

Fixed Point Theorem Using Generalized Meir-Keeler Contractions on G-Metric Spaces

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Abstract-In this paper we consider the concept of G-metric space and prove some fixed point theorems for Meir-Keeler contraction. We also present some applications.

Keywords-Fixed Point, G-metric space, Meir-Keeler contraction

1 Introduction and Preliminaries

Fixed point theory has many applications in wide areas of mathematics, also in many branches of quantitative sciences such as economics and computer sciences. The Banach contraction principle [13] is the famous result in this field. This result has many generalizations out of which Meir-Keeler contraction is one.

The Meir-Keeler contraction [22] which was proved in 1969 plays an important role in the field of fixed point theory and it has been extended by many authors.

In 2009, T.H. Chang and C.M. Chen [14] defined the weaker Meir-Keeler type function $\psi: \mathfrak{R}^+ \rightarrow \mathfrak{R}^+$ and proved following common fixed point theorem of two set-valued mappings in a complete metric space:

Let (X, d) be a complete metric space, and let $T, S: X \rightarrow B(X)$. If (T, S) have the non-contraction property, and if for each $t > 0$ with $\psi(t) < t$ and $\{\psi^n(t)\}_{n \in \mathbb{N}}$ is non-increasing, then S and T has a unique common fixed point a in. Moreover,

$$Sa = Ta = \{a\}.$$

In 2010 C. Chen and T. Chang [15] defined a weaker Meir-Keeler type function $\psi: \text{int}P \cup \{0\} \rightarrow \text{int}P \cup \{0\}$ in a cone metric space, and proved the following common fixed point theorems of four single-valued functions in cone metric spaces:

Let (X, d) be a complete cone metric space with regular cone P such that $d(x, y) \in \text{int}P$ for all $x, y \in X$ with $x \neq y$, and let $F, G, S, T: X \rightarrow X$ be four single-valued functions with $SX \subset GX$ and $TX \subset FX$ such that for all $x, y \in X$,

$$d(Sx, Ty) \leq \psi(\max\{d(Fx, Gy), d(Fx, Sx), d(Gy, Ty)\}, \frac{1}{2}[d(Fx, Ty) + d(Gy, Sx)]).$$

If S and F are compatible, T and G are compatible, and if either F or G is continuous, then S, T, F and G have a unique common fixed point in X .

Samet B. in 2010 [39] defined generalized Meir-Keeler type function and proved the following fixed point theorem in partial metric space:

Let (X, \leq) be a partially ordered set and suppose there is a metric d on X such that (X, d) is a complete metric space. Let $F: X \times X \rightarrow X$ be a mapping satisfying the following hypotheses:

- (i) F is continuous,
 - (ii) F has the mixed strict monotone property,
 - (iii) F is a generalized Meir-Keeler type function,
 - (iv) $\exists x_0, y_0 \in X$ such that $x_0 < F(x_0, y_0)$ and $y_0 \geq F(y_0, x_0)$.
- Then, there exists $(x, y) \in X$ such that $x = F(x, y)$ and $y = F(y, x)$.

Mustafa and Sims [32] in 2005 introduced G-metric space which was the generalization of metric space. Mustafa proved some fixed point results [24-34, 35, 5, 6] in G-metric spaces. Shatanawi W. [42] also proved some fixed point results in G-metric spaces for ϕ -maps and for two weakly mappings in partially ordered G-metric spaces.

In **2011** Aydi H., Damjanovic [11] proved coupled coincidence and coupled common fixed point theorems for a mixed g -monotone mapping satisfying nonlinear contractions in partially ordered G -metric spaces. Following result was proved by them:

Let (X, \leq) be a partially ordered set and G be a G -metric on X such that (X, G) is a complete G -metric space. Suppose that there exist $\phi \in \Phi, F: X \times X \rightarrow X$ and $g: X \rightarrow X$ such that

$$(1) G(F(x, y), F(u, v), F(w, z)) \leq \phi(G(gx, gu, gw) + G(gy, gv, gz))$$

$$(2) \text{ for all } x, y, u, v, w, z \in X \text{ with } gw \leq gu \leq gx \text{ and } gy \leq gv \leq gz.$$

Suppose also that F is continuous and has the mixed g -monotone property, $F(X \times X) \subseteq g(X)$ and g is continuous and commutes with F . If there exist $x_0, y_0 \in X$ such that

$$gx_0 \leq F(x_0, y_0) \text{ and } F(x_0, y_0) \leq gy_0,$$

then F and g have a coupled coincidence point, that is, there exists $(x, y) \in X \times X$ such that

$$gx = F(x, y) \text{ and } gy = F(y, x).$$

In 2012, Aydi H., Karapinar Erdal[9], proved a general common fixed point theorem for two pairs of weakly compatible self-mappings of a partial metric space satisfying a generalized Meir-Keeler type contractive condition.

