

Regular pre semi I totally continuous functions in Ideal Topological Spaces

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Abstract

The authors introduced $rpsI$ -closed sets and $rpsI$ -open sets in ideal topological spaces and established their relationships with some generalized sets in ideal topological spaces. The aim of this paper is to introduce $rpsI$ -totally continuous, totally $rpsI$ -continuous, strongly $rpsI$ -continuous functions and characterize their basic properties.

Keywords: $rpsI$ -totally continuous, totally $rpsI$ -continuous, strongly $rpsI$ -continuous functions, $rpsI$ -homeomorphism, rps^*I -homeomorphism

2010 AMS Subject Classification : 54C08.

1 Introduction

In 1980, Jain [2] introduced totally continuous functions. In 1995, Nour [4] introduced the concept of totally semi continuous functions as a generalization of totally continuous functions and several properties of totally semi-continuous functions were obtained. We introduced the $rpsI$ -closed sets and $rpsI$ -open sets in ideal topological spaces. Also we introduced $rpsI$ -continuous functions. In this paper, we

introduce the concept of $rpsI$ -totally continuous, strongly $rpsI$ -continuous, $rpsI$ -homeomorphisms and rps^*I -homeomorphisms in ideal topological spaces. Furthermore, basic properties of these functions and preservation theorems of $rpsI$ -totally continuous functions.

2 Preliminaries

For a subset A of an ideal topological space (X, τ, I) , $cl^*(A)$ and $int^*(A)$ denote the closure of A and interior of A respectively. A^c denotes the complement of A in X . Now we recall the following definitions.

Definition 2.1. A subset A of an ideal topological space (X, τ, I) is called

- i) semi- I -open [1] if $A \subseteq cl^*(int(A))$.
- ii) semi pre I -open [1] if $A \subseteq cl(int(cl^*(A)))$.
- iii) αI -open [1] if $A \subseteq int(cl^*(int(A)))$.
- iv) regular I -open [3] if $A = int(cl^*(A))$.

Definition 2.2. A subset A of an ideal topological space (X, τ, I) is called

- i) regular generalized I -closed (rg I -closed) [5] if $cl^*(A) \subseteq U$ whenever $A \subseteq U$ and U is regular I -open.
- ii) regular pre semi I -closed [5] (rps I -closed) if $spIcl(A) \subseteq U$ whenever $A \subseteq U$ and U is regular generalized I -open.

The complement of $rpsI$ -closed set is $rpsI$ -open set. $rpsIcl(A)$ is the smallest $rpsI$ -closed set containing A .

Definition 2.3. A function $f : (X, \tau) \rightarrow (Y, \sigma)$ is called totally continuous [2] if the inverse image of every open subset of Y is clopen in X .

Definition 2.4. A function $f : (X, \tau, I) \rightarrow (Y, \sigma)$ is called

- i) $rpsI$ -irresolute [6] if $f^{-1}(A)$ is $rpsI$ -closed in X , for every $rpsI$ -closed subset A of Y .
- ii) A function $f : (X, \tau, I) \rightarrow (Y, \sigma)$ is called $rpsI$ -continuous [6] if the inverse image of every closed subset of Y is $rpsI$ -closed in X .

3 $rpsI$ -totally continuous functions, totally $rpsI$ -continuous functions and strongly $rpsI$ -continuous

In this section, the notion of totally $rpsI$ -continuous, $rpsI$ -totally continuous functions and strongly $rpsI$ -continuous are introduced. Characterizations and some relationships between $rpsI$ -totally continuous functions and other similar functions are obtained. Also some basic properties of $rpsI$ -totally continuous functions are investigated.

Definition 3.1. A function $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ is called $rpsI$ -totally continuous function if the inverse image of every $rpsI$ -open subset of Y is clopen in X .

Theorem 3.2. A function $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ is $rpsI$ -totally continuous if and only if the inverse image of every $rpsI$ -closed subset of Y is clopen in X .

