Original Article

Existence and Uniqueness Solutions of System Caputo-Type Fractional-Order Boundary Value Problems using Monotone Iterative Method

Audubmbar Kumar Mule¹, Sidheshwar S. Bellale²

¹Department of Mathematics, Dayanand Science College, Latur, India. ²Mathematics Research center, Dayanand Science College, Latur, India.

¹Corresponding Author: audumbar21@gmail.com

Received: 21 April 2023 Revised: 28 May 2023 Accepted: 13 June 2023 Published: 27 June 2023

Abstract - In this paper, we investigate the existence and uniqueness solutions of nonlinear boundary value problems for a system of Caputo-type nonlinear fractional differential equations of the form:

$$\begin{cases} {}^{c}D_{a^{+}}^{q;\psi}u_{i}(t) = F_{i}(t, u_{1}(t), u_{2}(t)) & t \in J = [a, b], \\ \phi(v_{i}(a), v_{i}(b)) = 0. \end{cases}$$

To develop a monotone iterative technique by introducing upper and lower solutions to Caputo-type fractional differential equations with nonlinear boundary conditions. The monotone method yields monotone sequences which converge uniformly and monotonically to extremal solutions.

Keywords - ψ-Caputo fractional derivative, Upper and lower solutions, Monotone iterative method.

Mathematics Subject Classification(2020) - 26A33, 26A48, 34A08.

1. Introduction

Fractional differential equations or fractional differential systems have numerous applications in diverse and widespread fields of science and technology [4, 10, 22]. The study of fractional calculus and its applications see more details [12, 13, 20]. The approach to obtain the existence and uniqueness of solutions for the nonlinear fractional differential systems, in general, has been through the fixed point theorem method [3, 6, 9, 16, 23, 24, 25, 26]. In this paper investigates the existence and uniqueness using the method of lower and upper solutions combined with the monotone iterative technique [5, 8, 24, 28, 29].

The monotone method is useful for nonlinear equations and systems because it reduces the problem to sequences of linear equations. Specifically, if the nonlinear system is unwieldy and too difficult to solve explicitly, then the monotone method may be beneficial. If one can find upper and lower solutions to the original system that are less unwieldy and satisfy the particular requirements, then the monotone method implements a technique for constricting sequences from these upper and lower solutions. These sequences are solutions to linear equations and converge uniformly and monotonically to maximal and minimal solutions [11, 12, 14, 16, 17, 18, 19, 25].

Motivated by the work see [7], we determine the existence criteria of extremal solution for following system ψ -Caputo type fractional differential equations in a Caputo sense with nonlinear boundary conditions

$$\begin{cases} {}^{c}D_{a^{+}}^{q;\psi}u_{i}(t) = F_{i}(t, u_{1}(t), u_{2}(t)) & t \in J = [a, b], \\ \phi(v_{i}(a), v_{i}(b)) = 0. \end{cases}$$

The rest of the paper is arranged in the following way.



In section 2, definitions and basic results are discussed that play a vital role in the main results. These results are useful in main results proving that the sequences developed in the generalized monotone method converge to coupled minimal and maximal solutions of the non-linear system of the fractional differential equation. Finally, under the uniqueness assumption, we prove that there exists a unique solution to the non-linear system of ψ -Caputo fractional differential equation.

2. Definitions and Basic Results

In this section, we recall some known definitions and known results which are useful to develop our main result.

Definition 2.1 [4, 1] The ψ -Riemann-Liouville fractional integral of order q is defined by

$$I_{a+}^{q;\psi}u(t) = \frac{1}{\Gamma(q)} \int_0^t \psi'\left(\psi(t) - \psi(s)\right)^{q-1} u(s) ds, t > a.$$

Definition 2.2 [1] Let $\psi, u \in C^n(J, \mathbb{R})$. The ψ -Riemann-Liouville derivative of the order of a function u with $(n-1 < q \le n)$ can be written as

$$D_{a+}^{q;\psi}u(t) = \left(\frac{D_t}{\psi'(t)}\right)^n I_{a+}^{n-q;\psi}u(t)$$

$$= \frac{1}{\Gamma(n-q)} \left(\frac{D_t}{\psi'(t)}\right)^n \int_0^t \psi'\left(\psi(t) - \psi(s)\right)^{n-q-1} u(s) ds,$$

where $n = [q] + 1 (n \in \mathbb{N})$, and $D_t = \frac{d}{dt}$.

Definition 2.2 [1] Let $\psi, u \in C^n(J, \mathbb{R})$. The ψ -Caputo derivative of the order of a function u with $(n-1 < q \le n)$ can be written as

$$D_{a+}^{q;\psi}u(t) = I_{a+}^{n-q;\psi}u_{\psi}^{[n]}(t)$$

where $u_{\psi}^{[n]}(t) = \left(\frac{D_t}{\psi'(t)}\right)^n u(t), n = [q] + 1$ for $q \notin \mathbb{N}$ and n = q for $q \in \mathbb{N}$.

