

Behaviour of Solutions of Linear Systems

VijayalakshmiMenon R

Asst. Prof, Dept. of Mathematics, Govt. College, Madappally, Vatakara, Calicut, Kerala, S. India

Abstract

This paper deals with the behaviour of solutions of linear systems. The notions of stability, boundedness and asymptotic behaviour of solutions of a general linear system are studied.

AMS SUBJECT CLASSIFICATION CODE : 34D20

Keywords: Stability, perturbation, boundedness, almost-constant, trace, perturbed equation, perturbing matrix.

1. INTRODUCTION

We consider the behaviour of the solutions of the linear differential equation

$$\frac{dz}{dt} = [A + B(t)]z \rightarrow (1)$$

where A is a constant matrix and B (t) is small as $t \rightarrow \infty$.

Two particularly important cases are those where $\|B(t)\| \rightarrow 0$ or where $\int_0^\infty \|B(t)\| dt < \infty$

The solutions of (1) share many properties with the solutions of

$$\frac{dy}{dt} = Ay \rightarrow (2)$$

so far as their behaviours are concerned.

In this paper, section 2 deals with the concept of stability of linear equations. In section 3, the boundedness property of solutions and the sufficient conditions for boundedness of solutions are studied in detail. Section 4 illustrates the asymptotic behaviour of solutions of linear systems.

2. STABILITY OF LINEAR EQUATIONS [1]

2.1Defn: The solutions of $\frac{dy}{dt} = A(t)y \rightarrow (3)$

are stable with respect to a property P and perturbations B(t) of type T if the solutions of $\frac{dz}{dt} = [A(t) + B(t)]z \rightarrow (4)$ also possess property P. If this is not true, the solutions of (3) are said to be unstable with respect to property P under perturbations of type T.

To illustrate the above definition, we consider two simple differential equations:

$$\frac{du}{dt} = -au \rightarrow (5)$$

and

$$\frac{dv}{dt} = [-a + b(t)]v \rightarrow (6)$$

where $a > 0$ and $b(t) \rightarrow 0$ as $t \rightarrow \infty$.

Considering the solutions of (5) and (6)

$$\frac{du}{dt} = -au \Rightarrow \frac{du}{u} = -adt$$

$$\Rightarrow \log u = -at + c$$

$$\Rightarrow u = ce^{-at} \Rightarrow \lim_{t \rightarrow \infty} u = 0$$

$$\frac{dv}{dt} = [-a + b(t)]v$$

$$\Rightarrow \frac{dv}{v} = [-a + b(t)]dt$$

$$\Rightarrow \log v = -at + \int b(t)dt$$

$$\Rightarrow v = e^{-at + \int b(t)dt}$$

$$\Rightarrow \lim_{t \rightarrow \infty} v = 0$$

Thus, both solutions u and v tend to zero as $t \rightarrow \infty$

$$\text{Also, } \lim_{t \rightarrow \infty} \frac{\log u}{t} = \lim_{t \rightarrow \infty} \frac{\log v}{t} = -a$$

So, both solutions u and v have the following properties:

$$t \rightarrow \infty \quad t \rightarrow \infty$$

i) $\lim_{t \rightarrow \infty} u = \lim_{t \rightarrow \infty} v = 0$

and

ii) $\lim_{t \rightarrow \infty} \frac{\log u}{t} = \lim_{t \rightarrow \infty} \frac{\log v}{t} = -a$

Now suppose $a=0$ and $b(t) = \frac{1}{t}$

$$\text{Then } \frac{du}{dt} = -au \Rightarrow u = ce^{-at}$$

$$\Rightarrow u = c \text{ when } a = 0$$

and

$$\frac{dv}{dt} = [-a + b(t)]v$$

$$\Rightarrow \frac{dv}{v} = [-a + b(t)]dt = \left[-a + \frac{1}{t}\right] dt$$

$$\Rightarrow \log v = -at + \log t$$

$$\Rightarrow v = te^{-at}$$

$\therefore v$ is unbounded as $t \rightarrow \infty$

With respect to property (ii), since $a=0$,

$$\frac{\log u}{t} = 0$$

$$\therefore \lim_{t \rightarrow \infty} \frac{\log u}{t}$$

$$\text{Also } \frac{\log v}{t} = 0 \Rightarrow \lim_{t \rightarrow \infty} \frac{\log v}{t} = 0$$

Thus, there is stability with respect to property (ii) but instability with respect to property (i) – the property of boundedness.