Proof. Let F be any $rpsI$ -closed set in Y . Then F^c is $rpsI$ -open in Y . By definition, $f^{-1}(F^c)$ is clopen in X . But $f^{-1}(F^c) = (f^{-1}(F))^c$ which is clopen in X . This implies $f^{-1}(F)$ is clopen in X . Conversely suppose V is $rpsI$ -open in Y , then V^c is $rpsI$ -closed in Y . By hypothesis $f^{-1}(V^c)$ is clopen in X . But $f^{-1}(V^c) = (f^{-1}(V))^c$ which is clopen in X , which implies $f^{-1}(V)$ is clopen in X . Thus, inverse image of every $rpsI$ -open set in Y is clopen in X . Therefore f is $rpsI$ -totally continuous.

Theorem 3.3. Every $rpsI$ -totally continuous function is totally continuous.

Proof. Suppose $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ is $rpsI$ -totally continuous. Let U be any open subset of Y . Since every open set is $rpsI$ -open, U is $rpsI$ -open in Y and f is $rpsI$ -totally continuous, it follows $f^{-1}(U)$ is clopen in X . This proves the theorem. The converse of the above theorem need not be true as seen from the following example.

Example 3.4. Let $X = Y = Z = \{a, b, c\}$, $\tau = \{\phi, X, \{a\}, \{b, c\}\}$, $I = \{\phi, \{a\}\}$, $\sigma = \{\phi, Y, \{a\}\}$. Define a functions $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ by $f(a) = a$, $f(b) = b$, $f(c) = c$. Clearly the inverse image of every open set is clopen. Therefore f is totally continuous. But f is not $rpsI$ -totally continuous, because for the $rpsI$ -open set $\{a, b\}$, $f^{-1}(\{a, b\}) = \{a, b\}$ is not clopen in X .

Theorem 3.5. Let $f : X \rightarrow Y$ be a function, where X and Y are ideal topological spaces. Then the following are equivalent.

- i. f is $rpsI$ -totally continuous
- ii. for each $x \in X$ and each $rpsI$ -open set V in Y with $f(x) \in V$, there is a clopen set U in X such that $x \in U$ and $f(U) \subseteq V$.

Proof. (i) $\Rightarrow$ (ii). Suppose f is $rpsI$ -totally continuous and V be any $rpsI$ -open set in Y containing $f(x)$ so that $x \in f^{-1}(V)$. Since f is $rpsI$ -totally continuous, $f^{-1}(V)$ is clopen in X . Let $U = f^{-1}(V)$, then U is clopen in X and $x \in U$. Also $f(U) = f(f^{-1}(V)) \subseteq V$. This implies $f(U) \subseteq V$.

(ii) $\Rightarrow$ (i). Let V be $rpsI$ -open set in Y . Let $x \in f^{-1}(V)$ be any arbitrary point. This implies $f(x) \in V$. By (ii) there is a clopen set $f(G) \subseteq X$ containing x such that $f(G) \subseteq V$, which implies $G \subseteq f^{-1}(V)$. We have $x \in G \subseteq f^{-1}(V)$. This implies $f^{-1}(V)$ is clopen neighbourhood of each of its points. Hence it is clopen set in X . Therefore f is $rpsI$ -totally continuous.

Theorem 3.6. *If a function $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ is $rpsI$ -totally continuous then f is continuous but not conversely.*

Proof. Let V be an open set in Y . Then V is $rpsI$ -open in Y . Since f is $rpsI$ -totally continuous, $f^{-1}(V)$ is both open and closed in X . Thus f is continuous. Converse of the above theorem need not be true as seen from the following example

Example 3.7. *Let $X = Y = \{a, b, c, d\}$, $\tau = \{\phi, X, \{a, c\}, \{d\}, \{a, c, d\}\}$, $I = \{\phi, \{a\}\}$, $\sigma = \{\phi, Y, \{a\}, \{b\}, \{a, b\}, \{b, c\}, \{a, b, c\}\}$. Define a functions $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ by $f(a) = d$, $f(b) = c$, $f(c) = d$, $f(d) = b$. Then f is continuous but not $rpsI$ -totally continuous. Because the subset $\{b\}$ is $rpsI$ -open in Y but $f^{-1}(\{b\}) = \{d\}$ is not closed in X .*