One has

$$^{c}D_{a^{+}}^{q;\psi}u(t) = \begin{cases} \int_{0}^{t} \psi'\left(\psi(t) - \psi(s)\right)^{n-q-1} u_{\psi}^{[n]}(s)ds, & if q \notin \mathbb{N}, \\ u_{\psi}^{[n]}(t), & if q \in \mathbb{N} \end{cases}$$

Definition 2.3 [2] One and two-parameter Mittag-Leffler function is defined as

$$E_q(t) = \sum_{k=0}^{\infty} \frac{(t)^k}{\Gamma(qk+1)} \quad t \in \mathbb{R}, q > 0$$

$$E_{q,\beta}(t) = \sum_{k=0}^{\infty} \frac{(t)^k}{\Gamma(qk+\beta)} \quad q,\beta > 0, t \in \mathbb{R}$$

Lemma 2.1 [1] Let p,q > 0, and $u \in C(J,\mathbb{R})$, for every $t \in J$ i. ${}^cD^{q;\psi}_{a^+}I^{q;\psi}_{a^+}u(t) = u(t)$, ii. $I^{q;\psi}_{a^+}D^{q;\psi}_{a^+}u(t) = u(t) - u(a), 0 < q \le 1$.

$$\begin{split} &\text{iii. } I_{a^+}^{q;\psi} \big(\psi(t) - \psi(a) \big)^{p-1} = \frac{\Gamma(p)}{\Gamma(p-q)} \big(\psi(t) - \psi(a) \big)^{p+q-1}, \\ &\text{iv. } {^cD}_{a^+}^{q;\psi} \big(\psi(t) - \psi(a) \big)^{p-1} = \frac{\Gamma(p)}{\Gamma(p-q)} \big(\psi(t) - \psi(a) \big)^{p-q-1}, \\ &\text{v. } {^cD}_{a^+}^{q;\psi} \big(\psi(t) - \psi(a) \big)^k = 0, \forall k < n \in \mathbb{N} \end{split}$$

Lemma 2.2 [27] Let $q \in (0,1)$ and $x \in \mathbb{R}$, one has i. $E_{q,1}$ and $E_{q,q}$ are non-negative. ii. $E_{q,1}(x) \leq 1$, $E_{q,q}(x) \leq \frac{1}{\Gamma(q)}$, for any x < 0.

Lemma 2.3 [7] Let $q \in (0,1)$, $\lambda \in \mathbb{R}$ and $g \in C(J,\mathbb{R})$, then the linear problem

$$\begin{cases} {}^cD_{a^+}^{q;\psi}u(t)+\lambda u(t)=g(t), & t\in J.\\ u(a)=u_a, \end{cases}$$

has a unique solution as

$$u(t) = u_a E_{q,1} \left(-\lambda \left(\psi(t) - \psi(a) \right)^q \right)$$

$$+ \int_0^t \psi' \left(\psi(t) - \psi(s) \right)^{q-1} E_{q,q} \left(-\lambda \left(\psi(t) - \psi(a) \right)^q \right) g(s) ds,$$

where $E_{p,q}(.)$ is the two-parametric Mittag-Leffler function

Lemma 2.4 [Comprising result] [7]Let $q \in (0,1)$ and $\lambda \in \mathbb{R}$ if $\gamma \in C(J, \mathbb{R})$,

$$\begin{cases} {}^{c}D_{a^{+}}^{q;\psi}\gamma(t) \geq -\lambda\gamma(t), & t \in (a,b]. \\ \gamma(a) \geq 0, \end{cases}$$

then $\gamma(t) \ge 0$ for all $t \in J$.

3. Main Results

In this section, we develop a monotone method for the system ψ -Caputo fractional differential equations (3.7) using coupled lower and upper solutions, respectively.

Definition 3.1 The functions $f_i \in C(J, \mathbb{R})$ such that ${}^cD_{a^+}^{q;\psi}f_i(t)$ exist and is continuous on J and is known to be a solution (1.1). Further, f_i gives the statistics of the equation ${}^cD_{a^+}^{q;\psi}u_i(t) = F_i(t,u_1(t),u_2(t))$, for each $t \in J$ and the nonlinear boundary conditions

$$\phi\big(f_i(a),f_i(b)\big)=0$$

Definition 3.2 If the functions $v_i(x,t)$, $w_i(x,t) \in C^{2,q}[Q_T,\mathbb{R}]$ are called the lower and upper solutions of if

$$\begin{cases} {}^cD_{a^+}^{q;\psi}v_i(t) \le F_i(t,v_1(t),v_2(t)) & t \in [a,b], \\ \phi(v_i(a),v_i(b)) \le 0 \end{cases}$$

$$\begin{cases} {}^{c}D_{a}^{q;\psi}w_{i}(t) \geq F_{i}(t, w_{1}(t), w_{2}(t)) & t \in [a, b], \\ \phi(w_{i}(a), w_{i}(b)) \geq 0 \end{cases}$$

Theorem 3.1 Let $F: I \times \mathbb{R} \to \mathbb{R}$ be continuous. Assume that

- (i) There exist $v_i(t)$ and $w_i(t)$ as lower and upper solutions of problem (1.1) in $\mathcal{C}(J,\mathbb{R})$ respectively, with $v_i(t) \leq w_i(t)$, $t \in J$.
- (ii) There exists a constant $k_i > 0$ with

$$F_i(t, u_2) - F_i(t, u_1) \ge -k_i(u_2 - u_1)$$
 for $v_i(t) \le u_1 \le u_2 \le w_i(t), t \in J$

(iii) There exists non-negative constants M, N with $v_i(a) \le x_1 \le x_2 \le w_i(a)$, $v_i(b) \le y_1 \le y_2 \le w_i(b)$, such that

$$\phi_i(x_2, y_2) - \phi_i(x_1, y_1 \le M(x_2 - x_1) - N(y_2 - y_1)$$

Then there exist monotone sequences $\{v_i^n(t)\}$ and $\{w_i^n(t)\}$ such that $v_i^n(t) \to v_i(t)$ and $w_i^n(t) \to w_i(t)$ as $n \to \infty$ uniformly on I, to the extremal solutions of (1.1) in the sector $[v_i, w_i]$ where

$$= \{u_i \in \mathcal{C}(J,\mathbb{R}): v_i(t) \le u_i(t) \le w_i(t), t \in J\}$$

Proof.