2.2 Note:

If we replace $\frac{1}{t}$ by a function which is integrable over (t_0, ∞) , then boundedness will be preserved.

2.3 Note:

The most important property of solutions is that of boundedness. If a solution is bounded, we are interested in knowing whether or not it approaches zero at $t \rightarrow \infty$

3.1 BOUNDEDNESS OF SOLUTIONS([1],[2])

3.1.1 Definition:

We call the coefficient matrix $A(t)$ of the differential equation

$$\frac{dz}{dt} = A(t)z$$

almost constant if $\lim_{t \rightarrow \infty} A(t) = A$, a constant matrix.

3.1.2 Lemma(Fundamental lemma):

If $u, v \geq 0$, if C_1 is a positive constant,

and if

$$u \leq C_1 + \int_0^t uv dt_1 \rightarrow (7)$$

$$\text{then, } u \leq C_1 \exp\left(\int_0^t v dt_1\right) \rightarrow (8)$$

Proof: From (7), we have

$$\frac{uv}{C_1 + \int_0^t uv dt_1} \leq v \rightarrow (9)$$

Integrating both sides of (9) between 0 and t, we get

$$\log\left[C_1 + \int_0^t uv dt_1\right] - \log C_1 \leq \int_0^t v dt_1$$

$$\text{i.e., } \log\left(\frac{C_1 + \int_0^t uv dt_1}{C_1}\right) \leq \int_0^t v dt_1$$

$$C_1 + \int_0^t uv dt_1 \leq C_1 \exp\left(\int_0^t v dt_1\right) \rightarrow (10)$$

$$\therefore u \leq C_1 + \int_0^t uv dt_1 \leq C_1 \exp\left(\int_0^t v dt_1\right) \rightarrow (11)$$

which is the fundamental lemma.

3.1.3 Theorem:

If all solutions of

$$dy/dt = Ay \rightarrow (12)$$

where A is a constant matrix, are bounded as $t \rightarrow \infty$, then the same is true of the solutions of

$$\frac{dz}{dt} = [A + B(t)]z \rightarrow (13)$$

provided $\int_0^\infty \|B(t)\| dt < \infty$

Proof:

Equation (13) can be written as

$$\frac{dz}{dt} = Az + B(t)z \rightarrow (14)$$

Every solution of (14) satisfies a linear integral equation

$$z = y + \int_0^t Y(t-t_1)B(t_1)z(t_1) dt_1 \rightarrow (15)$$

where y is the solution of (12) for which $y(0) = z(0)$ and

Y is the matrix solution of

$$\frac{dY}{dt} = AY, Y(0) = I \rightarrow (16)$$

we have $y = Yy(0) = Yz(0)$

$$\text{Let } C_1 = \max\left(\sup_{t \geq 0} \|y\|, \sup_{t \geq 0} \|Y\|\right)$$

Then, from (15), we get

$$\|z\| \leq \|y\| + \int_0^t \|Y(t-t_1)\| \|B(t_1)\| \|z(t_1)\| dt_1$$

$$\leq C_1 + C_1 \int_0^t \|B(t_1)\| \|z(t_1)\| dt_1 \rightarrow (17)$$

Applying the fundamental lemma in (17), we get

$$\|z\| \leq C_1 \exp\left(C_1 \int_0^t \|B(t_1)\| dt_1\right) \rightarrow (18)$$

Since $\int_0^\infty \|B(t)\| dt < \infty$, from (18), it follows that $\|z\|$ is bounded.

i.e., the solutions of equation (13) are bounded.

Hence, the theorem.

3.1.4 Theorem

If all the solutions of the equation

$$\frac{dy}{dt} = Ay \rightarrow (19)$$

approach zero as $t \rightarrow \infty$, the same holds for the solutions of

$$\frac{dz}{dt} = [A + B(t)]z \rightarrow (20)$$

provided that $\|B(t)\| \leq C_1$ for $t \geq t_0$, where C_1 is a constant which depends upon A .