Example 3.8. *Let $X = Y = \{a, b, c, d\}$, $\tau = \{\phi, X, \{a\}, \{b, c, d\}, \{a, c, d\}\}$, $I = \{\phi, \{a\}\}$, $\sigma = \{\phi, Y, \{a\}, \{b\}, \{a, b\}, \{b, c\}, \{a, b, c\}\}$. Define a functions $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ by $f(a) = b$, $f(b) = d$, $f(c) = c$, $f(d) = d$. Then f is perfectly continuous but not $rpsI$ -totally continuous. Because the subset $\{c\}$ is $rpsI$ -open in Y but $f^{-1}(\{c\}) = \{c\}$ is not clopen in X .*

Theorem 3.9. *The composition of two $rpsI$ -totally continuous functions is $rpsI$ -totally continuous.*

Proof. Let $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ and $g : (Y, \sigma, J) \rightarrow (Z, \eta, K)$ be any two $rpsI$ -totally continuous functions. Let V be $rpsI$ -open set in Z . Since g is $rpsI$ -totally continuous, $g^{-1}(V)$ is clopen and hence open in Y . Since every open set is $rpsI$ -open, $g^{-1}(V)$ is $rpsI$ -open in Y . Further, since f is $rpsI$ -totally continuous, $f^{-1}(g^{-1}(V)) = (g \circ f)^{-1}(V)$ is clopen in X . Hence $g \circ f$ is $rpsI$ -totally continuous function.

Definition 3.10. *A function $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ is called strongly $rpsI$ -continuous if the inverse image of every $rpsI$ -open set of Y is open in X .*

Theorem 3.11. *If a function $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ is $rpsI$ -totally continuous then f is strongly $rpsI$ -continuous but not conversely.*

Proof. Proof follows from Definition.

Example 3.12. Let $X = Y = \{a, b, c, d\}$, $\tau = \{\phi, X, \{a, c\}, \{d\}, \{a, c, d\}\}$, $I = \{\phi, \{a\}\}$, $\sigma = \{\phi, Y, \{a\}, \{b\}, \{a, b\}, \{b, c\}, \{a, b, c\}\}$. Define a functions $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ by $f(a) = f(b) = f(c) = d$, $f(d) = a$. Then f is strongly $rpsI$ -continuous but not $rpsI$ -totally continuous. Because the subset a is $rpsI$ -open in Y but $f^{-1}(a) = d$ is not closed in X .

Theorem 3.13. Let X be a discrete topological space and Y be any ideal space and $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ be a function. If f is strongly $rpsI$ -continuous then f is $rpsI$ -totally continuous.

Proof. Let V be $rpsI$ -open in Y . Since f is strongly $rpsI$ -continuous, $f^{-1}(V)$ is open in X . Also since X is a discrete space, we have $f^{-1}(V)$ is closed in X and so f is $rpsI$ -totally continuous.

Definition 3.14. A function $f : (X, \tau, I) \rightarrow (Y, \sigma)$ is called totally $rpsI$ -continuous if $f^{-1}(V)$ is $rpsI$ -clopen in (X, τ, I) for each open set V in (Y, σ) .

Theorem 3.15. Every totally $rpsI$ -continuous function is $rpsI$ -continuous.

Proof. proof follows from definition The converse of the above statements need not be true as seen from the following example.

Example 3.16. Let $X = Y = \{a, b, c\}$, $\tau = \{\phi, X, \{a\}, \{a, b\}\}$, $I = \{\phi, \{b\}\}$, $\sigma = \{\phi, Y, \{b\}, \{a, b\}\}$. Define a function $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ by $f(a) = b, f(b) = a, f(c) = c$. Then f is $rpsI$ -continuous but not totally $rpsI$ -continuous because the set $\{b\}$ is open in Y but $f^{-1}(b) = \{a\}$ which is $rpsI$ -open and not $rpsI$ -closed in X .