We construct the sequences $\{v_i^{n+1}(t)\}$ and $\{w_i^{n+1}(t)\}$ and $k_i > 0$, we consider the following fractional differential equations

$$\begin{cases} {}^{c}D_{a+}^{q;\psi}v_{i}^{n+1}(t) = F_{i}(t,v_{i}^{n}(t)) - k(v_{i}^{n+1}(t) - v_{i}^{n}(t)) & t \in J, \\ v_{i}^{n+1}(a) = v_{i}^{n}(a) - \frac{1}{c}\phi(v_{i}^{n}(a),v_{i}^{n}(b)) \end{cases}$$
(3.1)

$$\begin{cases} {}^{c}D_{a^{+}}^{q;\psi}w_{i}^{n+1}(t) = F_{i}(t,w_{i}^{n}(t)) - k(w_{i}^{n+1}(t) - w_{i}^{n}(t)) & t \in J, \\ w_{i}^{n+1}(a) = w_{i}^{n}(a)) - \frac{1}{c}\phi(w_{i}^{n}(a),w_{i}^{n}(b)) \end{cases}$$
(3.2)

By Lemma 3 and equation (3.1),(3.2) preserve at most one solution in $\mathcal{C}(J,\mathbb{R})$ we have

$$\begin{split} v_{i}^{n+1}(t) &= \left(v_{i}^{n}(a)) - \frac{1}{c}\phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)\right) E_{q,1}\left(-k_{i}\left((\psi)_{i}(t) - \psi_{i}(a)\right)^{q}\right) \\ &+ \int_{a}^{t}\psi_{i}'(s)\left(\psi_{i}(t) - \psi_{i}(a)\right)^{q-1} E_{q,q}\left(-k_{i}\left(\psi_{i}(t) - \psi_{i}(s)\right)^{q}\right)\left(F_{i}\left(s, v_{i}^{n}(s)\right) + k_{i}\left(v_{i}^{n+1}(s)\right)\right) ds \quad t \in J, \\ w_{i}^{n+1}(t) &= \left(w_{i}^{n}(a)\right) - \frac{1}{c}\phi\left(w_{i}^{n}(a), w_{i}^{n}(b)\right)\right) E_{q,1}\left(-k_{i}\left((\psi)_{i}(t) - \psi_{i}(a)\right)^{q}\right) \\ &+ \int_{a}^{t}\psi_{i}'(s)\left(\psi_{i}(t) - \psi_{i}(a)\right)^{q-1} E_{q,q}\left(-k_{i}\left(\psi_{i}(t) - \psi_{i}(s)\right)^{q}\right)\left(F_{i}\left(s, w_{i}^{n}(s)\right) + k_{i}\left(w_{i}^{n+1}(s)\right)\right) ds \quad t \in J. \end{split}$$

Step 1: The sequences $\{v_i^{n+1}(t)\}, \{w_i^{n+1}(t)\}\}$ $(n \ge 1)$ are lower and upper solutions of (), respectively. We prove that $v_i^0(t) \le v_i^1(t)$. Let $\rho_i(t) = v_i^1(t) - v_i^0(t)$. Then equation (3.1) and Definition 3.2, we have

$${}^{c}D_{a^{+}}^{q;\psi}\rho_{i}(t) \stackrel{c}{=} D_{a^{+}}^{q;\psi}v_{i}^{1}(t) \stackrel{c}{-} D_{a^{+}}^{q;\psi}v_{i}^{0}(t)
 {}^{c}D_{a^{+}}^{q;\psi}\rho_{i}(t) - k_{i}\left(v_{i}^{1}(t) - v_{i}^{0}(t)\right) - F_{i}\left(t, v_{i}^{0}(t)\right)
 {}^{c}D_{a^{+}}^{q;\psi}\rho_{i}(t).$$

Since $\rho_i(a) = -\frac{1}{c}\phi\left(v_i^0(a), v_i^0(b)\right) \ge 0$, $\rho_i(t) \ge 0$, for $t \in J$ by Lemma 4. Thus $v_i^0(t) \le v_i^1(t)$. Assume that $v_i^{k-1}(t) \le v_i^k(t)$. Now we show that $v_i^k(t) \le v_i^{k+1}(t)$. Let $\rho_i(t) = v_i^k(t) - v_i^{k+1}(t)$

$${}^{c}D_{a^{+}}^{q;\psi}\rho_{i}(t) \stackrel{c}{=} D_{a^{+}}^{q;\psi}v_{i}^{k}(t) \stackrel{c}{-} D_{a^{+}}^{q;\psi}v_{i}^{k+1}(t)
 {}^{\geq} F_{i}\left(t,v_{i}^{k}(t)\right) - k_{i}\left(v_{i}^{k+1}(t) - v_{i}^{k}(t)\right) - F_{i}\left(t,v_{i}^{k}(t)\right)
 {}^{=} -k_{i}\rho_{i}(t).$$

Since $\rho_i(a) = -\frac{1}{c}\phi\left(v_i^k(a), v_i^k(b)\right) \ge 0$, $\rho_i(t) \ge 0$, for $t \in J$ by Lemma 4. Thus $v_i^k(t) \le v_i^{k+1}(t)$. Hence by mathematical induction, we have

$$v_i^0(t) \le v_i^1(t) \le \dots \le v_i^k(t) \le v_i^{k+1}(t) \le \dots \le v_i^n(t)$$
(3.3)

Next, we prove that $w_i^1(t) - w_i^0(t)$, $t \in J$. Let $\rho_i(t) = w_i^0(t) - w_i^1(t)$. Then equation (3.1) and Definition 3.2, we have

