

# Existence and Uniqueness of a Fuzzy Solution for Some Fuzzy Neutral Partial Differential Equation with Nonlocal Condition

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## Abstract

In this work, we establish several results about the existence of fuzzy solutions for some Fuzzy Neutral partial Differential Equation with nonlocal condition. Our approach rest on the Banach fixed-point theorem.

**Keywords** - Neutral partial Differential Equation, Fuzzy mild Solution, nonlocal condition, fuzzy semigroups of linear operators.

## I. INTRODUCTION

–In this work, we study the existence of fuzzy solutions for fuzzy neutral partial differential equations with nonlocal conditions of the following from:

$$\begin{cases} \frac{d}{dt} [x(t) \ominus F(t, x(h_1(t)))] = A [x(t) \ominus F(t, x(h_1(t)))] \oplus G(t, x(h_2(t))), & 0 \leq t \leq a, \\ x(0) \oplus g(x) = x_0 \in E^n \end{cases} \quad (1)$$

Where  $A: E^n \rightarrow E^n$  is fuzzy operator, is the infinitesimal generator of an  $C_0$ -semigroup on  $E^n$  and  $E^n$  is the set of all upper semi continuous, convex, normal fuzzy numbers with bounded  $\alpha$ -level intervals, called spaces of fuzzy numbers, or more general with values in  $E^n$ , where  $(E^n, \oplus, \odot, D)$  represents any from the fuzzy number type spaces introduced by section 2, and

$$F, G : [0, a] \times E^n \rightarrow E^n, g : C([0, a]; E^n) \rightarrow E^n \text{ and } h_i \in C([0, a]; [0, a]), i = 1, 2.$$

The very recent paper [10] is concerned with equation 1 in Banach space  $X$ , the theory of neutral differential equations has many applications, for the reader, we refer to [1,3]. Differential equations with nonlocal conditions have been studied extensively in the literature. The importance of nonlocal conditions in different fields has been discussed [4,5,9] and the references therein. In the past several years theorems about existence, uniqueness and stability of differential equations with nonlocal conditions have been studied by Byszewski and Lakshmikantham [6], Balachandran and Chandrasekaran [2], Lin and Liu [14] and Ntouyas and Tsamatos [15]. but it is known that the classical of neutral differential equations whose solution are real valued functions (or Banach space valued function, respectively) often represent an idealization of real situations, where imprecision may in fact play a significant role.

Generally, several systems are mostly related to uncertainty and inexactness. The problem of inexactness is considered in general exact science, and that of uncertainty is considered as vague or fuzzy and accident. Ding and Kandel [7,16-19] analyzed a way to combine differential equations with fuzzy sets to form a fuzzy logic system called a fuzzy dynamical system, which can be regarded to form a fuzzy neutral functional differential equation.

Note that with respect to Banach spaces, the fuzzy number type spaces  $(E^n, \oplus, \odot, D)$  represent more general structures, in the sense that although the metric has similar properties with a metric derived from a norm of Banach space, however  $(E^n, \oplus, \odot, D)$  with respect to the addition  $\oplus$  is not a group and with respect to the scalar multiplication is not linear space.

The organization of this work is as follows: in Section 2, we call some fundamental results on fuzzy numbers. In Section 3 we study the existence of fuzzy mild solutions.

## II. PRELIMINARIES

In this section, we introduce notations, definitions, and preliminary facts which are used throughout this paper.

Let  $T = [c, d] \subset \mathbb{R}$  be a compact interval and denote  $E^n = \{u \mid u : \mathbb{R}^n \rightarrow [0,1] \text{ satisfies (1)-(4) below} \}$  where

1.  $u$  is normal i.e, there exists an  $x_0 \in \mathbb{R}^n$  such that  $u(x_0) = 1$
2.  $u$  is fuzzy convex i.e for  $x, y \in \mathbb{R}^n$  and  $0 < \lambda \leq 1$ ,  $u(\lambda x + (1 - \lambda)y) \geq \min\{u(x), u(y)\}$
3.  $u$  is upper semi-continuous on  $\mathbb{R}$ .
4.  $[u]^0$  is a compact set.