Theorem 3.17. Every $rpsI$ -totally continuous function is totally $rpsI$ -continuous.

Proof. Suppose $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ is $rpsI$ -totally continuous. Let U be any open subset of Y . Since every open set is $rpsI$ -open, U is $rpsI$ -open in Y and f is $rpsI$ -totally continuous, it follows $f^{-1}(U)$ is clopen in X . Then $f^{-1}(U)$ is $rpsI$ -clopen in X . This proves the theorem.

The converse of the above theorem need not be true as seen from the following example.

Example 3.18. Let $X = Y = Z = \{a, b, c\}$, $\tau = \{\phi, X, \{a\}, \{b, c\}\}$, $I = \{\phi, \{a\}\}$, $\sigma = \{\phi, Y, \{a\}\}$. Define a functions $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ by $f(a) = a, f(b) = b, f(c) = c$. Clearly the inverse image of every open set is $rpsI$ -clopen in X . Therefore f is totally $rpsI$ -continuous. But f is not $rpsI$ -totally continuous, because for the $rpsI$ -open set $\{a, b\}$, $f^{-1}(\{a, b\}) = \{a, b\}$ is not clopen in X .

4 $rpsI$ -homeomorphisms

In this section, we introduce the concept of $rpsI$ -homeomorphisms and study its relationship with homeomorphisms. We also introduce a new class of functions rps^*I -homeomorphisms which form a subclass of $rpsI$ -homeomorphisms. We prove that the set of all rps^*I -homeomorphisms from (X, τ, I) onto itself is a group under the composition of functions.

Definition 4.1. A bijection $f : (X, \tau, I) \rightarrow (Y, \sigma)$ is called $rpsI$ -homeomorphism if both f and f^{-1} are $rpsI$ -continuous.

We say that the spaces (X, τ, I) and (Y, σ) are $rpsI$ -homeomorphic if there exists an $rpsI$ -homeomorphism from (X, τ, I) onto (Y, σ) .

Theorem 4.2. Every homeomorphism is an $rpsI$ -homeomorphism.

Proof. Let $f : (X, \tau, I) \rightarrow (Y, \sigma)$ be a homeomorphism. Then f and f^{-1} are continuous and f is a bijection. Since every continuous function is $rpsI$ -continuous, it follows that f is $rpsI$ -homeomorphism.

The converse of the above theorem need not be true as seen from the following example.

Example 4.3. Let $X = Y = \{a, b, c, d\}$, $\tau = \{\phi, X, \{a\}, \{b, d\}, \{a, b, d\}\}$, $I = \{\phi, \{a\}\}$, $\sigma = \{\phi, Y, \{b, c, d\}\}$. Define a function $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ by $f(a) = a$, $f(b) = b$, $f(c) = c$, $f(d) = d$. Then f is a $rpsI$ homeomorphism but not homeomorphism. Because the subset $(f^{-1})^{-1}(\{a\}) = \{a\}$ is closed in Y but not closed in X .

Remark 4.4. The composition of two $rpsI$ -homeomorphism need not be $rpsI$ -homeomorphism.

Example 4.5. Let $X = Y = Z = \{a, b, c, d\}$, $\tau = \{\phi, X, \{c\}, \{a, b, d\}\}$, $I = \{\phi, \{a\}\}$, $\sigma = \{\phi, Y, \{b\}, \{a, c, d\}\}$, $J = \{\phi, \{b\}\}$ and $\eta = \{\phi, Z, \{a\}, \{b, c, d\}\}$, $K = \{\phi, \{b\}\}$. Define a function $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ by $f(a) = a$, $f(b) = b$, $f(c) = c$, $f(d) = d$ and $g : (Y, \sigma, J) \rightarrow (Z, \eta, K)$ by $g(a) = c$, $g(b) = d$, $g(c) = b$, $g(d) = a$. Then f and g are both $rpsI$ -homeomorphisms but $g \circ f$ is not $rpsI$ -homeomorphism. Because the subset $b, d\}$ is closed in X , $((g \circ f)^{-1})^{-1}(\{b, d\}) = \{a, c, d\}$ is not $rpsI$ -closed in Z .