Since $\rho_i(a) = -\frac{1}{c}\phi\left(w_i^0(a), w_i^0(b)\right) \ge 0$, $\rho_i(t) \ge 0$, for $t \in J$ by Lemma 4. Thus $w_i^1(t) \le w_i^0(t)$. Assume that $w_i^k(t) \le w_i^{k-1}(t)$. Now we show that $w_i^{k+1}(t) \le w_i^k(t)$. Let $\rho_i(t) = w_i^{k+1}(t) - w_i^k(t)$

$$^{c}D_{a^{+}}^{q;\psi}\rho_{i}(t) \quad \stackrel{c}{=} D_{a^{+}}^{q;\psi}w_{i}^{k+1}(t) \stackrel{c}{=} D_{a^{+}}^{q;\psi}w_{i}^{k}(t)
 \leq F_{i}\left(t,w_{i}^{k+1}(t)\right) - k_{i}\left(w_{i}^{k+1}(t) - w_{i}^{k}(t)\right) - F_{i}\left(t,w_{i}^{k+1}(t)\right)
 = -k_{i}\rho_{i}(t).$$

Since $\rho_i(a) = -\frac{1}{c}\phi\left(w_i^{k+1}(a), w_i^{k+1}(b)\right) \ge 0$, $\rho_i(t) \ge 0$, for $t \in J$ by Lemma 4. Thus $w_i^{k+1}(t) \le w_i^k(t)$. Hence by mathematical induction, we have

$$w_i^n(t) \le w_i^{n-1}(t) \le \dots \le w_i^k(t) \le w_i^{k-1}(t) \le \dots \le w_i^1(t) \le w_i^0(t)$$
(3.4)

Now to Prove that $v_i^1(t) \le w_i^1(t)$. Let $\rho_i(t) = w_i^1(t) - v_i^1(t)$. Using equations (3.1) and (3.2) together with assumptions (ii) and (iii), we have

$${}^{c}D_{a^{+}}^{q;\psi}\rho_{i}(t) = F_{i}\left(t,w_{i}^{0}(t)\right) - F_{i}\left(t,v_{i}^{0}(t)\right) - k_{i}\left(w_{i}^{1}(t) - w_{i}^{0}(t)\right) + k_{i}(v_{i}^{1}(t) - v_{i}^{0}) \\
 \geq -k_{i}\left(w_{i}^{0}(t) - v_{i}^{0}(t)\right) - k_{i}\left(w_{i}^{1}(t) - w_{i}^{0}(t)\right) + k_{i}\left(v_{i}^{1}(t) - v_{i}^{0}(t)\right) \\
 = -k_{i}\rho_{i}(t).$$

Since

$$\rho_{i}(a) = \left(w_{i}^{0}(a) - v_{i}^{0}(t)\right) - \frac{1}{c} \left(\phi\left(w_{i}^{0}(a), w_{i}^{0}(b)\right) - \phi\left(v_{i}^{0}(a), v_{i}^{0}(b)\right)\right) \\
\geq \frac{d}{c} \left(\left(w_{i}^{0}(b) - v_{i}^{0}(b)\right) \\
\geq 0,$$

we have $v_i^1(t) \le w_i^1(t), t \in J$ by Lemma 4. Hence $v_i^0(t) \le v_i^1(t) \le w_i^1(t) \le w_i^0(t)$.

By mathematical inductions and equations (3.3) and (3.4), we get

$$v_i^0(t) \le v_i^1(t) \le \dots \le v_i^n(t) \le w_i^n(t) \le \dots \le w_i^1(t) \le w_i^0(t)$$
(3.5)

We prove that $v_i^0(t)$, $w_i^0(t)$ are extremum solutions of (1.1). Since v_i^0 and w_i^0 are lower and upper solutions of (1.1), assumptions (ii) and (iii), we get

$${}^{c}D_{a^{+}}^{q;\psi}v_{i}^{0}(t) = F_{i}(t,v_{i}^{0}(t)) - k_{i}(v_{i}^{1}(t) - v_{i}^{0}(t))$$

$$\leq F_{i}(t,v_{i}^{1}(t))$$

and

$$\begin{split} \phi\Big(v_i^1(a), v_i^1(b)\Big) & \leq \phi(v_i^0(a), v_i^0(b) + c\Big(v_i^1(a) - v_i^0(a)\Big) - d\Big(v_i^1(b) - v_i^0(b)\Big) \\ & = -d\Big(v_i^1(b) - v_i^0(b)\Big) \\ & \leq 0. \end{split}$$

$${}^{c}D_{a^{+}}^{q;\psi}w_{i}^{0}(t) = F_{i}\left(t, w_{i}^{0}(t)\right) - k_{i}\left(w_{i}^{1}(t) - w_{i}^{0}(t)\right)$$

$$\geq F_{i}\left(t, w_{i}^{1}(t)\right)$$

and

$$\begin{split} \phi\Big(w_i^1(a), w_i^1(b)\Big) & \geq \phi(w_i^0(a), w_i^0(b) + c\left(w_i^1(a) - w_i^0(a)\right) - d\left(w_i^1(b) - w_i^0(b)\right) \\ & = -d\left(w_i^1(b) - w_i^0(b)\right) \\ & > 0. \end{split}$$

Therefore, $v_i^1(t)$, $w_i^1(t)$ is the lower and upper solution of (1.1), respectively. By induction, Hence $v_i^n(t)$, $w_i^n(t)$ are lower and upper solutions of (1.1), respectively.