For  $0 < \alpha \leq 1$  denote  $\{[u]^\alpha = x \in \mathbb{R}^n \mid u(x) \geq \alpha\}$ , then from (1) to (4), it follows that the  $\alpha$  – level sets  $[u]^\alpha$  for all  $0 \leq \alpha \leq 1$  is a closed bounded interval which we denote by  $[u]^\alpha = [u_1(\alpha), u_2(\alpha)]$ ,

If  $g: \mathbb{R}^n \times \mathbb{R}^n \rightarrow \mathbb{R}^n$  is any function, then, according to Zadeh's extension principle, we can extend  $g: E^n \times E^n \rightarrow E^n$  by the function defined by  $g(u, v)(z) = \sup_{\{z=g(u,v)\}} \min\{u(x), v(y)\}$

It is well known that  $[g(u, v)]^\alpha = g([u]^\alpha, [v]^\alpha)$  for all  $u, v \in E^n, 0 \leq \alpha \leq 1$  and a continuous function  $g$ .

Especially for addition and scalar multiplication, we have  $[u \oplus v]^\alpha = [u]^\alpha + [v]^\alpha$ ,  $[k \odot u]^\alpha = k[u]^\alpha$  where  $u, v \in E^n, k \in \mathbb{R}, 0 \leq \alpha \leq 1$ . We say that there exists  $a \ominus b$ , if there exists  $c \in E^n$  such that  $a = b \oplus c$  and we denote  $c = a \ominus b$  [8].

The distance between  $A$  and  $B$  is defined by the Hausdorff metric

$$d_H(A, B) = \max\{\sup_{a \in A} \inf_{b \in B} \|a - b\|, \sup_{b \in B} \inf_{a \in A} \|a - b\|\}$$

where  $\|\cdot\|$  denotes the usual Euclidean norm in  $\mathbb{R}^n$ .

We define  $D: E^n \times E^n \rightarrow \mathbb{R}^+ \cup \{0\}$  by the equation  $D(u, v) = \sup_{\alpha \in [0,1]} d_H([u]^\alpha, [v]^\alpha)$  for all  $u, v \in E^n$  where  $d_H$  is the Hausdorff metric.

**proposition1:** Let  $u, v, w$  and  $e \in E^n$

- (i)  $D(u \oplus w, v \oplus w) = D(u, v)$
- (ii)  $D(k \odot u, k \odot v) = |k|D(u, v), \forall k \in \mathbb{R}$
- (iii)  $D(u \oplus v, w \oplus e) \leq D(u, w) + D(v, e)$
- (iv) If  $u \ominus v$  and  $w \ominus e$  exist, then  $D(u \ominus v, w \ominus e) \leq D(u, v) + D(w, e)$ .
- (v)  $(E^n, D)$  is a complete metric space

Now, according to [11], with the aid of  $(E^n, \oplus, \odot, D)$  we can define new spaces as follows.  $C([a, b], E^n)$  the space of all continuous functions, endowed with the metric

$H(u, v) = \sup_{t \in T} D(u(t), v(t))$ . and the natural operations induced by those in  $E^n$ ,  $(C([a, b], E^n), H)$  is a complete metric space.

**Theoreme1 :** [10]

1. If we denote  $\tilde{0} = \chi_{\{0\}}$  then  $\tilde{0} \in E^n$  is neutral element with respect to  $\oplus$  i.e  $u \oplus \tilde{0} = \tilde{0} \oplus u = u$  for all  $u \in E^n$

2. for any  $\lambda, \mu \in \mathbb{R}$  with  $\lambda, \mu \geq 0$  or  $\lambda, \mu \leq 0$  and any  $u, v \in E^n$  we have  $(\lambda + \mu) \odot u = \lambda \odot u \oplus \mu \odot u$  for general  $\lambda, \mu \in \mathbb{R}$  the above property does not hold  $\lambda \odot (u \oplus v) = \lambda \odot u \oplus \lambda \odot v, \lambda \odot (\mu \odot u) = (\lambda \cdot \mu) \odot u$