Proof

Every solution of (20) satisfies a linear integral equation

$$z = y + \int_0^t Y(t-t_1)B(t_1)z(t_1) dt_1 \rightarrow (21)$$

where Y is the matrix solution of

$$\frac{dY}{dt} = AY, Y(0) = I$$

$$\text{Now } \frac{dy}{dt} = AY \Rightarrow \frac{dy}{y} = A dt$$

$$\Rightarrow \log Y = At + B$$

$$\Rightarrow Y = e^{At+B} = Ce^{At}$$

Since $\|Y\| \rightarrow 0$ as $t \rightarrow \infty$, \exists a positive constant α such that

$$\|Y\| \leq C_2 e^{-\alpha t} \text{ for } t \geq 0 \rightarrow (22)$$

By theorem 3.1.3, we have $y =$

$$Yy(0) \therefore \|y\| \leq C_2 e^{-\alpha t} \text{ for } t \geq 0 \rightarrow (23)$$

Hence, from (21),

$$\|z\| \leq C_2 e^{-\alpha t} + C_2 \int_0^t e^{-\alpha(t-t_1)} \|B(t_1)\| \|z(t_1)\| dt_1 \rightarrow (24)$$

Since $\|B(t)\| \leq C_1$ for $t \geq t_0$, we get

$$\|z\| e^{\alpha t} \leq C_2 + C_1 C_2 \int_0^t e^{\alpha t_1} \|z(t_1)\| dt_1 \rightarrow (25)$$

Applying fundamental lemma in equation (25), we get

$$\|z\| e^{\alpha t} \leq C_2 \exp\left(\int_0^t C_1 C_2 dt_1\right) \rightarrow (26)$$

$$\text{i.e., } \|z\| e^{\alpha t} \leq C_2 e^{C_1 C_2 t} \rightarrow (27)$$

If $C_1 C_2 < \alpha$, then the above equation gives $\|z\| \rightarrow 0$ as $t \rightarrow \infty$. But the constants C_2 and α depend upon the characteristic roots of A. Hence, it follows that C_1 depends upon A. Hence the theorem.

3.2 SUFFICIENT CONDITIONS FOR BOUNDEDNESS OF SOLUTIONS. (I1)

In this section, the sufficient conditions required for the solutions of a linear system to be bounded, are being dealt with

The boundedness of the solutions of $\frac{dy}{dt} = A(t)y \rightarrow (28)$

together with the condition $\|B(t)\| \rightarrow 0$ as $t \rightarrow \infty$ is not sufficient to ensure the boundedness of all solutions of

$$\frac{dz}{dt} = [A(t) + B(t)]z \rightarrow (29)$$

Even if we amend the condition $\|B(t)\| \rightarrow 0$ as $t \rightarrow \infty$, by the condition $\int_0^\infty \|B(t)\| dt < \infty$, the sufficiency remains unjustified. This fact is illustrated in the following theorem:

3.2.1 Theorem

There is an equation of the type

$$\frac{dy}{dt} = A(t)y$$

with the property that all solutions approach zero as $t \rightarrow \infty$, and a matrix B(t) for which $\int_0^\infty \|B(t)\| dt < \infty$, such that all solutions of the equation

$$\frac{dz}{dt} = [A(t) + B(t)]z$$

are not bounded.

Proof: Consider the equations

$$\frac{dy_1}{dt} = -ay_1 \rightarrow (30)$$

and

$$\frac{dy_2}{dt} = [\sin(\log t) + \cos(\log t) - 2a]y_2 \rightarrow (31)$$

We solve for y_1 and y_2

$$\text{Equation (30)} \rightarrow \frac{dy_1}{y_1} = -a dt$$

Integrating, $\log y_1 = -at + \log C_1$
i.e., $y_1 = C_1 e^{-at}$

Equation (31)

$$\rightarrow \frac{dy_2}{y_2} = [\sin(\log t) + \cos(\log t) - 2a] dt$$

Integrating,

$$\log y_2 = [t \sin(\log t) - 2at] + \log C_2$$

$$\therefore y_2 = C_2 e^{t \sin(\log t) - 2at}$$

Thus, the general solutions of (30) and (31) are respectively

$$y_1 = C_1 e^{-at} \rightarrow (32)$$

and

$$y_2 = C_2 e^{t \sin(\log t) - 2at} \rightarrow (33)$$

If 'a' is any non-negative constant, then every solution of (32) and (33) approach zero as $t \rightarrow \infty$

