv(t) = 0$$

Thus,

$$\lim_{n \rightarrow \infty} d(p, Sy_n) = 0$$

$$\lim_{n \rightarrow \infty} Sy_n = p$$

Conversely, let $\lim_{n \rightarrow \infty} Sy_n = p$ then by lemma 2.2,

$$\begin{aligned} \int_0^{\in'_n} \varphi(t)dv(t) &= \int_0^{H(Sy_{n+1}, Ty_n)} \varphi(t)dv(t) \\ &\leq H(Sy_{n+1}, Ty_n) + a_n \\ &\leq d(Sy_{n+1}, p) + D(p, Ty_n) + a_n \\ &\leq [d(Sy_{n+1}, p) - a_n] + [D(p, Ty_n) - a_n] + 3a_n \end{aligned}$$

$$\leq \int_0^{d(Sy_{n+1}, p)} \varphi(t)dv(t) + \int_0^{H(Ty_n, Tp)} \varphi(t)dv(t) + 3a_n$$

$$\leq \int_0^{d(Sy_{n+1}, p)} \varphi(t)dv(t) + e^{LD(Sp, Tp)}$$

$$[\psi \int_0^{D(Sp, Tp)} \varphi(t)dv(t) + k \int_0^{d(Sp, Sy_n)} \varphi(t)dv(t)] + 3a_n$$

$$\leq \int_0^{d(Sy_{n+1}, p)} \varphi(t)dv(t) +$$

$$\begin{aligned} &e^{Ld(p,p)} [\psi \int_0^{d(p,p)} \varphi(t)dv(t) + \\ &k \int_0^{d(p, Sy_n)} \varphi(t)dv(t)] + 3a_n \\ &\leq \int_0^{d(Sy_{n+1}, p)} \varphi(t)dv(t) + k \int_0^{d(p, Sy_n)} \varphi(t)dv(t) + 3a_n \\ &\rightarrow 0 \text{ as } n \rightarrow \infty \end{aligned}$$

Hence,

$$\lim_{n \rightarrow \infty} \in_n = 0.$$

Corollary 3.1: Let $T: X \rightarrow X$ be a single valued mapping satisfying $\int_0^{d(Tx, Ty)} \varphi(t)dv(t) \leq e^{Ld(x, Tx)} [\psi \int_0^{d(x, Tx)} \varphi(t)dv(t) + k \int_0^{d(x, y)} \varphi(t)dv(t)]$ on a complete metric space (X, d) . Let p is a fixed point of T and for $x_0 \in X$, there exists a sequence

$$Sx_{n+1} = Tx_n, \quad n =$$

0, 1, 2, ...

Let $v, \psi: R^+ \rightarrow R^+$ be monotone increasing function such that $\psi(0) = 0$ and $\psi: R^+ \rightarrow R^+$ is a Lebesgue-integrable mapping which is summable, non-negative and such that for each

$\in > 0, \int_0^\infty \varphi(t)dv(t) > 0$, then Picard iteration is T-Stable.

Proof: We will prove similarly as in theorem 3.1.

Theorem 3.2: Let $T: Y \rightarrow CL(X)$ and $S: Y \rightarrow X$ be a mapping satisfying

$$\begin{aligned} &\int_0^{H(Tx, Ty)} \varphi(t)dv(t) \leq \\ &\alpha \int_0^{\max(d(Sx, Sy), D(Sx, Ty), D(Sy, Ty))} \varphi(t)dv(t) + \\ &\quad \int_0^{D(Sx, Ty)} \varphi(t)dv(t) + b \int_0^{d(Sx, Sy)} \varphi(t)dv(t) \end{aligned}$$

for all $x, y \in X, 0 \leq \alpha < 1, a, b \geq 0, a + b < 1$ on a complete metric space (X, d) and $S(Y) \subseteq T(Y)$ such that $S(Y)$ or $T(Y)$ is a complete subspace of X . Let p is a fixed point of T, S and for $x_0 \in X$, there exists a sequence

$$x_{n+1} \in Tx_n, \quad n =$$

0, 1, 2, ...

Let $v, \psi: R^+ \rightarrow R^+$ be monotone increasing function such that $\psi(0) = 0$ and $\psi: R^+ \rightarrow R^+$ a Lebesgue-integrable mapping which is summable, non-negative and such that for each

$\epsilon > 0$, $\int_0^\epsilon \varphi(t)dv(t) > 0$, then the Picard iteration is T-Stable.

Proof: Let us consider $\lim_{n \rightarrow \infty} \epsilon_n = 0$ where $\epsilon_n = H(y_{n+1}, Ty_n)$ such that $\{y_n\}_{n=0}^\infty \subset X$. Let us consider $\{a_n\}_{n=0}^\infty \subset (0, 1)$. Then by using lemma 2.2 and triangular inequality, we get,

$$\begin{aligned} & \int_0^{d(Sy_{n+1}, p)} \varphi(t)dv(t) \leq d(Sy_{n+1}, p) + \\ & a_n \\ & \leq H(Sy_{n+1}, Ty_n) + D(Ty_n, p) + a_n \\ & \leq [H(Sy_{n+1}, Ty_n) - a_n] + [D(Ty_n, p) - a_n] + 3a_n \\ & \leq \int_0^{H(Sy_{n+1}, Ty_n)} \varphi(t)dv(t) + \int_0^{H(Ty_n, Tp)} \varphi(t)dv(t) \\ & \qquad \qquad \qquad + 3a_n \end{aligned}$$

$$\leq \alpha \int_0^{\max(d(Sy_n, Sp), D(Sy_n, Tp), D(Sp, Tp))} \varphi(t)dv(t)$$