Let A, B, S and T be any self-maps of a partial metric space (X, p) satisfying the following conditions;

$$(C_1) AX \subseteq TX, BX \subseteq SX, \tag{1}$$

(C₂) Given $\epsilon > 0$, there exists a $\delta > 0$ such that for all x, y in X

$$\epsilon < M(x, y) < \epsilon + \delta \Rightarrow p(Ax, By) < \epsilon \tag{2}$$

$$\text{Where } M(x, y) = \max \left\{ p(Sx, Ty), p(Ax, Sx), p(By, Ty), \frac{1}{2}(p(Sx, By) + p(Ax, Ty)) \right\}$$

(C₃) for all $x, y \in X$ with $M > 0 \Rightarrow p(Ax, By) < M(x, y)$

$$(iii) p(Ax, By) < \max \{ a[p(Sx, Ty) + p(Ax, Sx) + p(By, Ty)], b[p(Sx, By) + p(Ax, Ty)] \}$$

$$\text{for } 0 \leq a < \frac{1}{2}, 0 \leq b < \frac{1}{2}$$

(3)

If one of AX, BX, SX and TX is a closed subset of X , then

(i) A and S have a coincidence

(ii) B and T have coincidence

Moreover, if A and S , as well as, B and T are weakly compatible, then A, B, S and T have a unique common fixed point.

In **2013** Abdeljawad T.[4] developed the fixed point theorems for α -contractive type maps to Meir-Keeler versions and generalize the results as:

Let (X, d) be an (f, g) orbitally complete metric space, where f, g are self-mappings of X . Also, let $\alpha: X \times X \rightarrow [0, \infty)$ be a mapping. Assume the following:

(1) (f, g) is α -admissible and there exists an $x_0 \in X$ such that

$$\alpha(x_0, fx_0) \geq 1 \text{ and } \alpha(x_0, gx_0) \geq 1.$$

(2) the pair (f, g) is generalized Meir-Keeler α -contractive.

Then the sequence $d_n = d(x_n, x_{n+1})$ is monotone decreasing. If, moreover, we assume that

(3) On the (f, g) -orbit of x_0 we have $\alpha(x_n, x_j) \geq 1$ for all n even and $j > n$ odd and that f and g are continuous on the (f, g) -orbit of x_0 .

Then either (1) f or g has a fixed point in the (f, g) -orbit $\{x_0\}$ of x_0 or (2) f and g have a common fixed point p and $\lim_{n \rightarrow \infty} x_n = p$. If, moreover, we assume that the following condition (H) holds: If $\{x_n\}$ is a sequence in X such that $\alpha(x_n, x_{n+1}) \geq 1$ for all n and $x_n \rightarrow x$ implies $\alpha(x_n, x) \geq 1$ for all n , then uniqueness of the fixed point is obtained.

Definition 1.1.[32] Let X be a non- empty set, and let $G: X \times X \times X \rightarrow R^+$ be a function satisfying the following axioms:

- (G₁) $G(x, y, z) = 0$ if $x = y = z$,
- (G₂) $0 < G(x, x, y)$, for all $x, y \in X$, with $x \neq y$,
- (G₃) $G(x, x, y) \leq G(x, y, z)$, for all $x, y, z \in X$, with $z \neq y$,
- (G₄) $G(x, y, z) = G(x, z, y) = G(y, z, x) = \dots$ (symmetry in all three variables),
- (G₅) $G(x, y, z) \leq G(x, a, a) + G(a, y, z)$, for all $x, y, z, a \in X$, (Rectangle inequality).

Then the function G is called a generalized metric or more specifically a G -metric on X , and the pair (X, G) is called a G -metric space.

Example 1.2. Let R be the set of all real numbers. Define $G: R \times R \times R \rightarrow R^+$ by

$$G(x, y, z) = |x - y| + |y - z| + |z - x|, \text{ for all } x, y, z \in R.$$

Then it is clear that (R, G) is a G -metric space.