Let

$$B(t) = \begin{bmatrix} 0 & 0 \\ e^{-at} & 0 \end{bmatrix}$$

be the perturbing matrix

The perturbed equation has the form

$$\frac{dz_1}{dt} = -az_1 \rightarrow (34)$$

and

$$= [\sin(\log t) + \cos(\log t) - 2a]z_2 + z_1 e^{-at} \rightarrow (35)$$

Equation (34) gives $z_1 = C_1 e^{-at}$ and

$$\text{Equation (35) gives } z_2 = e^{\int [\sin(\log t) - 2a] dt}$$

$$\left\{ C_2 + C_1 \int_0^t e^{-t_1 \sin(\log t_1)} dt_1 \right\}$$

$$\text{Let } t = e^{\left(2n + \frac{1}{2}\right)\pi}$$

If $1 < 2a < 1 + e^{-\frac{\pi}{2}}$, then

$$\int_0^t e^{-t_1 \sin(\log t_1)} dt_1 > \int_{te^{-\frac{2\pi}{3}}}^{te^{-\frac{\pi}{3}}} e^{-t_1 \sin(\log t_1)} dt_1 > t \left(e^{-\frac{2\pi}{3}} - e^{-\pi} \right) \exp\left(-\frac{e^{-\pi} t}{2}\right),$$

which implies the solutions of (34) and (35) will be bounded only if $C_1 = 0$

Now, $C_1 = 0 \Leftrightarrow z_1(0) = 0$

Thus, if $z_1(0) \neq 0$, the solutions of (35) are not bounded

3.2.2 Theorem:

If all the solutions of the equation $\frac{dy}{dt} = A(t)y$ are bounded, then all the solutions of the

equation $\frac{dz}{dt} = [A(t) + B(t)]z$ are bounded, provided

(a) $\int_0^\infty \|B(t)\| dt < \infty$

&

(b) $\lim_{t \rightarrow \infty} \int_0^t \text{tr}(A) dt > -\infty$

Proof: Expressing z in terms of y, we have

$$z = y + \int_0^t Y(t) Y^{-1}(t_1) B(t_1) z(t_1) dt_1$$

$$\therefore \|z\| \leq \|y\| +$$

$$\int_0^t \|Y(t)\| \|Y^{-1}(t_1)\| \|B(t_1)\| \|z(t_1)\| dt_1$$

Since $\det Y = \exp \left[\int_0^t \text{tr}(A) dt \right]$, if

condition (b) is satisfied, then

$\|Y^{-1}(t)\|$ is bounded as $t \rightarrow \infty$

$$\therefore \|z\| \leq C_1 + C_1 \int_0^t \|B(t_1)\| \|z(t_1)\| dt_1$$

Applying the fundamental lemma in the above equation, we get

$$\|z\| \leq C_1 \exp \left(C_1 \int_0^t \|B(t_1)\| dt_1 \right)$$

Since $\int_0^\infty \|B(t)\| dt < \infty$, $\|z\|$ is bounded

Hence, the theorem.

4. ASYMPTOTIC BEHAVIOUR OF SOLUTIONS [3]

In the previous section, we have dealt with the necessary and sufficient conditions for the boundedness of a solution. If a solution is bounded, we are interested in knowing whether or not it approaches zero as $t \rightarrow +\infty$, which depicts the asymptotic behaviour of the solutions.