$$(1 - \alpha) [a \int_0^{D(Sy_n, Tp)} \varphi(t)dv(t) + b \int_0^{d(Sy_n, Sp)} \varphi(t)dv(t)]$$

$$+ \int_0^{\epsilon_n} \varphi(t)dv(t) + 3a_n.$$

$$\leq \int_0^{\epsilon_n} \varphi(t)dv(t) + 3a_n +$$

$$\alpha \int_0^{\max(d(Sy_n, p), d(Sy_n, p), d(p, p))} \varphi(t)dv(t) +$$

$$(1 - \alpha) [a \int_0^{d(Sy_n, p)} \varphi(t)dv(t) + b \int_0^{d(Sy_n, p)} \varphi(t)dv(t)]$$

$$\begin{aligned} & \leq \\ & \int_0^{\epsilon_n} \varphi(t)dv(t) + 3a_n + \\ & \alpha \int_0^{d(Sy_n, p)} \varphi(t)dv(t) + \qquad (1 - \\ & \alpha)(a + b) \int_0^{d(Sy_n, p)} \varphi(t)dv(t) \end{aligned}$$

$$\leq \int_0^{\epsilon_n} \varphi(t)dv(t) + 3a_n$$

$$+ (\alpha + (1 - \alpha)(a + b)) \int_0^{d(Sy_n, p)} \varphi(t)dv(t)$$

By lemma 2.1, we have,

$$u_{n+1} \leq \delta u_n + \epsilon'_n$$

$$0 \leq \delta = (\alpha + (1 - \alpha)(a + b)) < 1$$

$$u_n = \int_0^{d(p, Sy_n)} \varphi(t)dv(t)$$

$$\epsilon'_n = \int_0^{\epsilon_n} \varphi(t)dv(t) + 3a_n$$

With,

$$\lim_{n \rightarrow \infty} \epsilon'_n = \lim_{n \rightarrow \infty} (\int_0^{\epsilon_n} \varphi(t)dv(t) + 3a_n) = 0$$

So that by Lemma 2.1 and $\int_0^\epsilon \varphi(t)dv(t) > 0$ for each $\epsilon > 0$, We have,

$$\lim_{n \rightarrow \infty} \int_0^{d(p, Sy_n)} \varphi(t)dv(t) = 0$$

Thus,

$$\lim_{n \rightarrow \infty} d(p, Sy_n) = 0$$

$$\lim_{n \rightarrow \infty} Sy_n = p.$$

Conversely,

$$\text{Let } \lim_{n \rightarrow \infty} Sy_n = p$$

then by lemma 2.2,

$$\begin{aligned} \int_0^{\epsilon_n} \varphi(t)dv(t) &= \int_0^{H(Sy_{n+1}, Ty_n)} \varphi(t)dv(t) \\ &\leq H(Sy_{n+1}, Ty_n) + a_n \end{aligned}$$

$$\leq d(Sy_{n+1}, p) + D(p, Ty_n) + a_n$$

$$\leq [d(Sy_{n+1}, p) - a_n] + [D(p, Ty_n) - a_n] + 3a_n$$

$$\leq \int_0^{d(Sy_{n+1}, p)} \varphi(t)dv(t) + \int_0^{H(Ty_n, Tp)} \varphi(t)dv(t) + 3a_n$$

$$\leq \int_0^{d(Sy_{n+1}, p)} \varphi(t)dv(t) + 3a_n$$

$$+ \alpha \int_0^{\max(d(Sy_n, Sp), D(Sy_n, Tp), D(Sp, Tp))} \varphi(t)dv(t) +$$

$$(1 - \alpha) [a \int_0^{D(Sy_n, Tp)} \varphi(t)dv(t) + b \int_0^{d(Sy_n, Sp)} \varphi(t)dv(t)]$$

$$\leq \int_0^{d(Sy_{n+1}, p)} \varphi(t) dv(t) + 3a_n + \alpha \int_0^{d(Sy_n, p)} \varphi(t) dv(t) + (1 - \alpha) [a \int_0^{d(Sy_n, p)} \varphi(t) dv(t) + b \int_0^{d(Sy_n, p)} \varphi(t) dv(t)] \rightarrow 0 \text{ as } n \rightarrow \infty$$

Thus,

$$\lim_{n \rightarrow \infty} \epsilon_n = 0.$$

Corollary 3.2: Let $T: X \rightarrow X$ be a single-valued mapping satisfying

$$\int_0^{d(Tx, Ty)} \varphi(t) dv(t) \leq \alpha \int_0^{\max(d(x, y), d(x, Ty), d(y, Ty))} \varphi(t) dv(t) + (1 - \alpha) [a \int_0^{d(x, Ty)} \varphi(t) dv(t) + b \int_0^{d(x, y)} \varphi(t) dv(t)]$$

for all $x, y \in X, 0 \leq \alpha < 1, a, b \geq 0, a + b < 1$ on a complete metric space (X, d) . Let p is a fixed point of T

and for $x_0 \in X$, there exists a sequence

$$x_{n+1} = Tx_n, n = 0, 1, 2, \dots$$

Let $v, \psi: R^+ \rightarrow R^+$ be monotone increasing function such that $\psi(0) = 0$ and $\psi: R^+ \rightarrow R^+$ a Lebesgue-stieltjes integrable mapping which is summable, non-negative and such that for each $\epsilon > 0, \int_0^\epsilon \varphi(t) dv(t) > 0$, then the Picard iteration is T-Stable.

Proof: We will prove similarly as in theorem 3.2.

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