3. If we denote  $\|u\|_{E^n} = D(u, \tilde{0}), \forall u \in E^n$  then  $\|\cdot\|_{E^n}$  has the properties of a usual norm or  $E^n$  i.e  $\|u\|_{E^n} = 0$  if  $u = \tilde{0}$ ,  $\|\lambda \odot u\|_{E^n} = |\lambda| \cdot \|u\|_{E^n}$  and  $\|u \odot v\|_{E^n} \leq \|u\|_{E^n} + \|v\|_{E^n}$  and  $|\|u\|_{E^n} - \|v\|_{E^n}| \leq D(u, v)$ .

**Remark1 :** from theorem 1, (2) we can deduce that for any  $\lambda, \mu \in \mathbb{R}$  with  $\lambda > \mu > 0$  and any  $u \in E^n$   $\lambda \odot u \ominus \mu \odot u$  exists and  $\lambda \odot u \ominus \mu \odot u = (\lambda - \mu) \odot u$

The following definitions and theorems are given in [12]

**Definition1:** A mapping  $F: T \times E^n \rightarrow E^n$  is strongly measurable if, for all  $\alpha \in [0,1]$  the multi-valued mapping  $F_\alpha: T \rightarrow P_K(\mathbb{R}^n)$  defined by  $F_\alpha(t) = [F(t)]^\alpha$  is Lebesgue measurable when  $P_K(\mathbb{R}^n)$  is endowed with the topology generated by the Hausdorff metric  $d_H$  and  $T$  is a subinterval of real number  $\mathbb{R}$  where  $P_K(\mathbb{R}^n)$  denote the family of all nonempty compact convex subsets of  $\mathbb{R}^n$

**Definition2:** A mapping is called levelwise continuous at  $t_0 \in T$  if the set-valued mapping  $F_\alpha(t) = [F(t)]^\alpha$  is continuous at  $t = t_0$  with respect to the Hausdorff metric  $d_H$  for all  $\alpha \in [0,1]$ .

A mapping  $F: T \rightarrow E^n$  is called integrably bounded if there exists an integrable function  $h$  such that  $\|x\| \leq h(t)$  for all  $x \in F_0(t)$

**Definition3:** Let  $F: T \rightarrow E^n$ . Then the integral of  $F$  over  $T$ , denoted by  $\int_T F(t)dt$  or  $\int_c^d F(t)dt$  is defined

$[\int_T F(t) dt]^\alpha = \int_T F_\alpha(t) dt = \left\{ \int_T f(t) dt \mid f: T \rightarrow \mathbb{R}^n \text{ is a measurable selection for } F_\alpha(t) \right\}$  for all  $0 < \alpha \leq 1$ .

Also, a strongly measurable and integrably bounded mapping  $F: T \times E^n \rightarrow E^n$  is said to be integrable over T if  $\int_T f(t) dt \in E^n$

**Theorem2:** If  $F: T \rightarrow E^n$  is strangely measurable and integrably bounded, then F is integrable. It is known that

$$[\int_T F(t) dt]^0 = \int_T F_0(t) dt$$

**Theorem3:** Let  $F, G: T \rightarrow E^n$  be integrable and  $\lambda \in \mathbb{R}$ . Then

(i)  $\int_T (F(t) + G(t)) dt = \int_T F(t) dt + \int_T G(t) dt$

(ii)  $\int_T \lambda F(t) dt = \lambda \int_T F(t) dt$

(iii)  $D(F,G)$  is integrable,

(iv)  $D(\int_T F(t) dt, \int_T G(t) dt) \leq \int_T D(F,G)(t) dt$

**Definition4:** A mapping  $F: T \rightarrow E^n$  is Hukuhara differentiable at  $t_0 \in T$  if there exists a  $F'(t_0) \rightarrow E^n$  such that the limits

$$\lim_{h \rightarrow 0^+} \frac{F(x_0+h) \ominus F(x_0)}{h} = \lim_{h \rightarrow 0^+} \frac{F(x_0) \ominus F(x_0-h)}{h}$$

exist and are equal to  $F'(t_0)$  ( $F'(t_0)$  is called the Hukuhara derivative of F at  $t_0 \in T$ . Here the limit is taken in the metric space  $(E^n, D)$ . At the end points of T, we consider only the one-site derivatives.