Proposition 1.3.[32] Let (X, G) be a G -metric space. Then for any x, y, z , and $a \in X$, it follows that

- (1) If $G(x, y, z) = 0$, then $x = y = z$,
- (2) $G(x, y, z) \leq G(x, x, y) + G(x, x, z)$,
- (3) $G(x, y, y) \leq 2G(y, x, x)$,
- (4) $G(x, y, z) \leq G(x, a, z) + G(a, y, z)$,
- (5) $G(x, y, z) \leq (\frac{2}{3})(G(x, y, a) + G(x, a, z) + G(a, y, z))$,
- (6) $G(x, y, z) \leq (\frac{2}{3})(G(x, a, a) + G(y, a, a) + G(z, a, a))$.

Definition 1.4.[32] Let (X, G) be a G -metric space, let $\{x_n\}$ be a sequence of points of X , we say that $\{x_n\}$ is G -convergent

$$\lim_{n, m \rightarrow \infty} G(x, x_n, x_m) = 0; \text{ i.e.}$$

for any $\epsilon > 0$, there exists $n_0 \in \mathbb{N}$ such that

$$G(x, x_n, x_m) < \epsilon, \text{ for all } n, m \geq n_0.$$

We refer to x as the limit of the sequence $\{x_n\}$ and write $x_n (G) \rightarrow x$.

Proposition 1.5. [32] Let (X, G) be a G -metric space. Then the following are equivalent:

- (1) $\{x_n\}$ is G -convergent to x .
- (2) $G(x_n, x_n, x) \rightarrow 0$ as $n \rightarrow +\infty$
- (3) $G(x_n, x, x) \rightarrow 0$ as $n \rightarrow +\infty$
- (4) $G(x_n, x_m, x) \rightarrow 0$ as $m, n \rightarrow +\infty$

Definition 1.6. [32] Let (X, G) be a G -metric space. A sequence $\{x_n\}$ is called G -Cauchy if given $\epsilon > 0$, there is $n_0 \in \mathbb{N}$ such that $G(x, x_n, x_m) < \epsilon$, for all $n, m, l \geq n_0$ that is

$$\text{if } G(x_n, x_m, x_l) \rightarrow 0 \text{ as } n, m, l \rightarrow \infty.$$

Proposition 1.7. [32] In a G -metric space (X, G) , the followings are equivalent-

- (1) The sequence $\{x_n\}$ is G -Cauchy.
- (2) For every $\epsilon > 0$, $\exists N \in \mathbb{N}$ such that $G(x_n, x_m, x_m) < \epsilon$ for all $n, m \geq N$.

$\{x_n\}$ is a Cauchy sequence in the metric space (X, G) .

Definition 1.8. [32] A G -metric space (X, G) is said to be G -complete (or a complete G -metric space) if every G -Cauchy sequence in (X, G) is G -convergent in (X, G) .

Example 1.9. Let $X = \{0, 1, 2, 3, \dots\}$ and $G : X \times X \times X \rightarrow R^+$ be defined as follows:

$$G(x, y, z) = \begin{cases} x + y + z, & \text{if } x, y, z \text{ are all distinct and different from zero} \\ x + z, & \text{if } x = y \neq z \text{ and all are different from zero} \\ y + z + 1, & \text{if } x = 0, y \neq z, y \text{ and } z \text{ are different from zero} \\ y + 2, & \text{if } x = 0, y = z \neq 0 \\ z + 1, & \text{if } x = 0, y = 0, z \neq 0 \\ 0, & \text{if } x = y = z \end{cases}$$

Then (X, G) is a complete G -metric space, then G is also nonsymmetric since $G(0, 0, 1) \neq G(1, 1, 0)$.

Proposition 1.10.[32] In a G -metric space, (X, G) , the following are equivalent.

- (1) the sequence $\{x_n\}$ is G -Cauchy.
- (2) For every $\epsilon > 0$, there exists $N \in \mathbb{N}$ such that $G(x_n, x_m, x_m) < \epsilon$, for all $n, m \geq N$.
- (3) $\{x_n\}$ is a Cauchy sequence in the metric space (X, d_G) .

Definition 1.11. A G -metric space (X, G) is said to be G -complete (or a complete G -metric space) if every G -Cauchy sequence in (X, G) is G -convergent in (X, G) .

Corollary 1.12. Every G -convergent sequence in a G -metric space is G -Cauchy.

Corollary 1.13. If a G -Cauchy sequence in a G -metric space (X, G) contains a G -convergent subsequence, then the sequence itself is G -convergent.

Proposition 1.14. A G -metric space (X, G) is G -complete if and only if (X, d_G) is a complete metric space.