Step 2: $v_i^n \to v_i$ and $w_i^n \to w_i$

First, we prove that $\{v_i^n\}$ is uniformly bounded. By considering supposition Hypothesis 2, we have

$$F_i(t, v_i^0(t)) + k_i v_i^0(t) \le F_i(t, v_i^n(t)) + k_i v_i^n(t) \le F_i(t, w_i^0(t)) + k_i w_i^0(t), \quad t \in J$$

That is

$$0 \leq F_{i}(t, v_{i}^{n}(t)) - F_{i}(t, v_{i}^{0}(t)) + k_{i}(v_{i}^{n}(t) - v_{i}^{0}(t))$$

$$\leq F_{i}(t, w_{i}^{0}(t)) - F_{i}(t, v_{i}^{0}(t)) + k_{i}(w_{i}^{0}(t) - v_{i}^{0}(t))$$

Hence, we have

$$|F_{i}(t, v_{i}^{n}(t)) - F_{i}(t, v_{i}^{0}(t)) + k_{i}(v_{i}^{n}(t) - v_{i}^{0}(t))| \leq |F_{i}(t, w_{i}^{0}(t)) - F_{i}(t, v_{i}^{0}(t))| + k_{i}(w_{i}^{0}(t) - v_{i}^{0}(t))|.$$

Thus

$$\begin{split} |F_{i}\big(t,v_{i}^{n}(t)\big) + k_{i}(v_{i}^{n}(t)) &\leq |F_{i}\big(t,v_{i}^{n}(t)\big) - F_{i}\left(t,v_{i}^{0}(t)\right) + k_{i}\left(v_{i}^{n}(t) - v_{i}^{0}(t)\right)| \\ &+ |F_{i}\left(t,v_{i}^{0}(t)\right) + k_{i}(v_{i}^{0}(t))| \\ &\leq |F_{i}\left(t,w_{i}^{0}(t)\right) - F_{i}\left(t,v_{i}^{0}(t)\right) + k_{i}\left(w_{i}^{0}(t) - v_{i}^{0}(t)\right)| \\ &+ |F_{i}\left(t,v_{i}^{0}(t)\right) + k_{i}(v_{i}^{0}(t))| \\ &+ \leq 2|F_{i}\left(t,v_{i}^{0}(t)\right) + k_{i}(v_{i}^{0}(t))| + |F_{i}\left(t,v_{i}^{0}(t)\right) + k_{i}(v_{i}^{0}(t))|. \end{split}$$

Since v_i^0 , F_i are continuous on J, we can see a constant C independent of n with

$$|F_i(t, v_i^n(t)) + k_i(v_i^n(t))| \le C \tag{3.6}$$

Furthermore, from Hypothesis 3, we have

$$v_i^0(a) - \frac{1}{c}\phi\left(v_i^0(a), v_i^0(b)\right) \le v_i^n(a) - \frac{1}{c}\phi\left(w_i^0(a), w_i^0(b)\right) \le w_i^0(a) - \frac{1}{c}\phi\left(v_i^0(a), v_i^0(b)\right)$$

That is

$$0 \leq v_i^n(a) - v_i^0(a) - \frac{1}{c}\phi(v_i^n(a), v_i^n(b)) - \phi(v_i^0(a), v_i^0(b))$$

$$\leq w_i^0(a) - v_i^0(a) - \frac{1}{c}\phi(w_i^n(0), w_i^0(b)) - \phi(v_i^0(a), v_i^0(b)).$$

Hence, we have

$$|v_{i}^{n}(a) - v_{i}^{0}(a) - \frac{1}{c}\phi(v_{i}^{n}(a), v_{i}^{n}(b)) - \phi(v_{i}^{0}(a), v_{i}^{0}(b))|$$

$$\leq |v_{i}^{n}(a) - v_{i}^{0}(a) - \frac{1}{c}\phi(v_{i}^{n}(a), v_{i}^{n}(b)) - \phi(v_{i}^{0}(a), v_{i}^{0}(b))|$$

$$\leq |v_{i}^{n}(a) - v_{i}^{0}(a) - \frac{1}{c}\phi(v_{i}^{n}(a), v_{i}^{n}(b)) - \phi(v_{i}^{0}(a), v_{i}^{0}(b))|.$$

Thus

$$\begin{split} |v_i^n(a) - \frac{1}{c}\phi \Big(v_i^n(a), v_i^n(b)\Big)| & \leq |v_i^n(a) - v_i^0(a) - \frac{1}{c}\phi \Big(v_i^n(a), v_i^n(b)\Big) - \phi \left(v_i^0(a), v_i^0(b)\right)| \\ & + |v_i^0(a) - \frac{1}{c}\phi \left(v_i^0(a), v_i^0(b)\right)| \\ & \leq 2|v_i^0(a) - \frac{1}{c}\phi \left(v_i^0(a), v_i^0(b)\right)| + |w_i^0(a) - \frac{1}{c}\phi \left(w_i^0(a), w_i^0(b)\right)|. - \frac{1}{c}\phi \left(w_i^0(a), w_i^0(b)$$

Since v_i^0 , w_i^0 and ϕ are continuous functions; we can see a constant D independent of n with

$$|v_i^n(a) - \frac{1}{c}\phi(v_i^n(a), v_i^n(b))| \le D$$
 (3.7)

Moreover, by (3.1) and (3.2), we have

$$|v_{i}^{n+1}(t)| = |v_{i}^{n}(a) - \frac{1}{c}\phi(v_{i}^{n}(a), v_{i}^{n}(b))|E_{q,1}(-k_{i}(\psi(t) - \psi(a))^{q})$$

$$+ \int_{a}^{t} \psi'(s)(\psi(t) - \psi(s))^{v-1} E_{q,q}(-k_{i}(\psi(t) - \psi(s)))^{q} |F(s, v_{i}^{n}(s) + k_{i}v_{i}^{n}(t)|ds,$$