If  $F: T \rightarrow E^n$  is differentiable at  $t_0 \in T$ , then we say that  $F'(t_0)$  is the fuzzy derivative of  $F(t)$  at point  $t_0$ . For the concepts of fuzzy measurability and fuzzy continuity we refer to [13].

**Theorem4:** Let  $F: T \rightarrow E^1$  be differentiable with level sets  $F_\alpha(t) = [f_1^\alpha, f_2^\alpha]$ . Then  $f_1^\alpha, f_2^\alpha: [0,1] \rightarrow \mathbb{R}^1$  are differentiable and  $[F'(t)]^\alpha = [f_1^{\alpha'}, f_2^{\alpha'}]$  for all  $0 < \alpha \leq 1$ .

**Definition5:** A mapping  $F: T \times E^n \rightarrow E^n$  is called levelwise continuous provided that for any fixed  $\alpha \in [0,1]$  and arbitrary  $\varepsilon > 0$  there exists a  $\delta(\varepsilon, \alpha) > 0$  such that  $d_H([f(t, x)]^\alpha, [f(t_0, x_0)]^\alpha) < \varepsilon$  whenever  $|t - t_0| < \delta(\varepsilon, \alpha)$  and  $d_H([x]^\alpha, [x_0]^\alpha) < \delta(\varepsilon, \alpha)$  for all  $t \in T, x \in E^n$ .

Now, let us recall some elements of operator theory and semigroup of operators on  $E^n$  in [11]

**Definition6:**  $A: E^n \rightarrow E^n$  is called linear operator if

$$A(\lambda \odot x \oplus \mu \odot y) = \lambda \odot A(x) \oplus \mu \odot A(y)$$

for all  $\lambda, \mu \in \mathbb{R}$  with  $\lambda > \mu > 0$  and all  $x, y \in E^n$

**Definition7:** A family of functions  $(T(t))_{t \geq 0}$  of continuous linear operators on  $E^n$  is called fuzzy  $C_0$ -semigroup if

1. For all  $x \in E^n$  the mapping  $T(t)(x): \mathbb{R}_+ \rightarrow E^n$  is continuous with respect to  $t \geq 0$
2.  $T(t+s) = T(t)[T(s)]$  for all  $t, s \in \mathbb{R}_+$
3.  $T(0) = I$  where  $I$  is the identity operator on  $E^n$ .

**Definition8:** if  $A: E^n \rightarrow E^n$  is a linear operator, then it is called generator of the  $C_0$ -semigroup if for all  $x \in E^n$ , there exists  $T(t)(x) \ominus x$  and  $\lim_{t \rightarrow 0^+} \frac{1}{t} \odot [T(t)(x) \ominus x] = A(x)$

**Theorem5:** [11] if  $A: E^n \rightarrow E^n$  is linear and continuous on  $\tilde{0}$  then for all  $x \in E^n$  we have

$$\|A(x)\|_{E^n} \leq \|A\|_{E^n} \|x\|_{E^n}$$

where  $\|A\|_{E^n} = \sup\{\|A(x)\|_{E^n}, x \in E^n, \|x\|_{E^n} \leq 1\} \in \mathbb{R}, \|A(x)\|_{E^n} = D(A(x), \tilde{0})$

if A is linear on  $E^n$  and continuous on  $\tilde{0}$ , then it does not follow the continuity of A on the whole space  $E^n$ .