Corollary 1.15. If Y is a non-empty subset of a G -complete metric space (X, G) , then $(Y, G|_Y)$ is complete if and only if Y is G -closed in (X, G) .

Definition 1.16. Let (X, G) and (X', G') be G -metric spaces and let $f : (X, G) \rightarrow (X', G')$ be a function, then f is said to be G -continuous at a point $a \in X$ if given $\epsilon > 0$, there exists $\delta > 0$ such that $x, y \in X$; $G(a, x, y) < \delta$ implies $G'(f(a), f(x), f(y)) < \epsilon$.

A function f is G -continuous on X if and only if it is G -continuous at all $a \in X$.

Proposition 1.17. Let (X, G) and (X', G') be G -metric spaces and let $f : (X, G) \rightarrow (X', G')$ be G -continuous at a point $x \in X$ if and only if G -sequentially continuous at $x \in X$; that is whenever $\{x_n\}$ is G -convergent to x we have $(f(x_n))$ is G -convergent to $(f(x))$.

Definition 1.18. Let (X, d) be a metric space and T be a self map on X . Then T is called a Meir-Keeler type contraction whenever for each $\epsilon > 0$, there exists $\delta > 0$ such that

$$\epsilon < d(x, y) < \epsilon + \delta \Rightarrow d(Tx, Ty) < \epsilon$$

This contraction has been modified and extended by many authors in metric spaces and some other related structures [1-38, 40-41, 43]. Now we prove a unique fixed point result by using generalized Meir-Keeler contraction on G -metric spaces.

2.Main Results

Definition2.1.Let (X, G) be a G –Metric space and T be a self map on X . Then T is called a generalized Meir-Keeler type contraction whenever for each $\varepsilon > 0$, there exists $\delta > 0$ such that

$$\varepsilon < M(x, y, z) < \varepsilon + \delta \Rightarrow G(Tx, Ty, Tz) < \varepsilon \tag{2.1}$$

Where $M(x, y, z) = \max\{G(x, y, z), G(Tx, x, x), G(x, Ty, z), G(x, y, Tz)\}$

Remark 2.2. Note that if T is a generalized Meir-Keeler type contraction then we have

$$G(Tx, Ty, Tz) < M(x, y, z). \tag{2.2}$$

Now we come to our main results.

Proposition2.3. Let (X, G) be a G –Metric space and let $T: X \rightarrow X$ be a generalized Meir-Keeler type contraction. Then

$$\lim_{n \rightarrow \infty} G(T^{n+1}x, T^n x, T^n x) = 0 \text{ for all } x \in X.$$

Proof: Let $x_0 \in X$. we define an iterative sequence $\{x_n\}$ as

$$x_n = Tx_n = T^{n+1}x_0 \tag{2.3}$$

for all $n \geq 0$. If $x_{n_0+1} = x_{n_0}$ for some $n_0 \geq 0$, then x_{n_0} is required fixed point of T . Indeed ,

$Tx_{n_0} = x_{n_0+1} = x_{n_0}$. In this case, the proposition follows. Throughout the proof, we assume that $x_{k+1} \neq x_k$ for all $k \geq n_0$. consequently, we have $M(x_{n+1}, x_n, x_n) > 0$ for every $n \geq 0$. By remark 2.2, we get

$$\begin{aligned} G(x_{n+2}, x_{n+1}, x_{n+1}) &= G(Tx_{n+1}, Tx_n, Tx_n) < M(x_{n+1}, x_n, x_n) \\ &= \max\{G(x_{n+1}, x_n, x_n), G(Tx_{n+1}, x_{n+1}, x_{n+1}), G(x_{n+1}, Tx_n, x_n), G(x_{n+1}, x_n, Tx_n)\} \\ &= \max\{G(x_{n+1}, x_n, x_n), G(x_{n+2}, x_{n+1}, x_{n+1})\} \end{aligned}$$

Since $M(x_{n+1}, x_n, x_n) > 0$ for each n , we find that

$$G(x_{n+2}, x_{n+1}, x_{n+1}) < M(x_{n+1}, x_n, x_n) \leq \max\{G(x_{n+1}, x_n, x_n), G(x_{n+2}, x_{n+1}, x_{n+1})\}$$

By the use of remark 2.2 again, we notice that the case where

$$\max\{G(x_{n+1}, x_n, x_n), G(x_{n+2}, x_{n+1}, x_{n+1})\} = G(x_{n+2}, x_{n+1}, x_{n+1})$$

is impossible . Hence we derive that

$$G(x_{n+2}, x_{n+1}, x_{n+1}) < M(x_{n+1}, x_n, x_n) = G(x_{n+1}, x_n, x_n) \tag{2.4}$$

for every n .