Consider the linear system

$$\frac{dy}{dt} = A(t)y, \quad t \geq 0 \rightarrow (36)$$

where $A(t)$ is a real-valued continuous $n \times n$ matrix on $0 \leq t < \infty$

We want to find the behaviour of solutions of (36) as $t \rightarrow \infty$

If the eigen values of the matrix A are known, all solutions of (36) are completely determined. Hence, the eigen values determine the behaviour of solutions as $t \rightarrow \infty$

4.1 Theorem:

Let $A(t)$ be a real-valued, continuous, $n \times n$ matrix on $[0, \infty)$.

Let $M(t)$ be the largest eigen value of $(t) + A^T(t)$, where $A^T(t)$ is the transpose of the matrix $A(t)$.

If $\lim_{t \rightarrow \infty} \int_{t_0}^t M(s)ds = -\infty$ ($t_0 > 0$ is fixed) \rightarrow (37), then every solution of (36) tends to zero as $t \rightarrow +\infty$.

Proof:

Let ϕ be a solution of (36)

Then $|\phi(t)|^2 = \phi^T(t)\phi(t)$

$$\begin{aligned} \therefore \frac{d}{dt} |\phi(t)|^2 &= \phi^T(t)\phi'(t) + \phi^{T'}(t)\phi(t) \\ &= \phi^T(t)A(t)\phi(t) + A^T(t)\phi^T(t)\phi(t) \\ &= \phi^T(t)[A(t) + A^T(t)]\phi(t) \end{aligned}$$

Since $M(t)$ is the largest eigen value of the symmetric matrix $A(t) + A^T(t)$, we get

$$|\phi^T(t)[A(t) + A^T(t)]\phi(t)| \leq M(t)|\phi(t)|^2$$

Thus,

$$0 \leq |\phi(t)|^2 \leq |\phi(t_0)|^2 \left(\exp \left[\int_{t_0}^t M(s)ds \right] \right) \rightarrow (38)$$

By condition (37), the right side of (38) tends to zero

Hence, $\lim_{t \rightarrow \infty} \phi(t) = 0$

Hence, the theorem

4.2 Theorem:

Let $m(t)$ be the smallest eigen value of $A(t) + A^T(t)$. If

$$\limsup_{t \rightarrow \infty} \int_{t_0}^t m(s)ds = +\infty \quad (t_0 > 0 \text{ is fixed}) \rightarrow (39)$$

then every non-zero solution of (36) is unbounded as $t \rightarrow +\infty$.

Proof: Let ϕ be a solution of (36)

As in the previous theorem, we have

$$\frac{d}{dt} |\phi(t)|^2 = \phi^T(t) [A(t) + A^T(t)]\phi(t) \rightarrow (40)$$

Since $m(t)$ is the smallest eigen value of $(t) + A^T(t)$, we get

$$\frac{d}{dt} |\phi(t)|^2 \geq m(t)|\phi(t)|^2$$

Thus, $\frac{d}{dt} \left\{ e^{-\int_{t_0}^t m(s)ds} |\phi(t)|^2 \right\}$

$$= e^{-\int_{t_0}^t m(s)ds} \left\{ \frac{d}{dt} |\phi(t)|^2 - m(t)|\phi(t)|^2 \right\} \geq 0$$

$$\therefore |\phi(t)|^2 \geq |\phi(t_0)|^2 e^{\int_{t_0}^t m(s)ds} \rightarrow (41)$$

By condition (39) the right side of (41) tends to $+\infty$ as $t \rightarrow +\infty$.

$\therefore \lim_{t \rightarrow \infty} |\phi(t)| = +\infty$

i.e, the solution ϕ is unbounded

Hence, the theorem

5. CONCLUSION

This paper is a work on the behaviour of solutions of linear systems, when the time is increased indefinitely; which is a kind of stability property. This provides an insight into the necessary steps to be taken to avoid unwanted phenomena or criteria in a system.

REFERENCES

- [1] BELLMAN. R, Stability theory of differential equations, McGraw-Hill Book Company, INC, 1953, pp 32-60.
- [2] BOYCE and DiPrima, Elementary differential equations and boundary value problems, Wiley Nineth Edition, pp 470-520.
- [3] DEO. S.G and RAGHAVENDRA.V, Ordinary differential equations and stability theory, Tata McGraw-Hill Publishing Company Ltd, New Delhi, pp 164-205.