$T(t)$  is generalized differentiable with respect to  $t \in \mathbb{R}_+$ , with the derivative equal to  $A[T(t)]$ . More exactly, it is Hukuhara differentiable with respect to  $t \in \mathbb{R}_+$  i.e

$$\lim_{h \rightarrow 0} \frac{1}{h} \odot [T(t+h)(x) \ominus T(t)x] = A[T(t)(x)]$$

$$\lim_{h \rightarrow 0} \frac{1}{h} \odot [T(t)(x) \ominus T(t-h)x] = A[T(t)(x)]$$

Here, the limit is taken in the metric space  $(E^n, D)$ .

**Remark2 :** By the linearity of  $T(t)$  it easily follows that

$$T(t)[x(t) \ominus y(t)] = T(t)[x(t)] \ominus T(t)[y(t)] \quad t \geq 0$$

### III. FUZZY NEUTRAL FUNCTIONAL DIFFERENTIAL EQUATIONS WITH NONLOCAL CONDITIONS

the Throughout the whole of this work, we assume that

(H<sub>0</sub>) The linear and continuous operator A generates a C<sub>0</sub>-semigroup (T(t))<sub>t≥0</sub> on E<sup>n</sup> such that || T(t) || |E<sup>n</sup> ≤ M for all t ≥ 0 with M > 0.

#### III.1 existence of mild solutions

Let C([0, a], E<sup>n</sup>) be the space of continuous functions. We assume that: (H<sub>1</sub>), F, G: [0, a] × E<sup>n</sup> → E<sup>n</sup> are levelwise continuous and lipschitzians with respect to the second argument there existe constants L<sub>1</sub> > 0 and L<sub>2</sub> > 0 such that

$$d_H([F(t, x)]^\alpha, [F(t, y)]^\alpha) \leq L_1 d_H([x]^\alpha, [y]^\alpha) \quad (2)$$

And

$$d_H([G(t, x)]^\alpha, [G(t, y)]^\alpha) \leq L_2 d_H([x]^\alpha, [y]^\alpha) \quad (3)$$

for any pairs (t, x), (t, y) ∈ [0, a] × E<sup>n</sup>.

(H<sub>2</sub>), g: C([0, a], E<sup>n</sup>) → E<sup>n</sup> is lipschitz continuous : there existe constants L<sub>3</sub> > 0 such that

$$d_H([g(u_1)]^\alpha, [g(u_2)]^\alpha) \leq L_3 d_H([u_1]^\alpha, [u_2]^\alpha) \quad (4)$$

for u<sub>1</sub>, u<sub>2</sub> ∈ C([0, a], E<sup>n</sup>).

(H<sub>3</sub>) h<sub>i</sub>: C([0, a], [0, a]), i = 1,2

**Definition9:** A continuous function x(·): [0, a] → E<sup>n</sup> is said to be a mild solution of equation (1) if

$$x(t) = T(t) \left[ x_0 \ominus g(x) \ominus F(0, x(h_1(0))) \right] \oplus F(t, x(h_{\{1\}}(t))) \oplus \int_0^t T(t-s) G(t, x(h_{\{2\}}(s))) ds \quad (5)$$

for all t ∈ [0, a].

everywhere in this section when we refer to the equation (1) we mean that there + is replaced by the fuzzy addition ⊕ and - is replaced by the fuzzy subtraction ⊖.

**Theoreme6:** Assume that assumptions (H<sub>0</sub> – H<sub>3</sub>) hold. Then there existe a unique mild solution x = x(t) of Eq (1) provided that

$$L_0 = ML_3 + (M + 1)L_1 + a ML_3 < 1$$

#### Proof:

Consider the operator N defined on C([0, a], E<sup>n</sup>) by

$$Nx(t) = T(t) \left[ x_0 \ominus g(x) \ominus F(0, x(h_1(0))) \right] \oplus F(t, x(h_{\{1\}}(t))) \oplus \int_0^t T(t-s) G(t, x(h_{\{2\}}(s))) ds$$