Using Lemma 2 along with (3.6) and (3.7), we have

$$\begin{aligned} |v_i^{n+1}(t)| &= D + \frac{C}{\Gamma(q)} \int_a^t \psi'(s) \big(\psi(t) - \psi(s) \big)^{v-1} ds, \\ &\leq D + \frac{C \big(\psi(t) - \psi(s) \big)^q}{\Gamma(q+1)}. \end{aligned}$$

Hence, v_i^n is uniformly bounded in $C(J, \mathbb{R})$. Similarly w_i^n is uniformly bounded $C(J, \mathbb{R})$. Next, to prove that the sequence v_i^n and w_i^n are equi-continuous on J. Choosing $t_1, t_2 \in J$, with $t_1 \le t_2$. By (3.6),(3.7) and Lemma 2, we have

$$\begin{split} |v_{i}^{n+1}(t_{2}) - v_{i}^{n+1}(t_{1})| &\leq |v_{i}^{n}(a) - \frac{1}{c}\phi\left(v_{i}^{n}(a), v_{i}^{n}(b)\right)||E_{q,1}\left(-k_{i}\left(\psi(t_{2}) - \psi(a)\right)^{q}\right) \\ &- E_{q,1}\left(-k_{i}\left(\psi(t_{1}) - \psi(a)\right)^{q}\right)| \\ &\leq \int_{a}^{t_{1}} \frac{\psi'(s)\left[\left(\psi(t_{1}) - \psi(s)\right)^{v-1} - \left(\psi(t_{2}) - \psi(s)\right)^{v-1}\right]}{\gamma(q)}|F(s, v_{i}^{n}(s) + k_{i}v_{i}^{n}(s)|ds \\ &+ \int_{t_{1}}^{t_{2}} \frac{\psi'(s)\left[\left(\psi(t_{2}) - \psi(s)\right)^{v-1}\right]}{\Gamma(q)}|F(s, v_{i}^{n}(s) + k_{i}v_{i}^{n}(s)|ds \\ &\leq D|E_{q,1}\left(-k_{i}\left(\psi(t_{2}) - \psi(a)\right)^{q}\right) - E_{q,1}\left(-k_{i}\left(\psi(t_{1}) - \psi(a)\right)^{q}\right)| \\ &+ \frac{2C\left(\psi(t_{2}) - \psi(t_{1})\right)^{q}}{\Gamma(q+1)}. \end{split}$$

By the continuity of $E_{q,1}\left(-k_i\left(\psi(t_1)-\psi(a)\right)^q\right)$ on J, the right-hand-side of the preceding inequality approaches zero, when $t_1 \to t_2$. This implies that $\{v_i^{n+1}(t)\}$ is equi-continuous on J. Similarly $\{w_i^{n+1}(t)\}$ is equi-continuous on J. Hence, by using the Ascoli-Arzelas theorem, the subsequences converge to $v_i^*(t)$ and $w_i^*(t)$. Hence the monotonic sequences combined with $v_i^n(t)$ and $w_i^n(t)$ yields $\lim_{n\to\infty}v_i^n(t)=v_i^*(t)$ and $\lim_{n\to\infty}w_i^n(t)=w_i^*(t)$, uniformly on $t\in J$ and limit functions v_i^*,w_i^* satisfy (1.1)

Step 3: v_i^* and w_i^* are maximal solutions of (1.1)in $[v_i^0, w_i^0]$ Let $u_i \in [v_i^0, w_i^0]$ be any solution of (1.1). Suppose that

$$v_i^n(t) \le u_i(t) \le w_i^n(t), \quad t \in J \tag{3.8}$$

for some $n \in \mathbb{N}$. To prove that $u_i(t) \leq v_i^n(t)$ Let $\rho_i(t) = u_i(t) - v_i^n(t)$. Then from, we have

$${}^{c}D_{a^{+}}^{q;\psi}\rho_{i}(t) = F_{i}(t,u_{i}(t)) - F_{i}(t,v_{i}^{0}(t)) - k_{i}(v_{i}^{n+1}(t) - v_{i}^{n}(t))
 \geq -k_{i}(_{i}(t) - v_{i}^{n}(t)) + k_{i}(v_{i}^{n+1}(t) - v_{i}^{n}(t))
 = -k_{i}\rho_{i}(t).$$

Furthermore

$$v_{i}^{n+1}(a) = (v_{i}^{n}(a) - \frac{1}{c}(\phi(v_{i}^{n}(a), v_{i}^{n}(b)))$$

$$= (v_{i}^{n}(a) - \frac{1}{c}(\phi(u_{i}(a), u_{i}(b)) - \frac{1}{c}(\phi(v_{i}^{n}(a), v_{i}^{n}(b)))$$

$$\leq u_{i}(a) - \frac{d}{c}((u_{i}(b) - v_{i}^{n}(b)))$$

$$\leq u_{i}(a)$$

that is $\rho_i \ge 0$. By Lemma 4, we have $\rho_i \ge 0$, $t \in J$ which implies that

$$v_i^n(t) \le u_i(t), \quad t \in J$$

Next, we prove that $w_i^{n+1}(t) \le u_i(t)$ Let $\rho_i(t) = w_i^{n+1}(t) \le u_i(t)$. Then from, we have

$${}^{c}D_{a^{+}}^{q;\psi}\rho_{i}(t) = F_{i}(t, w_{i}^{n+1}(t)) - F_{i}(t, u_{i}(t)) - k_{i}(u_{i}(t) - u_{i}(t))$$