Thus $\{G(x_{n+1}, x_n, x_n)\}_{n=0}^\infty$ is decreasing sequence which is bounded by 0. Hence, it converges to some $\varepsilon \in [0, \infty)$, i.e.

$$\lim_{n \rightarrow \infty} G(x_{n+1}, x_n, x_n) = \varepsilon \tag{2.5}$$

In particular, we have

$$\lim_{n \rightarrow \infty} M(x_{n+1}, x_n, x_n) = \varepsilon \tag{2.6}$$

Here $\varepsilon = \inf\{G(x_{n+1}, x_n, x_n): n \in N\}$

We claim that $\varepsilon = 0$. Suppose to the contrary that $\varepsilon > 0$. Regarding (2.6) together with the assumption that T is a generalized Meir- Keeler type contraction, for this , there exists a $\delta > 0$ and a natural no m such that

$$\varepsilon \leq M(x_{m+1}, x_m, x_m) < \varepsilon + \delta \text{ implies}$$

$$G(Tx_{m+1}, Tx_m, Tx_m) = G(x_{m+2}, x_m, x_m) < \varepsilon \tag{2.7}$$

which is a contradiction Because $\varepsilon = \inf\{G(x_{n+1}, x_n, x_n): n \in N\}$.

Theorem2.4 : Let (X, G) be a complete G –metric space and $T: X \rightarrow X$ be an orbitally continuous generalized Meir- Keeler type contraction. Then T has a unique fixed point, say $w \in X$. ver, $\lim_{n \rightarrow \infty} G(T^n x, w, w) = 0$ for all $x \in X$.

Proof: Let $x_0 \in X$. we define an iterative sequence $\{x_n\}$ as

$$x_n = Tx_n = T^{n+1}x_0 \tag{2.8}$$

for all $n \geq 0$. We claim that $\lim_{m,n \rightarrow \infty} G(x_n, x_m, x_m) = 0$. If this is not the case, then there exist a $\varepsilon > 0$ and a subsequence $\{x_{n(i)}\}$ of $\{x_n\}$ such that

$$G(x_{n(i)}, x_{n(i+1)}, x_{n(i+1)}) > 2\varepsilon \tag{2.9}$$

For the same $\varepsilon > 0$ above, $\exists \delta > 0$ such that

$$\varepsilon \leq M(x, y, z) < \varepsilon + \delta$$

which implies that $G(Tx, Ty, Tz) < \varepsilon$.

Set $r = \min\{\varepsilon, \delta\}$ and $g_n = G(x_n, x_n, x_{n+1})$ for all $n \geq 1$. By proposition 2.3, one can choose a natural no n_0 such that

$$g_n = G(x_n, x_n, x_{n+1}) < \frac{r}{4} \tag{2.10}$$

for all $n \geq n_0$. Let $n(i) > n_0$. We have $n(i) \leq n(i+1) - 1$.

$$\text{If } G(x_{n(i)}, x_{n(i+1)-1}, x_{n(i+1)-1}) \leq \varepsilon + \frac{r}{2}.$$

Then by using (G5) we derive

$$\begin{aligned} G(x_{n(i)}, x_{n(i+1)}, x_{n(i+1)}) &\leq G(x_{n(i)}, x_{n(i+1)-1}, x_{n(i+1)-1}) + G(x_{n(i+1)-1}, x_{n(i+1)}, x_{n(i+1)}) \\ &\leq \varepsilon + \frac{r}{2} + g_{n(i+1)-1} < \varepsilon + \frac{3r}{4} < 2\varepsilon \end{aligned} \tag{2.11}$$

which contradicts the assumption (2.9). Therefore, there are values of k such that

$$n(i) \leq k \leq n(i+1) \text{ and } G(x_{n(i)}, x_k, x_k) > \varepsilon + \frac{r}{2}.$$

$$\text{Now if } (x_{n(i)}, x_{n(i+1)}, x_{n(i+1)}) \geq \varepsilon + \frac{r}{2} > r + \frac{r}{2} > \frac{r}{4}.$$