for all 0 ≤ t ≤ a

we shall that is N a contraction operator. Indeed, consider

x, y ∈ C([0, a], E<sup>n</sup>) and α ∈ (0,1] then

$$\begin{aligned} & d_H([(Nx)(t)]^\alpha, [(Ny)(t)]^\alpha) = \\ & d_H([T(t) \left[ x_0 \ominus g(x) \ominus F(0, x(h_1(0))) \right] \oplus F(t, x(h_{\{1\}}(t))) \oplus \int_0^t T(t-s) G(t, x(h_{\{2\}}(s))) ds ]^\alpha, \\ & [T(t) \left[ x_0 \ominus g(y) \ominus F(0, y(h_1(0))) \right] \oplus F(t, y(h_{\{1\}}(t))) \oplus \int_0^t T(t-s) G(t, y(h_{\{2\}}(s))) ds ]^\alpha) \\ & \leq d_H([ [T(t)x_0]^\alpha - [T(t)g(x)]^\alpha - [T(t)F(0, x(h_1(0)))]^\alpha ] + [F(t, x(h_{\{1\}}(t)))]^\alpha \\ & \quad + [ \int_0^t T(t-s) G(t, x(h_{\{2\}}(s))) ds ]^\alpha, [T(t)x_0]^\alpha - [T(t)g(y)]^\alpha \\ & \quad + [T(t)F(0, y(h_1(0)))]^\alpha + [F(t, y(h_{\{1\}}(t)))]^\alpha + [ \int_0^t T(t-s) G(t, y(h_{\{2\}}(s))) ds ]^\alpha) \\ & \leq d_H([T(t)g(x)]^\alpha, [T(t)g(y)]^\alpha) + d_H([T(t)F(0, x(h_1(0)))]^\alpha, [T(t)F(0, y(h_1(0)))]^\alpha) \end{aligned}$$