Definition 4.6. A bijection $f : (X, \tau, I) \rightarrow (Y, \sigma)$ is called rps^*I -homeomorphism if both f and f^{-1} are $rpsI$ -irresolute.

We say that the spaces (X, τ, I) and (Y, σ) are rps^*I -homeomorphic if there exists an rps^*I -homeomorphism from (X, τ, I) onto (Y, σ) .

We denote the family of all rps^*I -homeomorphism of an ideal topological space (X, τ, I) onto itself by $rps^*I - h(X, \tau)$.

Proof. Let $f : (X, \tau, I) \rightarrow (Y, \sigma)$ be a rps^*I -homeomorphism. Then f and f^{-1} are $rpsI$ -irresolute and f is bijection. Therefore f and f^{-1} are $rpsI$ -continuous. Therefore f is $rpsI$ -homeomorphism.

The converse is not true as seen from the following example.

Theorem 4.7. *Let $f : (X, \tau, I) \rightarrow (Y, \sigma, J)$ and $g : (Y, \sigma, J) \rightarrow (Z, \eta, K)$ be rps^*I -homeomorphisms. Then their composition $g \circ f : (X, \tau, I) \rightarrow (Z, \eta, K)$ is rps^*I -homeomorphism.*

Proof. Suppose f and g are rps^*I -homeomorphisms. Then f and g are $rpsI$ -irresolute. Let U be $rpsI$ -open in Z . Since g is $rpsI$ -irresolute, $g^{-1}(U)$ is $rpsI$ -open in Y . Since f is $rpsI$ -irresolute, $f^{-1}(g^{-1}(U)) = (g \circ f)^{-1}(U)$ is $rpsI$ open in X . Hence $g \circ f$ is $rpsI$ -irresolute. Also for an $rpsI$ -open set G in X , we have $(g \circ f)(G) = g(f(G)) = g(U)$ where $U = f(G)$. By hypothesis, $f(G)$ is $rpsI$ -open in Y and so again by hypothesis, $g(f(G))$ is an $rpsI$ -open set in Z . That is $(g \circ f)(G)$ is an $rpsI$ -open set in Z and therefore $(g \circ f)^{-1}$ is $rpsI$ -irresolute. Also $g \circ f$ is a bijection. This proves $g \circ f$ is rps^*I -homeomorphism.

Theorem 4.8. *The set $rps^*I - h(X, \tau)$ from (X, τ, I) onto itself is a group under the composition of functions.*

Proof. Let $f, g \in rps^*I - h(X, \tau)$. Then $g \circ f \in rps^*I - h(X, \tau)$. We know that the composition of functions is associative and the identity element $I : (X, \tau, I) \rightarrow (X, \tau, I)$ belonging to $rps^*I - h(X, \tau)$ serves as the identity element. If $f \in rps^*I - h(X, \tau)$ then $f^{-1} \in rps^*I - h(X, \tau)$. This proves $rps^*I - h(X, \tau)$ is a group under the operation of composition of functions.

Theorem 4.9. *Let $f : (X, \tau, I) \rightarrow (Y, \sigma)$ be an rps^*I -homeomorphism. Then f induces an isomorphism from the group $rps^*I - h(X, \tau)$ onto the group $rps^*I - h(Y, \sigma)$.*

Proof. Let $f \in rps^*I - h(X, \tau)$. We define a function $\psi f : rps^*I - h(X, \tau) \rightarrow rps^*I - h(Y, \sigma)$ by $\psi(f(h)) = f \circ h \circ f^{-1}$ for every $h \in rps^*I - h(X, \tau)$. Then f is a bijection. Further for all $g, h \in rps^*I - h(X, \tau)$, $\psi f(g \circ h) = f \circ (g \circ h) \circ f^{-1} = (f \circ g \circ f^{-1}) \circ (f \circ h \circ f^{-1}) = \psi f(g) \circ \psi f(h)$.

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