$$\geq -k_{i}(w_{i}6n(t) - u_{i}(t)) + k_{i}(u_{i}(t) - u_{i}(t))$$

$$= -k_{i}\rho_{i}(t).$$

Furthermore

$$u_{i}(a) = (u_{i}(a) - \frac{1}{c}(\phi(u_{i}(a), u_{i}(b)))$$

$$= (u_{i}(a) - \frac{1}{c}(\phi(w_{i}^{n}(a), w_{i}^{n}(b)) - \frac{1}{c}(\phi(u_{i}(a), u_{i}(b)))$$

$$\leq w_{i}^{n}(a) - \frac{d}{c}((w_{i}^{n}(b) - u_{i}(b))$$

$$\leq w_{i}^{n}(a)$$

that is $\rho_i \geq 0$. By Lemma 4, we have $\rho_i \geq 0$, $t \in J$ which implies that

$$u_i(t) \le w_i^n(t), \quad t \in J$$

Hence.

$$v_i^n(t) \le u_i(t) \le w_i^n(t), \quad t \in J$$

By (4.8) is satisfied on *J* for all $n \in \mathbb{N}$. For $n \to \infty$ on (3.8), we have

$$v_i^* \le u_i \le w_i^*.$$

Hence v_i^* , w_i^* are the extremal solutions of (1.1)in $[v_i^0, w_i^0]$

Theorem 3.2 Let all the assumptions of Theorem 3.1 hold. Further, there exist non-negative constants M and N such that the function f_i satisfies the condition

$$f_i(x, u_1, u_2) - f_i(x, v_1, v_2) \le M(u_1 - v_1) + N((u_2 - v_2), v_1)$$

for $v_i^0(t) \le u_i \le w_i^0(t)$. Then the problem $u_i(t)$ of (1.1) has a unique solution. **Proof.** We know $v_i^0(t) \le w_i^0(t)$ on J. It is sufficient to prove that $v_i(t)^0 \ge w_i^0(t)$ on J. Consider $\rho_i(t) = w_i^0(t) - v_i^0(t)$. Then we have

$${}^{c}D_{a^{+}}^{q;\psi}\rho_{i}(t) = F_{i}\left(t,w_{i}^{0}(t)\right) - F_{i}\left(t,v_{i}^{0}(t)\right) - k_{i}\left(w_{i}^{0}(t) - w_{i}^{0}(t)\right) + k_{i}(v_{i}^{0}(t) - v_{i}^{0})$$

$$\geq -k_{i}\left(w_{i}^{0}(t) - v_{i}^{0}(t)\right) - k_{i}\left(w_{i}^{0}(t) - w_{i}^{0}(t)\right) + k_{i}\left(v_{i}^{0}(t) - v_{i}^{0}(t)\right)$$

$$= -k_{i}\rho_{i}(t).$$

Since

$$\rho(a) = \left(w_i^0(a) - v_i^0(t)\right) - \frac{1}{c} \left(\phi\left(w_i^0(a), w_i^0(b)\right) - \phi\left(v_i^0(a), v_i^0(b)\right)\right)$$

$$\geq \frac{d}{c} \left(\left(w_i^0(b) - v_i^0(b)\right)$$

$$\geq 0,$$

we have $w_i^0(t) \ge v_i^0(t)$, $t \in J$. By Lemma 4, we know $p_i \ge 0$, implying that $w_i^0(t) \ge v_i^0(t)$ on J. Hence $v_i(t) = u_i(t) = 0$ $w_i(t)$.

4. Conclusion

In this work, initially, we have investigated by using a monotone iterative method together with upper and lower solutions for boundary value problems involving a generalized system of Caputo derivative of fractional order. The monotone method yields monotone sequences which converge uniformly and monotonically to extremal (maximal and minimal) solutions of (1.1). We have proven that the unique solution of $u_i(t)$ of the system.