$$\begin{aligned}
 & +d_H([F(t, x(h_{\{1\}}(t)))]^\alpha, [F(t, y(h_{\{1\}}(t)))]^\alpha) \\
 & \quad + d_H([\int_0^t T(t-s)G(t, x(h_{\{2\}}(s))) ds ]^\alpha, [\int_0^t T(t-s)G(t, y(h_{\{2\}}(s))) ds ]^\alpha) \\
 & = d_H([T(t)g(x)]^\alpha, [T(t)g(y)]^\alpha) + d_H([T(t)F(0, x(h_1(0)))]^\alpha, [T(t)F(0, y(h_1(0)))]^\alpha) \\
 & +d_H([F(t, x(h_{\{1\}}(t)))]^\alpha, [F(t, y(h_{\{1\}}(t)))]^\alpha) \\
 & \quad + d_H([\int_0^t T(t-s)G(s, x(h_{\{2\}}(s))) ]^\alpha ds, [\int_0^t T(t-s)G(s, y(h_{\{2\}}(s))) ]^\alpha ds) \\
 & \leq d_H([T(t)g(x)]^\alpha, [T(t)g(y)]^\alpha) + d_H([T(t)F(0, x(h_1(0)))]^\alpha, [T(t)F(0, y(h_1(0)))]^\alpha) \\
 & \quad +d_H([F(t, x(h_{\{1\}}(t)))]^\alpha, [F(t, y(h_{\{1\}}(t)))]^\alpha) \\
 & \quad + \int_0^t (d_H([T(t-s)G(s, x(h_{\{2\}}(s)))]^\alpha, [T(t-s)G(s, y(h_{\{2\}}(s)))]^\alpha) ds \\
 & \quad \leq \max\{|T_1^\alpha(t)(g_1^\alpha(x) - g_1^\alpha(y))|, T_2^\alpha(t)(g_2^\alpha(x) - g_2^\alpha(y))|\} \\
 & + \max\{|T_1^\alpha(t)(F_1^\alpha(0, x(h_1(0))) - F_1^\alpha(0, y(h_1(0))))|, T_2^\alpha(t)(F_2^\alpha(0, x(h_1(0))) - F_2^\alpha(0, y(h_1(0))))|\} \\
 & \quad + \max\{|(F_1^\alpha(t, x(h_1(t))) - F_1^\alpha(t, y(h_1(t))))|, (F_2^\alpha(t, x(h_1(t))) - F_2^\alpha(t, y(h_1(t))))|\} \\
 & + \int_0^t \max\{|T_1^\alpha(t-s)(G_1^\alpha(t, x(h_{\{2\}}(s))) - G_1^\alpha(t, y(h_{\{2\}}(s))))|, T_2^\alpha(t-s)(G_2^\alpha(t, x(h_{\{2\}}(s))) \\
 & \quad - G_2^\alpha(t, y(h_{\{2\}}(s))))|\} ds \\
 & \quad \leq \max\{T_1^\alpha(t), T_2^\alpha(t)\} \max\{|g_1^\alpha(x) - g_1^\alpha(y)|, |g_2^\alpha(x) - g_2^\alpha(y)|\} \\
 & + \max\{T_1^\alpha(t), T_2^\alpha(t)\} \max\{|F_1^\alpha(0, x(h_1(0))) - F_1^\alpha(0, y(h_1(0)))|, |F_2^\alpha(0, x(h_1(0))) - F_2^\alpha(0, y(h_1(0)))|\} \\
 & \quad + \max\{|F_1^\alpha(t, x(h_1(t))) - F_1^\alpha(t, y(h_1(t)))|, |F_2^\alpha(t, x(h_1(t))) - F_2^\alpha(t, y(h_1(t)))|\} \\
 & + \int_0^t \max\{|T_1^\alpha(t-s), T_2^\alpha(t-s)\} \max\{|G_1^\alpha(t, x(h_{\{2\}}(s))) - G_1^\alpha(t, y(h_{\{2\}}(s)))|, |G_2^\alpha(t, x(h_{\{2\}}(s))) \\
 & \quad - G_2^\alpha(t, y(h_{\{2\}}(s)))|\} ds \\
 & \leq d_H([T(t)]^\alpha, 0)d_H([g(x)]^\alpha, [g(y)]^\alpha) + d_H([T(t)]^\alpha, 0)d_H([F(0, x(h_1(0)))]^\alpha, [F(0, y(h_1(0)))]^\alpha) \\
 & \quad + d_H([F(t, x(h_{\{1\}}(t)))]^\alpha, [F(t, y(h_{\{1\}}(t)))]^\alpha) \\
 & \quad + \int_0^t d_H([T(t-s)]^\alpha, 0) d_H([G(s, x(h_{\{2\}}(s)))]^\alpha, [G(s, y(h_{\{2\}}(s)))]^\alpha) ds \\
 & \leq L_3 d_H([T(t)]^\alpha, 0)d_H([x]^\alpha, [y]^\alpha) + L_1 d_H([T(t)]^\alpha, 0)d_H([x]^\alpha, [y]^\alpha) + L_1 d_H([x]^\alpha, [y]^\alpha) \\
 & +L_2 \int_0^t d_H([T(t-s)]^\alpha, 0)d_H([x]^\alpha, [y]^\alpha) ds \\
 \\
 & D((Nx)(t), (Ny)(t)) \leq L_3 D(T(t), \tilde{0})D(x(t), y(t)) + L_1 D(T(t), \tilde{0})D(x(t), y(t)) + L_1 D(x(t), y(t)) \\
 & +L_2 \int_0^t D(T(t-s), \tilde{0})D(x(s), y(s)) ds \\
 & \leq L_3 \|T(t)\|_{E^n} D(x(t), y(t)) + L_1 \|T(t)\|_{E^n} D(x(t), y(t)) + L_1 D(x(t), y(t)) \\
 & \quad +L_2 \int_0^t \|T(t-s)\|_{E^n} D(x(s), y(s)) ds
 \end{aligned}$$