This is a contradiction because of (2.10). Hence there are values of k with $n(i) \leq k \leq n(i+1)$ such that

$$G(x_{n(i)}, x_k, x_k) < \varepsilon + \frac{r}{2}.$$

We choose the smallest integer k with $k \geq n(i)$ such that $G(x_{n(i)}, x_k, x_k) \geq \varepsilon + \frac{r}{2}$. Then, we find

$$G(x_{n(i)}, x_{k-1}, x_{k-1}) < \varepsilon + \frac{r}{2}.$$

So we see that

$$G(x_{n(i)}, x_k, x_k) \leq G(x_{n(i)}, x_{k-1}, x_{k-1}) + G(x_{k-1}, x_{k-1}, x_k) < \varepsilon + \frac{r}{2} + \frac{r}{4} = \varepsilon + \frac{3r}{4} \tag{2.12}$$

Now we can choose a natural number k satisfying $n(i) \leq k \leq n(i+1)$ such that

$$\varepsilon + \frac{r}{2} \leq G(x_{n(i)}, x_k, x_k) < \varepsilon + \frac{3r}{4} \tag{2.13}$$

Therefore we obtain the inequalities

$$G(x_{n(i)}, x_k, x_k) < \varepsilon + \frac{3r}{4} < \varepsilon + r, \tag{2.14}$$

$$G(x_{n(i)}, x_{n(i+1)}, x_{n(i+1)}) = g_{n(i)} < \frac{r}{4} < \varepsilon + r, \tag{2.15}$$

$$\text{and } G(x_k, x_{k+1}, x_{k+1}) = d_k < \frac{r}{4} < \varepsilon + r \tag{2.16}$$

By (2.14) -(2.16), we get that $M(x_{n(i)}, x_k, x_k) < \varepsilon + r \leq \varepsilon + \delta$. Since T is a generalized Meir-Keeler type contraction,

$$G(x_{n(i)+1}, x_{k+1}, x_{k+1}) < \varepsilon$$

By using (G5), we obtain

$$G(T^{n(i)}x_0, T^kx_0, T^kx_0) \leq G(T^{n(i)}x_0, T^{n(i)+1}x_0, T^{n(i)+1}x_0) + G(T^{n(i)+1}x_0, T^kx_0, T^kx_0)$$

$$\leq G(T^{n(i)}x_0, T^{n(i)+1}x_0, T^{n(i)+1}x_0) + G(T^{n(i)+1}x_0, T^{k+1}x_0, T^{k+1}x_0) + G(T^{k+1}x_0, T^kx_0, T^kx_0)$$

We combine the inequality above with (2.13), (2.15) and (2.16) to conclude

$$G(x_{n(i)+1}, x_{k+1}, x_{k+1}) \geq G(x_{n(i)}, x_k, x_k) - G(x_k, x_{k+1}, x_{k+1}) > \varepsilon + \frac{r}{2} - \frac{r}{4} = \varepsilon.$$

which is a contradiction. Therefore our claim is proved. So $\{x_n\} = \{T^n x_0\}$ is a G – Cauchy sequence. Since (X, G) is G – complete, the sequence $\{x_n\}$ converges to some $w \in X$.

By proposition 2.3, we have

$$\lim_{n \rightarrow \infty} G(T^n x_0, w, w) = \lim_{n \rightarrow \infty} G(T^n x_0, T^n x_0, w) = 0.$$

Next we will prove w is a fixed point of T .

Since T is orbitally continuous and $\lim_{n \rightarrow \infty} G(T^n x_0, w, w) = 0$, we get

$$\lim_{n \rightarrow \infty} G(TT^n x_0, Tw, Tw) = \lim_{n \rightarrow \infty} G(x_{n+1}, Tw, Tw) = 0$$

where $x_{n+1} = TT^n x_0 = T^{n+1}x_0$. Thus $\{x_{n+1}\}$ converges to Tw in (X, G) . By the uniqueness of limit, we get $Tw = w$.

Finally we show that T has a unique fixed point. If there exist $u \in X$ such that $Tu = u$ and $G(u, w, w) \neq 0$, then we get $M(u, w, w) \geq G(u, w, w) > 0$. Since T is a generalized Meir-Keeler type contraction, we derive

$$\begin{aligned} 0 < G(u, w, w) &= G(Tu, Tw, Tw) < M(u, w, w) \\ &= \max\{G(u, w, w), G(Tu, u, u), G(u, Tw, w), G(u, w, Tw)\} = \max\{G(u, w, w), 0\} \\ &= G(u, w, w) \end{aligned}$$

which is a contradiction. Thus we find that $G(u, w, w) = 0$. So by (G1) we conclude that $u = w$. In lar, T has a unique fixed point.

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