References

- [1] Ricardo Almeida, "Caputo Fractional Derivative of a Function with Respect to another Functions," *Communications in Nonlinear Science and Numerical Simulation*, vol. 44, pp. 460-481, 2017. [CrossRef] [Google Scholar] [Publisher Link]
- [2] A.A. Kilbas, F. Mainardi, and S.V. Rogosin, Mittaf-Leffer Functions, Related Topic and Applications, Springer Monographs in Mathematics, 2014.
- [3] Anatoly Kilbas, and Sergei Marzan, "Cauchy Problem for Differential Equation with Caputo Derivative," *Fractional Calculus and Applied Analysis*, vol. 7, no. 3, pp. 297-321, 2004. [Google Scholar] [Publisher Link]
- [4] Anatoly A. Kilbas, Hari M. Srivastava, and Juan J. Trujillo, *Theory and Applications of Fractional Differential Equations*, Elsevier, 2006. [Google Scholar] [Publisher Link]
- [5] A.S. Vatsala, and Donna Stutson, "Generalized Monotone Method for Fractional Reaction-Diffusion Equation," *Communications in Applied Analysis*, vol. 16, no. 2, pp. 165-174, 2012. [Google Scholar]
- [6] Choukri Derbazi et al., "Extremal Solutions of Generalized Caputo-Type Fractional-Order Boundary Value Problems Using Monotone Iterative Method," *Fractal and Fractional*, vol. 6, no. 3, p. 146, 2022. [CrossRef] [Google Scholar] [Publisher Link]
- [7] Choukri Derbazi et al., "Initial value problem for Nonlinear Fractional Differential Equations with ψ-Caputo Derivative via Monotone Iterative Technique," *Axioms*, vol. 9, no. 2, p. 57, 2020. [CrossRef] [Google Scholar] [Publisher Link]
- [8] Donna Stutson, and A.S. Vatsala, "A Representations Solution is Obtained for the one Dimentional Caputo Fractional Reaction-Diffusion Equation," Dynamic System and Applications, vol. 6, 2012.
- [9] D.B. Dhaigude, and J.A. Nanware, "Monotone Technique for Weakly Coupled System of Caputo Fractional Differential Equations with Periodic Boundary Conditions," *Dynamics of Continuous, Discrete and Impulsive Systems*, vol. 22, no. 1, pp. 13-23, 2015. [Google Scholar]
- [10] I. Podlubny, Fractional Differential Equations, Academics Press, San Diego, vol. 198, 1999.
- [11] J.D. Ramirez, and A.S. Vatsala, "Generalized Monotone Iterative Technique for Caputo Fractional Differential Equations with Periodic Boundary Conditions via Initial Value Problem," *International Journal of Differential Equation*, 2012. [CrossRef] [Google Scholar] [Publisher Link]
- [12] Jagdish A. Nanware, and Pandurang D. Kundgar, "Generalized Monotone Method for System of Riemann-Liouville Fractional Reaction-Diffusion Equations," *Communication in Nonlinear Analysis*, vol. 9, no. 1, pp. 1-20, 2021. [Google Scholar] [Publisher Link]
- [13] J. A. Nanware, and P.D. Kundgar, "Existence and Uniqueness of Solutions for System of Fractional Reaction Diffusion Equations". [Communicated]
- [14] J.A. Nanware, and D.B. Dhaigude, "Existence of Uniqueness of Solutions of Riemann- Liouville Fractional Differential Equations with Integral Bounadry Conditions," *International Journal of Nonlinear Science*, vol. 14, no. 4, pp. 410 415, 2012.
- [15] J.A. Nanware, and D.B. Dhaigude, "System of Initial Value Problems Involving Riemann-Liouville Sequential Fractional Derivative," *Communications in Applied Analysis*, vol. 22, no. 3, pp. 353-368, 2018. [Google Scholar] [Publisher Link]
- [16] J.A. Nanware, N.B. Jadhav, and D.B. Dhaigude, "Monotone Iterative Technique for Finite System of Riemann-Liouville fractional Differential Equations with Integral Boundary Conditions," *International Conference on Mathematical Sciences*, pp. 235- 238, 2014. [Google Scholar] [Publisher Link]
- [17] J.A. Nanware, N.B. Jadhav, and D.B. Dhaigude, "Initial Value Problems for Fractional Differential Equations Involving Riemann-Liouville Derivative," *Malaya Journal of Matematik*, vol. 5, no. 2, pp. 337-345, 2017. [CrossRef] [Google Scholar] [Publisher Link]
- [18] J.A. Nanware, N.B. Jadhav, and D.B. Dhaigude, "Existence and Uniqueness of Solutions of Nonlinear Implicit Fractional Differential Equations," *Dynamics of Continuous, Discrete and Impulsive Systems Series A: Mathematical Analysis*, vol. 27, pp. 275-282, 2020. [Google Scholar] [Publisher Link]
- [19] K.B. Oldham, and J. Spanier, The Fractional Calculus, Dover Publications, INC, New York, 2002.
- [20] Gangaram S. Ladde, Vangipuram Lakshmikntham, and Aghalaya S. Vatsala, *Monotone Iterative Techniques for Nonliner Differential Equations*, Pitman, New York, 1985. [Google Scholar]
- [21] M. Sowmya, and A.S. Vatsala, "Generalized Method for Caputo Fractional Differential Equations via Coupled Lower and Upper Solutions with Superlinear Convergence," *Nonlinear Dynamics and System Theory*, vol. 15, no. 2, pp. 198-208, 2015. [Publisher Link]
- [22] R. Hilfer, Applications of Fractional Calculus in Physics, World Scientific, Singapore, 2000. [Google Scholar] [Publisher Link]
- [23] V. Lakshmikantham, S. Leela and D.J. Vasundhara Devi, *Theory of Fractional Dynamic Systems*, Cambridge Scientific Publishers, 2009.
- [24] V. Lakshmikantham, and A.S. Vatsala, "General Monotone Method For fractional Reaction-Diffusion Equations," *Communications in Applied Analysis*, vol. 16, pp. 165-174, 2012. [Google Scholar]
- [25] V. Lakshmikantham, "Theory of Fractional Functional Differential Equations," *Nonlinear Analysis: Theory, Methods and Applications*, vol. 69, no. 10, pp. 3337-3343, 2008. [CrossRef] [Google Scholar] [Publisher Link]

- [26] Zhongli Wei, Qingdong Li, and Junling Che, "Initial Value Problems for Fractional Differential Equations Involving Riemann-Liouville Sequential Fractional Derivative," *Journal of Mathematical Analysis and Applications*, vol. 367, no. 1, pp. 260-272, 2010. [CrossRef] [Google Scholar] [Publisher Link]
- [27] Z. Denton, and A.S. Vatsala, "Monotone Iterative Technique For Finite System of Non- linear Riemann- Liouville Fractional Differential Equations," *Opuscula Mathematica*, vol. 31, no. 3, pp. 327-339, 2011. [Google Scholar] [Publisher Link]
- [28] Z. Denton P.W. Ngand, and A.S. Vatsala, "Quasilinearization Method Via Lower and Upper Solutions for Riemann-Liouville Fractional Differential Equations," *Nonlinear Dynamics and System Theory*, vol. 11, no. 3, pp. 239-251, 2011. [Google Scholar] [Publisher Link]