Then we obtain

$$\begin{aligned}
 D((Nx)(t), (Ny)(t)) & \leq ML_3 D(x(t), y(t)) + (M + 1)L_1 D(x(t), y(t)) + ML_2 \int_0^t D(x(s), y(s)) ds \\
 H(Nx, Ny) & \leq \sup_{0 \leq t \leq a} \{ML_3 D(x(t), y(t)) + (M + 1)L_1 D(x(t), y(t)) + ML_2 \int_0^t D(x(s), y(s)) ds \} \\
 & \leq (ML_3 + (M + 1)L_1 + aML_2)H(x, y)
 \end{aligned}$$

Since  $ML_3 + (M + 1)L_1 + aML_2 < 1$ ,  $N$  is a strict contraction mapping. By Banach fixed point theorem we conclude that  $N$  has a unique fixed point  $x = Nx \in C([0, a], E^n)$ .

**Theorem7:** Suppose that  $F, G, g$  and  $h_i, i = 1,2$  are the same as in theorem6. let  $x(\cdot, x_0), y(\cdot, y_0)$  be a mild solution of Eq (1) corresponding to  $x_0, y_0$  respectively. Then there exists a constant  $\xi > 0$  such that

$$H(x(\cdot, x_0), y(\cdot, y_0)) \leq \xi D(x_0, y_0) \text{ for any } x_0, y_0 \in E^n \text{ and } \xi = M/(1 - L_0)$$

**Proof :** Let  $x(t, x_0), y(t, y_0)$  be a mild solution to Eq.(1) corresponding to  $x_0, y_0$  respectively. Then  $d_H([x(t, x_0)]^\alpha, [y(t, x_0)]^\alpha) =$

$$\begin{aligned} & d_H([T(t)[x_0 \ominus g(x) \ominus F(0, x(h_1(0)))] \oplus F(t, x(h_{\{1\}}(t))) \oplus \int_0^t T(t-s)G(t, x(h_{\{2\}}(s))) ds]^\alpha, \\ & [T(t)[x_0 \ominus g(y) \ominus F(0, y(h_1(0)))] \oplus F(t, y(h_{\{1\}}(t))) \oplus \int_0^t T(t-s)G(t, y(h_{\{2\}}(s))) ds]^\alpha) \\ & \leq d_H([T(t)]^\alpha, 0)d_H([x_0]^\alpha, [y_0]^\alpha) + L_3 d_H([T(t)]^\alpha, 0)d_H([x]^\alpha, [y]^\alpha) + L_1 d_H([T(t)]^\alpha, 0)d_H([x]^\alpha, [y]^\alpha) + \\ & L_1 d_H([x]^\alpha, [y]^\alpha) + L_2 \int_0^t d_H([T(t-s)]^\alpha, 0)d_H([x]^\alpha, [y]^\alpha) ds \end{aligned}$$

Then we obtain

$$\begin{aligned} D(x(t, x_0), y(t, x_0)) \leq & \| \| T(t) \| \|_{E^n} D(x_0, y_0) + L_3 \| \| T(t) \| \|_{E^n} D(x(t), y(t)) + (M + 1) L_1 \| \| T(t) \| \|_{E^n} \\ & D(x(t), y(t)) + L_2 \| \| T(t) \| \|_{E^n} \int_0^t D(x(s), y(s)) ds \end{aligned}$$

Thus,

$$\begin{aligned} & \leq MD(x_0, y_0) + ML_3 D(x(t), y(t)) + (M + 1)L_1 D(x(t), y(t)) + ML_2 \int_0^t D(x(s), y(s)) ds \\ & H(x(\cdot, x_0), y(\cdot, y_0)) \leq MD(x_0, y_0) + (ML_3 + (M + 1)L_1 + aML_2)H(x(\cdot, x_0), y(\cdot, y_0)) \end{aligned}$$

So

$$H(x(\cdot, x_0), y(\cdot, y_0)) \leq \frac{M}{1 - (ML_3 + (M + 1)L_1 + aML_2)} D(x_0, y_0)$$

Were  $l_0 = ML_3 + (M + 1)L_1 + aML_2$

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